# Positive solutions of a second-order nonlinear Robin problem involving the first-order derivative 

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## Abstract

This paper is concerned with the second-order nonlinear Robin problem involving the first-order derivative:

$$
\left\{\begin{array}{l}
u^{\prime \prime}+f\left(t, u, u^{\prime}\right)=0 \\
u(0)=u^{\prime}(1)-\alpha u(1)=0
\end{array}\right.
$$

where $f \in C\left([0,1] \times \mathbb{R}_{++}^{2}, \mathbb{R}_{+}\right)$and $\left.\alpha \in\right] 0,1[$. Based on a priori estimates, we use fixed point index theory to establish some results on existence, multiplicity and uniqueness of positive solutions thereof, with the unique positive solution being the limit of of an iterative sequence. The results presented here generalize and extend the corresponding ones for nonlinearities independent of the first-order derivative.

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## 1 Introduction

In this paper, we study the existence, multiplicity and uniqueness of positive solutions for the second-order nonlinear Robin problem involving the first-order derivative:

$$
\left\{\begin{array}{l}
-u^{\prime \prime}=f\left(t, u, u^{\prime}\right)  \tag{1}\\
u(0)=0, \quad u^{\prime}(1)=\alpha u(1),
\end{array}\right.
$$

where $f \in C\left([0,1] \times \mathbb{R}_{+}^{2}, \mathbb{R}_{+}\right)\left(\mathbb{R}_{+}:=[0, \infty[)\right.$ and $\alpha \in] 0,1[$.
In 1994, Erbe et al. [10] studied the existence of positive solutions for the second-order boundary value problem below:

$$
\left\{\begin{array}{l}
u^{\prime \prime}+f(t, u)=0  \tag{2}\\
\alpha u(0)-\beta u^{\prime}(0)=0, \\
\gamma u(1)+\delta u^{\prime}(1)=0,
\end{array}\right.
$$

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where $f \in C\left([0,1] \times \mathbb{R}_{+}, \mathbb{R}_{+}\right), \alpha \geq 0, \beta \geq 0, \gamma \geq 0, \delta \geq 0, \gamma \beta+\alpha \gamma+\alpha \delta>0$. The main conditions used in [10] are as follows:
(A1) $\lim _{u \rightarrow 0^{+}} \min _{t \in[0,1]} \frac{f(t, u)}{u}=+\infty, \lim _{u \rightarrow+\infty} \min _{t \in[0,1]} \frac{f(t, u)}{u}=+\infty$;
(A2) $\lim _{u \rightarrow 0^{+}} \max _{t \in[0,1]} \frac{f(t, u)}{u}=0, \lim _{u \rightarrow+\infty} \max _{t \in[0,1]} \frac{f(t, u)}{u}=0$.
Let $\lambda_{1}>0$ be the first characteristic value of the following characteristic value problem:

$$
\left\{\begin{array}{l}
-u^{\prime \prime}=\lambda u \\
\alpha u(0)-\beta u^{\prime}(0)=0 \\
\gamma u(1)+\delta u^{\prime}(1)=0
\end{array}\right.
$$

In 1996 and 1998, Liu et al. [20, 23] generalized and extended the above work, replacing (A1) and (A2) with the following sharp conditions:
(B1) $\lim _{u \rightarrow 0^{+}} \min _{t \in[0,1]} \frac{f(t, u)}{u}>\lambda_{1}, \lim _{u \rightarrow+\infty} \min _{t \in[0,1]} \frac{f(t, u)}{u}>\lambda_{1}$,
(B2) $\lim _{u \rightarrow 0^{+}} \max _{t \in[0,1]} \frac{f(t, u)}{u}<\lambda_{1}, \lim _{u \rightarrow+\infty} \max _{t \in[0,1]} \frac{f(t, u)}{u}<\lambda_{1}$.
Now the main results in $[20,23]$ have been generalized to many other boundary value problems, including ones with delays, ones in measure chains, ones with three-point and multipoint conditions, ones with integral conditions and ones with generalized Lidstone conditions. See [18, 22, 28, 29, 33-35] and the references therein (see also [25-27]).
Notice that our boundary value conditions in Problem (1) correspond to $\alpha=1, \beta=0$, $\gamma=1, \delta=-\alpha<0$ in (2), so the boundary value conditions in (1) are faux special cases of (2). What is more important, the nonlinearity in (1) involves the first-order derivative, whereas the nonlinearity in (2) does not. This means that (1) is much more difficult to deal with than (2). When tackling the boundary value problems involving the first order derivative, one usually employs the Leggett-Williams fixed point theorem [19] and all kinds of its generalizations [4-6], or the coincidence degree theory [11]. The methods mentioned above cannot be applied to generalize the sharp results in [20,23]. Consequently, in this paper, we shall use neither the Leggett-Williams fixed point theorems and its variants, nor the coincidence degree theory to deal with our problem (1), rather utilize the fixed point index theory on cones of Banach spaces to do that. The most important and difficult ingredients in our proofs are the establishing of the a priori estimates of positive solutions for some associated problems, in particular these for the first-order derivatives. In order to facilitate our proofs, we first establish an integral identity and an integral inequality that are of vital importance in the proofs of our main results. For the cases of superlinear nonlinearity at $\infty$, the Bernstein-Nagumo type condition [7, 9, 25] is introduced to enable us to obtain the a priori estimate of the first-order derivative for associated boundary value problems. Our results generalize and extend the ones in [20,23], are strikingly different from the ones in $[1-3,8,12,14,15,17,21]$ and also complement the main ones in $[16,24]$.

This paper is also a continuation of [32](see also [30,31]), where we studied (1) with $\alpha=0$ by the integro-differential equation argument. In contrast to [32], with the introduction of a cone in $C^{1}[0,1]$ and the function $g(x, y):=(1-\alpha) x+2 y$, we shall tackle Problem (1) using fixed point index theory more directly, thereby rendering the statements and proofs of the main results clearer and more concise.

The remainder of this paper is organized as follows. Some basic lemmas, including two versatile results, i.e. an integral identity and an integral inequality, are stated and proved in Sect. 2. The main results, Theorems 3.1-3.3, are presented and proved in Sect. 3. Also,
three extra results parallel with Theorems 3.1-3.3 are given in this section. The uniqueness of positive solutions and its iteration convergence are offered in Sect. 4.

## 2 Preliminaries and basic lemmas

For the sake of convenience, we denote $\beta:=1-\alpha$ from now on.
Notice that (1) is equivalent to the integral equation below:

$$
\begin{equation*}
u(t)=\int_{0}^{1} k(t, s) f\left(s, u(s), u^{\prime}(s)\right) \mathrm{d} s \tag{3}
\end{equation*}
$$

where $k(t, s)$ is the Green function defined by

$$
k(t, s):= \begin{cases}\frac{t(1-\alpha(1-s))}{\beta}, & 0 \leq t \leq s \leq 1, \\ \frac{s(1-\alpha(1-t))}{\beta}, & 0 \leq s \leq t \leq 1 .\end{cases}
$$

Let $E:=C^{1}[0,1]$ and $P:=\left\{u \in E: u(t) \geq 0, u^{\prime}(t) \geq 0, t \in[0,1]\right\}$. Define the norm $\|u\|$ by

$$
\|u\|:=\max _{t \in[0,1]}\left\{|u(t)|,\left|u^{\prime}(t)\right|\right\} .
$$

Then $(E,\|\cdot\|)$ is a Banach space and $P$ is a normal cone in $E$. Define $A: P \rightarrow P$ by

$$
(A u)(t):=\int_{0}^{1} k(t, s) f\left(s, u(s), u^{\prime}(s)\right) \mathrm{d} s
$$

Under the condition $f \in C\left([0,1] \times \mathbb{R}_{+}^{2}, \mathbb{R}_{+}\right)$, the operator $A: P \rightarrow P$ is completely continuous. In our setting, the existence of positive solutions for (1) is equivalent to that of positive fixed points of the completely continuous nonlinear operator $A: P \rightarrow P$.

Lemma 2.1 (see [13]) Let E be a real Banach space and P a cone in E. Suppose that $\Omega \subset E$ is a bounded open set and that $T: \bar{\Omega} \cap P \rightarrow P$ is a completely continuous operator. If there exists $w_{0} \in P \backslash\{0\}$ such that

$$
w-T w \neq \lambda w_{0}, \quad \forall \lambda \geq 0, w \in \partial \Omega \cap P,
$$

then $i(T, \Omega \cap P, P)=0$, where $i$ indicates the fixed point index.

Lemma 2.2 (see [13]) Let E be a real Banach space and Pa cone in E. Suppose that $\Omega \subset E$ is a bounded open set with $0 \in \Omega$ and that $T: \bar{\Omega} \cap P \rightarrow P$ is a completely continuous operator. If

$$
w-\lambda T w \neq 0, \quad \forall \lambda \in[0,1], w \in \partial \Omega \cap P,
$$

then $i(T, \Omega \cap P, P)=1$.

What follows are two versatile lemmas in the proofs of our main resuts.

Lemma 2.3 If $w \in C^{2}[0,1]$ with $w(0)=w^{\prime}(1)-\alpha w(1)=0$, then

$$
\begin{equation*}
\int_{0}^{1}\left(-w^{\prime \prime}(t)\right) t e^{\beta t} \mathrm{~d} t=\beta \int_{0}^{1}\left(2 w^{\prime}(t)+\beta w(t)\right) t e^{\beta t} \mathrm{~d} t \tag{4}
\end{equation*}
$$

Proof By integration by parts, we have

$$
\begin{aligned}
\int_{0}^{1}\left(-w^{\prime \prime}(t)\right) t e^{\beta t} \mathrm{~d} t= & -w^{\prime}(1) e^{\beta}+\int_{0}^{1} w^{\prime}(t)(1+\beta t) e^{\beta t} \mathrm{~d} t \\
= & -w^{\prime}(1) e^{\beta}+\int_{0}^{1} 2 \beta w^{\prime}(t) t e^{\beta t} \mathrm{~d} t \\
& +\int_{0}^{1} w^{\prime}(t)(1-\beta t) e^{\beta t} \mathrm{~d} t
\end{aligned}
$$

and

$$
\int_{0}^{1} w^{\prime}(t)(1-\beta t) e^{\beta t} \mathrm{~d} t=\alpha e^{\beta} w(1)+\int_{0}^{1} \beta^{2} w(t) t e^{\beta t} \mathrm{~d} t
$$

Combining the preceding two equalities and noting $w(0)=w^{\prime}(1)-\alpha w(1)=0$, we obtain the desired result.

Lemma 2.4 If $w \in P$ with $w(0)=0$, then

$$
w(1) \leq \frac{\beta}{1-\alpha e^{\beta}} \int_{0}^{1}\left(\beta w(t)+2 w^{\prime}(t)\right) t e^{\beta t} \mathrm{~d} t .
$$

Proof Integrating by parts, we have

$$
\int_{0}^{1} \beta w(t) t e^{\beta t} \mathrm{~d} t=-\frac{\alpha e^{\beta} w(1)}{\beta}+\frac{1}{\beta} \int_{0}^{1} w^{\prime}(t)(1-\beta t) e^{\beta t} \mathrm{~d} t,
$$

and thus

$$
\begin{aligned}
\int_{0}^{1}\left(\beta w(t)+2 w^{\prime}(t)\right) t e^{\beta t} \mathrm{~d} t & =-\frac{\alpha e^{\beta} w(1)}{\beta}+\frac{1}{\beta} \int_{0}^{1} w^{\prime}(t)(1+\beta t) e^{\beta t} \mathrm{~d} t \\
& \geq-\frac{\alpha e^{\beta} w(1)}{\beta}+\frac{1}{\beta} \int_{0}^{1} w^{\prime}(t) \mathrm{d} t \\
& =\frac{1-\alpha e^{\beta}}{\beta} w(1)
\end{aligned}
$$

Then the desired inequality follows immediately.

## 3 Existence and multiplicity of positive solutions of (1)

For the sake of convenience, we define the function $g$ by

$$
g(x, y):=\beta x+2 y
$$

Recall that we have defined $\beta:=1-\alpha$ in the preceding section. We make the following hypotheses in this section.
(H1) $f \in C\left([0,1] \times \mathbb{R}_{+}^{2}, \mathbb{R}_{+}\right)$.
(H2) There are two constants $a>\beta$ and $c_{1}>0$ such that

$$
f(t, x, y) \geq a g(x, y)-c_{1}, \quad \forall x \geq 0, y \geq 0, t \in[0,1] .
$$

(H3) For every $M>0$ there is a function $\Phi_{M} \in C\left(\mathbb{R}_{+}, \mathbb{R}_{+}\right)$such that

$$
f(t, x, y) \leq \Phi_{M}(y), \quad \forall t \in[0,1], x \in[0, M], y \in \mathbb{R}_{+}
$$

and $\int_{0}^{\infty} \frac{\xi \mathrm{d} \xi}{\Phi_{M}(\xi)+\delta}=\infty$ for every $\delta>0$.
(H4) There are two constants $r>0, b \in] 0, \beta$ [ such that

$$
f(t, x, y) \leq b g(x, y), \quad t \in[0,1], x \in[0, r], y \in[0, r] .
$$

(H5) There are two constants $r>0, d>\beta$ such that

$$
f(t, x, y) \geq d g(x, y), \quad t \in[0,1], x \in[0, r], y \in[0, r] .
$$

(H6) There are two constants $c \in] 0, \beta\left[, c_{2}>0\right.$ such that

$$
f(t, x, y) \leq c g(x, y)+c_{2}, \quad t \in[0,1], x \in \mathbb{R}_{+}, y \in \mathbb{R}_{+} .
$$

(H7) $f(t, x, y)$ is increasing in $x, y$ and there is a constant $\omega>0$ such that $\int_{0}^{1}(1-\alpha(1-$ s) $) f(s, \omega, \omega) \mathrm{d} s<\beta \omega$.

Remark 3.1 By saying that $f(t, x, y)$ is increasing in $x, y$, we mean that, if $x_{2} \geq x_{1} \geq 0$ and $y_{2} \geq y_{1} \geq 0$, then the inequality $f\left(t, x_{2}, y_{2}\right) \geq f\left(t, x_{1}, y_{1}\right)$ holds for all $t \in[0,1]$.

Theorem 3.1 If(H1)-(H4) hold, then (1) has at least one positive solution.

## Proof Let

$$
\mathscr{M}_{1}:=\{u \in P: u=A u+\lambda \varphi, \text { for some } \lambda \geq 0\},
$$

where $\varphi(t):=t e^{-\beta t}$. Clearly, if $u \in \mathscr{M}_{1}$, then $u$ is increasing on [ 0,1 ], and $u(t) \geq(A u)(t), t \in$ $[0,1]$. We shall prove that $\mathscr{M}_{1}$ is bounded. We first establish the a priori bound of $\|u\|_{0}:=$ $\max \{u(t): 0 \leq t \leq 1\}=u(1)$ for $\mathscr{M}_{1}$. If $u \in \mathscr{M}_{1}$, then $A u \in C^{2}[0,1]$ (whence $u \in C^{2}[0,1]$ ) and there is $\lambda \geq 0$ such that $u=A u+\lambda \varphi$, and equivalently, $-u^{\prime \prime}(t)=f\left(t, u(t), u^{\prime}(t)\right)+\lambda(2-$ $\beta t) e^{-\beta t}$. Therefore, $u$ is concave on $[0,1]$ and $-u^{\prime \prime}(t) \geq f\left(t, u(t), u^{\prime}(t)\right)$. By (H2), we have

$$
-u^{\prime \prime}(t) \geq a g\left(u(t), u^{\prime}(t)\right)-c_{1}=a\left(\beta u(t)+2 u^{\prime}(t)\right)-c_{1} .
$$

Multiply the preceding inequalities by $\psi(t):=t e^{\beta t}$ and integrate over [0,1] and invoke Lemma 2.3 to obtain

$$
\beta \int_{0}^{1}\left(\beta u(t)+2 u^{\prime}(t)\right) \psi(t) \mathrm{d} t \geq a \int_{0}^{1}\left(\beta u(t)+2 u^{\prime}(t)\right) \psi(t) \mathrm{d} t-\frac{c_{1}\left(1-\alpha e^{\beta}\right)}{\beta^{2}}
$$

and whence

$$
\int_{0}^{1}\left(\beta u(t)+2 u^{\prime}(t)\right) \psi(t) \mathrm{d} t \leq \frac{c_{1}\left(1-\alpha e^{\beta}\right)}{(a-\beta) \beta^{2}}, \quad \forall u \in \mathscr{M}_{1}
$$

Invoking Lemma 2.4 yields

$$
\|u\|_{0}=u(1) \leq \frac{c_{1}}{(a-\beta) \beta}:=M, \quad \forall u \in \mathscr{M}_{1},
$$

thereby establishing the a priori bound of $\|u\|_{0}$ for $\mathscr{M}_{1}$. Now we turn to establish the a priori bound of $\left\|u^{\prime}\right\|_{0}$ for $\mathscr{M}_{1}$. Indeed, if $u \in \mathscr{M}_{1}$, then $u \in C^{2}[0,1]$ (as explained previously) and there is a constant $\lambda \geq 0$ such that $u=A u+\lambda \psi$, which can be equivalently rewritten as

$$
-u^{\prime \prime}(t)=f\left(t, u(t), u^{\prime}(t)\right)+\lambda \beta(2-\beta t) e^{-\beta t} .
$$

Let

$$
\mu:=\sup \{\lambda \geq 0: u=A u+\lambda \varphi \text { for some } u \in P\} .
$$

Then $\mu<\infty$ and, for every $u \in \mathscr{M}_{1}$, we have

$$
-u^{\prime \prime}(t) \leq f\left(t, u(t), u^{\prime}(t)\right)+\mu \beta(2-\beta t) e^{-\beta t} \leq f\left(t, u, u^{\prime}\right)+2 \mu \beta
$$

By (H3), there is a function $\Phi_{M} \in C\left(\mathbb{R}_{+}, \mathbb{R}_{+}\right)$such that

$$
-u^{\prime \prime}(t) \leq \Phi_{M}\left(u^{\prime}(t)\right)+2 \mu \beta
$$

This implies that

$$
\begin{aligned}
\int_{0}^{1}-\frac{u^{\prime \prime}(t) u^{\prime}(t) \mathrm{d} t}{\Phi_{M}\left(u^{\prime}(t)\right)+2 \mu \beta} & =\int_{u^{\prime}(1)}^{u^{\prime}(0)} \frac{\xi \mathrm{d} \xi}{\Phi_{M}(\xi)+2 \mu \beta}=\int_{\alpha u(1)}^{u^{\prime}(0)} \frac{\xi \mathrm{d} \xi}{\Phi_{M}(\xi)+2 \mu \beta} \\
& \leq \int_{0}^{1} u^{\prime}(t) \mathrm{d} t=u(1)
\end{aligned}
$$

Noticing $u(1) \leq M, \forall u \in \mathscr{M}_{1}$, we obtain

$$
\int_{\alpha M}^{u^{\prime}(0)} \frac{\xi \mathrm{d} \xi}{\Phi_{M}(\xi)+2 \mu \beta} \leq \int_{\alpha u(1)}^{u^{\prime}(0)} \frac{\xi \mathrm{d} \xi}{\Phi_{M}(\xi)+2 \mu \beta} \leq u(1) \leq M, \quad \forall u \in \mathscr{M}_{1} .
$$

Now (H3) means that there is a constant $M_{1}>0$ such that

$$
\left\|u^{\prime}\right\|_{0}=u^{\prime}(0) \leq M_{1}, \quad \forall u \in \mathscr{M}_{1}
$$

thereby establishing the a priori bound of $u^{\prime}$ for $\mathscr{M}_{1}$. This, together with $\|u\|_{0} \leq M$, implies that the $\mathscr{M}_{1}$ is bounded. Taking $R>\sup \left\{\|u\|: u \in \mathscr{M}_{1}\right\}$, we have

$$
u \neq A u+\lambda \varphi, \quad \forall u \in \partial B_{R} \cap P, \lambda \geq 0
$$

where $B_{R}:=\{u \in E:\|u\|<R\}$. Invoking Lemma 2.1 gives

$$
\begin{equation*}
i\left(A, B_{R} \cap P, P\right)=0 . \tag{5}
\end{equation*}
$$

On the other hand, let

$$
\mathscr{M}_{2}:=\left\{u \in \bar{B}_{r} \cap P: u=\lambda A u \text { for some } \lambda \in[0,1]\right\}
$$

where $r>0$ is specified by (H4). We are in a position to prove that $\mathscr{M}_{2}=\{0\}$. Indeed, if $u \in \mathscr{M}_{2}$, then $A u \in C^{2}[0,1]$ (whence $u \in C^{2}[0,1]$ ) and there is $\lambda \in[0,1]$ such that $u=\lambda A u$, which is equivalent to $-u^{\prime \prime}(t)=\lambda f\left(t, u(t), u^{\prime}(t)\right)$. By (H4), we have

$$
-u^{\prime \prime}(t) \leq f\left(t, u(t), u^{\prime}(t)\right) \leq b\left(\beta u(t)+2 u^{\prime}(t)\right), \quad \forall u \in \bar{B}_{r} \cap P .
$$

Multiply the preceding inequalities by $\psi(t):=t e^{\beta t}$ and integrate over $[0,1]$ and use Lemma 2.3 to obtain

$$
\beta \int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t \leq b \int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t,
$$

whence $u=0$, and, in turn, $\mathscr{M}_{2}=\{0\}$, as desired. As a result of this, we have

$$
u \neq \lambda A u, \quad \forall u \in \partial B_{r} \cap P, \lambda \in[0.1] .
$$

Then invoking Lemma 2.2 yields

$$
\begin{equation*}
i\left(A, B_{r} \cap P, P\right)=1 \tag{6}
\end{equation*}
$$

Obviously, we may assume $R>r$ in (5) and (6). Therefore, combining (5) and (6), we arrive at

$$
i\left(A,\left(B_{R} \backslash \bar{B}_{r}\right) \cap P, P\right)=i\left(A, B_{R} \cap P, P\right)-i\left(A, B_{r} \cap P, P\right)=0-1=-1 .
$$

Consequently, the operator $A$ has at least one fixed point on $\left(B_{R} \backslash \bar{B}_{r}\right) \cap P$. Equivalently, (1) has at least one positive solution $u$. This completes the proof.

Theorem 3.2 If (H1), (H5) and (H6) hold, then (1) has at least one positive solution.

## Proof Let

$$
\mathscr{M}_{3}:=\{u \in P: u=\lambda A u \text { for some } \lambda \in[0,1]\} .
$$

We are going to prove that $\mathscr{M}_{3}$ is bounded. Indeed, if $u \in \mathscr{M}_{3}$, then $A u \in C^{2}[0,1]$ (whence $\left.u \in C^{2}[0,1]\right)$ and there is $\lambda \in[0,1]$ such that $u=\lambda A u$, which is equivalent to $-u^{\prime \prime}(t)=$ $\lambda f\left(t, u(t), u^{\prime}(t)\right)$. By (H6), we have

$$
-u^{\prime \prime}(t) \leq f\left(t, u(t), u^{\prime}(t)\right) \leq c\left(\beta u(t)+2 u^{\prime}(t)\right)+c_{2} .
$$

Multiply the preceding inequalities by $\psi(t):=t e^{\beta t}$ and integrate over [0,1] and use Lemma 2.3 to obtain

$$
\beta \int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t \leq c \int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t+\frac{c_{2}\left(1-\alpha e^{\beta}\right)}{\beta^{2}}
$$

whence

$$
\int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t \leq \frac{c_{2}\left(1-\alpha e^{\beta}\right)}{(\beta-c) \beta^{2}}, \quad \forall u \in \mathscr{M}_{3} .
$$

Now Lemma 2.4 implies

$$
\|u\|_{0}=u(1) \leq \frac{c_{2}}{(\beta-c) \beta}:=M_{2}, \quad \forall u \in \mathscr{M}_{3} .
$$

By (H6) again, we have

$$
-u^{\prime \prime}(t) \leq 2 c u^{\prime}(t)+M_{2}+c_{2}, \quad \forall u \in \mathscr{M}_{3} .
$$

Some basic calculations, along with the boundary value condition $u^{\prime}(1)=\alpha u(1)$, imply

$$
u^{\prime}(0) \leq \alpha e^{2 c} u(1)+\frac{M_{2}\left(e^{2 c}-1\right)}{2 c} \leq \alpha e^{2 c} M_{2}+\frac{M_{2}\left(e^{2 c}-1\right)}{2 c}:=M_{3}, \quad \forall u \in \mathscr{M}_{3} .
$$

This establishes the a priori bound of $\left\|u^{\prime}\right\|_{0}$ for $\mathscr{M}_{3}$, which, together with the a priori bound of $\|u\|_{0}$, implies the boundedness of $\mathscr{M}_{3}$. Taking $R>\sup \left\{\|u\|: u \in \mathscr{M}_{3}\right\}$, we have

$$
u \neq \lambda A u, \quad \forall u \in \partial B_{R} \cap P, \lambda \in[0,1] .
$$

Invoking Lemma 2.2 yields

$$
\begin{equation*}
i\left(A, B_{R} \cap P, P\right)=1 \tag{7}
\end{equation*}
$$

On the other hand, let

$$
\mathscr{M}_{4}:=\left\{u \in \bar{B}_{r} \cap P: u=A u+\lambda \varphi \text { for some } \lambda \geq 0\right\}
$$

where $r>0$ is specified in (H5). We shall prove that $\mathscr{M}_{4} \subset\{0\}$. Indeed, if $u \in \mathscr{M}_{4}$, then $A u \in C^{2}[0,1]$ (whence $u \in C^{2}[0,1]$ ) and there is $\lambda \geq 0$ such that $u=A u+\lambda \varphi$, which is equivalent to $-u^{\prime \prime}(t)=f\left(t, u(t), u^{\prime}(t)\right)+\lambda \beta(2+(1-\lambda) t) e^{\beta t}$. By (H5), we have

$$
-u^{\prime \prime}(t) \geq f\left(t, u(t), u^{\prime}(t)\right) \geq d\left(\beta u(t)+2 u^{\prime}(t)\right)
$$

Multiply the preceding inequalities by $\psi(t):=t e^{\beta t}$ and integrate over [0,1] and use Lemma 2.3 to obtain

$$
\beta \int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t \geq d \int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t,
$$

whence

$$
\int_{0}^{1}\left(2 u^{\prime}(t)+\beta u(t)\right) t e^{\beta t} \mathrm{~d} t=0
$$

Therefore $u=0$, and, in turn, $\mathscr{M}_{4} \subset\{0\}$, as desired, and this implies

$$
u \neq A u+\lambda \varphi, \quad \forall u \in \partial B_{r} \cap P, \lambda \geq 0
$$

Now invoking Lemma 2.1 gives

$$
\begin{equation*}
i\left(A, B_{r} \cap P, P\right)=0 . \tag{8}
\end{equation*}
$$

Combining (7) and (8), we arrive at

$$
\begin{equation*}
i\left(A,\left(B_{R} \backslash \bar{B}_{r}\right) \cap P, P\right)=i\left(A, B_{R} \cap P, P\right)-i\left(A, B_{r} \cap P, P\right)=1-0=1 \tag{9}
\end{equation*}
$$

Consequently, the operator $A$ has at least one fixed point on $\left(B_{R} \backslash \bar{B}_{r}\right) \cap P$. Equivalently, (1) has at least one positive solution $u$. This completes the proof.

Theorem 3.3 If (H1)-(H3), (H5) and (H7) hold, then (1) has at least two positive solutions.

Proof (H1)-(H3) and (H5) imply that (5) and (8) hold(see the proofs of Theorems 3.1 and 3.2). On the other hand, by (H7), we have

$$
\begin{aligned}
\|A u\|_{0} & =(A u)(1)=\int_{0}^{1} k(1, s) f\left(s, u(s), u^{\prime}(s)\right) \mathrm{d} s \\
& \leq \frac{1}{\beta} \int_{0}^{1} s f(s, \omega, \omega) \mathrm{d} s \\
& \leq \frac{1}{\beta} \int_{0}^{1}(1-\alpha(1-s)) f(s, \omega, \omega) \mathrm{d} s \\
& <\omega, \forall u \in \partial B_{\omega} \cap P
\end{aligned}
$$

and

$$
\begin{aligned}
\left\|(A u)^{\prime}\right\|_{0} & =(A u)^{\prime}(0)=\frac{1}{\beta} \int_{0}^{1}(1-\alpha(1-s)) k(1, s) f\left(s, u(s), u^{\prime}(s)\right) \mathrm{d} s \\
& \leq \frac{1}{\beta} \int_{0}^{1}(1-\alpha(1-s)) f(s, \omega, \omega) \mathrm{d} s \\
& <\omega, \quad \forall u \in \partial B_{\omega} \cap P,
\end{aligned}
$$

whence

$$
\|A u\|<\|u\|=\omega, \quad \forall u \in \partial B_{\omega} \cap P
$$

This implies

$$
u \neq \lambda A u, \quad \forall u \in \partial B_{\omega} \cap P, \lambda \in[0,1] .
$$

Invoking Lemma 2.2 yields

$$
\begin{equation*}
i\left(A, B_{\omega} \cap P, P\right)=1 . \tag{10}
\end{equation*}
$$

This, along with (5) and (8), leads to

$$
i\left(A,\left(B_{R} \backslash \bar{B}_{\omega}\right) \cap P, P\right)=0-1=-1
$$

and

$$
i\left(A,\left(B_{\omega} \backslash \bar{B}_{r}\right) \cap P, P\right)=1-0=1 .
$$

Therefore, $A$ has at least two positive fixed points, one on $\left(B_{R} \backslash \bar{B}_{\omega}\right) \cap P$ and the other on $\left(B_{\omega} \backslash \bar{B}_{r}\right) \cap P$. This implies (1) has at least two positive solutions, which completes the proof.

An example of multiple positive solutions Let

$$
f(t, x, y):=\lambda\left(x^{p_{1}}+y^{q_{1}}+x^{p_{2}}+y^{q_{2}}\right),
$$

where $p_{1}>1,2 \geq q_{1}>1,1>p_{2}, q_{2}>0, \frac{1-\alpha}{4-2 \alpha}>\lambda>0$. Then (H1)-(H3), (H5) and (H7) hold. By Theorem 3.3, (1), with $f$ being defined as above, has two positive solutions.
Now we present some extra results paralell with Theorems 3.1-3.3.
Let $\lambda_{1}$ be the minimal positive solution of the transcendental equation

$$
\sqrt{\lambda}=\alpha \tan \sqrt{\lambda} .
$$

Then $\lambda_{1}$ is the first characteristic value of

$$
\left\{\begin{array}{l}
-u^{\prime \prime}=\lambda u, \\
u(0)=u^{\prime}(1)-\alpha u(1)=0 .
\end{array}\right.
$$

And $\varphi_{1}(t):=\sin \sqrt{\lambda_{1}} t$ is a characteristic function thereof.
It is worthwhile to point out that (H2) and (H4)-(H6) all are described in terms of the function $g(x, y):=\beta x+2 y$. We replace (H2) and (H5) with the conditions below described in terms of $\lambda_{1}$ :
(H2) There are two constants $a>\lambda_{1}$ and $c_{1}>0$ such that

$$
f(t, x, y) \geq a x-c_{1}, \quad \forall x \geq 0, y \geq 0, t \in[0,1] .
$$

(H5)' There are two constants $r>0, d>\lambda_{1}$ such that

$$
f(t, x, y) \geq d x, \quad t \in[0,1], x \in[0, r], y \in[0, r] .
$$

What follows is a result obtained by elementary calculus.

Lemma 3.1 If $u \in P$ is concave on $[0,1]$ with $u(0)=0$, then

$$
u(1) \leq \frac{\alpha^{2}}{\beta} \sin \sqrt{\lambda_{1}} \sec ^{2} \sqrt{\lambda_{1}} \int_{0}^{1} u(t) \sin \sqrt{\lambda_{1}} t \mathrm{~d} t
$$

The following three results are paralell counterparts of Theorems 3.1-3.3, acquired by replacing (H2) and (H5) with (H2)' and (H5)', respectively.

Theorem 3.1' If(H1), (H2)',(H3) and (H4) hold, then (1) has at least one positive solution.

Proof Recall that (H2) serves to establish the a priori bound of $\|u\|_{0}$ (see the proof of Theorem 3.1 for more details). The obtaining of the a priori bound of $\|u\|_{0}$ can proceed as that of the proof of Theorem 3.1 with replacing $\psi(t):=t e^{\beta t}$ with $\varphi_{1}(t):=\sin \sqrt{\lambda_{1}} t$ and employing Lemma 3.1. Then we may keep the remainder of the proof of Theorem 3.1 unchanged. This completes the proof.

Theorem 3.2' If(H1), (H5)' and (H6) hold, then (1) has at least one positive solution.
Theorem 3.3' If (H1), (H2) , (H3), (H5) and (H7) hold, then (1) has at least two positive solutions.

## 4 Uniqueness of positive solutions and iteration convergence

Let

$$
w_{0}(t):=\frac{(2-\alpha) t-\beta t^{2}}{2 \beta}=\int_{0}^{1} k(t, s) \mathrm{d} s .
$$

Then

$$
w_{0}^{\prime}(t)=\frac{2-\alpha-2 \beta t}{2 \beta} \geq \frac{\alpha}{2 \beta}, \quad t \in[0,1] .
$$

Below is a result that is easy to prove.

Lemma 4.1 If $h \in C\left([0,1], \mathbb{R}_{+}\right), h(t) \not \equiv 0$, then there are two positive constants $M_{h} \geq m_{h}$ such that

$$
m_{h} w_{0}(t) \leq \int_{0}^{1} k(t, s) h(s) \mathrm{d} s \leq M_{h} w_{0}(t), m_{h} w_{0}^{\prime}(t) \leq \int_{0}^{1} \frac{\partial}{\partial t} k(t, s) h(s) \mathrm{d} s \leq M_{h} w_{0}^{\prime}(t)
$$

(H8) $f$ is increasing in $x, y$ and $f(t, \lambda x, \lambda y)>\lambda f(t, x, y)$ for all $x>0, y>0$ and $t \in[0,1]$.

Theorem 4.1 If (H1), (H5), (H6) and (H8) hold, then (1) has exactly one positive solution.

Proof By Theorem 3.2, (1) has at least one positive solution. It remains to prove the uniqueness of positive solutions. Indeed, if $u_{1} \in C^{2}[0,1] \cap P$ and $u_{2} \in C^{2}[0,1] \cap P$ are two positive solutions, then

$$
\left.u_{i}(t)>0, \quad u_{i}^{\prime}(t)>0, \quad \forall t \in\right] 0,1[(i=1,2) .
$$

By Lemma 4.1, there are four constants $m_{i}, M_{i}$ such that

$$
m_{i} w_{0}(t) \leq u_{i}(t) \leq M_{i} w_{0}(t), \quad m_{i} w_{0}^{\prime}(t) \leq u_{i}^{\prime}(t) \leq M_{i} w_{0}^{\prime}(t) \quad(i=1,2)
$$

Therefore

$$
u_{1}(t) \geq \frac{m_{1}}{M_{2}} w_{0}(t), \quad u_{1}^{\prime}(t) \geq \frac{m_{1}}{M_{2}} w_{0}^{\prime}(t)
$$

Let

$$
\mu:=\left\{\lambda>0: u_{1}(t) \geq \lambda u_{2}(t), u_{1}^{\prime}(t) \geq \lambda u_{2}^{\prime}(t)\right\} .
$$

We claim that $\mu \geq 1$. Indeed, if the claim were false, then $0<\mu<1$ and $u_{1}(t) \geq \mu u_{2}(t)$ and $u_{1}^{\prime}(t) \geq \mu u_{2}^{\prime}(t)$. Let

$$
\left.\omega(t):=f\left(t, \mu u_{2}(t), \mu u_{2}^{\prime}(t)\right)\right)-\mu f\left(t, u_{2}(t), u_{2}^{\prime}(t)\right)
$$

(H8) implies $\omega(t)>0, t \in] 0,1[$. By Lemma 4.1 again, there is a constant $\varepsilon>0$ such that

$$
\int_{0}^{1} k(t, s) \omega(s) \mathrm{d} s \geq \varepsilon w_{0}(t), \quad t \in[0,1] .
$$

Therefore, we have

$$
\begin{aligned}
u_{1}(t) & =\int_{0}^{1} k(t, s) f\left(s, u_{1}(s), u_{1}^{\prime}(s)\right) \mathrm{d} s \\
& \geq \int_{0}^{1} k(t, s) f\left(s, \mu u_{2}(s), \mu u_{2}^{\prime}(s)\right) \mathrm{d} s \\
& =\int_{0}^{1} k(t, s) \omega(s) \mathrm{d} s+\mu \int_{0}^{1} k(t, s) f\left(s, u_{2}(s), u_{2}^{\prime}(s)\right) \mathrm{d} s \\
& \geq(\varepsilon+\mu) u_{2}(t) \\
u_{1}^{\prime}(t) & =\int_{0}^{1} \frac{\partial}{\partial t} k(t, s) f\left(s, u_{1}(s), u_{1}^{\prime}(s)\right) \mathrm{d} s \\
& \geq \int_{0}^{1} \frac{\partial}{\partial t} k(t, s) f\left(s, \mu u_{2}(s), \mu u_{2}^{\prime}(s)\right) \mathrm{d} s \\
& =\int_{0}^{1} \frac{\partial}{\partial t} k(t, s) \omega(s) \mathrm{d} s+\mu \int_{0}^{1} \frac{\partial}{\partial t} k(t, s) f\left(s, u_{2}(s), u_{2}^{\prime}(s)\right) \mathrm{d} s \\
& \geq(\varepsilon+\mu) u_{2}^{\prime}(t) .
\end{aligned}
$$

The preceding two inequalities contradict the very definition of $\mu$. As a result, we have proved that $\mu \geq 1$ and thus $u_{1}(t) \geq u_{2}(t)$. Similarly, $u_{1}(t) \geq u_{1}(t)$. Therefore $u_{1}(t) \equiv u_{2}(t)$. This proves the uniqueness of positive solutions of (1).

Recall that we have defined, in the proof of Theorem 3.1, the function $\varphi \in P \backslash\{0\}$ by

$$
\varphi(t):=t e^{-\beta t}
$$

It is easy to see that

$$
\begin{equation*}
\int_{0}^{1} k(t, s)\left(\beta \varphi(s)+2 \varphi^{\prime}(s)\right) \mathrm{d} s=\frac{\varphi(t)}{\beta} \tag{11}
\end{equation*}
$$

By Lemma 4.1, we obtain the result below.

Lemma 4.2 Given every $h \in C\left([0,1], \mathbb{R}_{+}\right), h \not \equiv 0$, there exist two positive solutions $M_{h} \geq m_{h}$ such that

$$
m_{h} \varphi(t) \leq \int_{0}^{1} k(t, s) h(s) \mathrm{d} s \leq M_{h} \varphi(t), m_{h} \varphi^{\prime}(t) \leq \int_{0}^{1} \frac{\partial}{\partial t} k(t, s) h(s) \mathrm{d} s \leq M_{h} \varphi^{\prime}(t)
$$

Notice that the cone $P$ defines a partial ordering $\lesssim$ in $E$ :

$$
u \lesssim v \quad \Longleftrightarrow \quad u(t) \leq v(t), \quad u^{\prime}(t) \leq v^{\prime}(t), \quad t \in[0,1] .
$$

Lemma 4.3 If(H1) and (H5) hold, then there is a constant $\delta>0$ such that for every $\varepsilon \in] 0, \delta]$, $u_{\varepsilon}(t):=\varepsilon \varphi(t)$ is a subsolution of the operator $A u=u$, i.e. $A u_{\varepsilon} \gtrsim u_{\varepsilon}$.

## Proof Let

$$
\delta:=r=\frac{r}{\left\|\varphi^{\prime}\right\|_{0}}<\frac{r}{\|\varphi\|_{0}}=e^{\beta} r .
$$

Then, by (H5) and (11), for every $\varepsilon \in] 0, \delta]$, we have

$$
\begin{aligned}
& \left(A u_{\varepsilon}\right)(t) \geq d \int_{0}^{1} k(t, s)\left(\beta u_{\varepsilon}(s)+2 u_{\varepsilon}^{\prime}(s)\right) \mathrm{d} s=\frac{d}{\beta} u_{\varepsilon}(t) \geq u_{\varepsilon}(t), \\
& \left(A u_{\varepsilon}\right)^{\prime}(t) \geq d \int_{0}^{1} \frac{\partial}{\partial t} k(t, s)\left(\beta u_{\varepsilon}(s)+2 u_{\varepsilon}^{\prime}(s)\right) \mathrm{d} s=\frac{d}{\beta} u_{\varepsilon}^{\prime}(t) \geq u_{\varepsilon}^{\prime}(t),
\end{aligned}
$$

or, equivalently, $A u_{\varepsilon} \gtrsim u_{\varepsilon}$.

Lemma 4.4 If (H1) and $(H 6)$ hold, then there is a constant $m_{0}>0$ such that for all $m \geq m_{0}$, $v_{m}(t):=m \varphi(t)$ is a supersolution of the operator equation $A u=u$, i.e. $A v_{m} \lesssim v_{m}$.

Proof By (H6) and Lemma 4.2, for every $m>0$,

$$
\begin{aligned}
\left(A v_{m}\right)(t) & =\int_{0}^{1} k(t, s) f\left(s, v_{m}(s), v_{m}^{\prime}(s)\right) \mathrm{d} s \\
& \leq \int_{0}^{1} k(t, s)\left(c \beta v_{m}(s)+2 c v_{m}^{\prime}(s)+c_{2}\right) \mathrm{d} s \\
& =\frac{c v_{m}(t)}{\beta}+c_{2} w_{0}(t) \\
& \leq \frac{c m \varphi(t)}{\beta}+\frac{c_{2} e^{\beta}}{2 \beta} \varphi(t)
\end{aligned}
$$

and

$$
\begin{aligned}
\left(A v_{m}\right)^{\prime}(t) & =\int_{0}^{1} \frac{\partial}{\partial t} k(t, s) f\left(s, v_{m}(s), v_{m}^{\prime}(s)\right) \mathrm{d} s \\
& \leq \int_{0}^{1} \frac{\partial}{\partial t} k(t, s)\left(c \beta v_{m}(s)+2 c v_{m}^{\prime}(s)+c_{2}\right) \mathrm{d} s \\
& =\frac{c m \varphi^{\prime}(t)}{\beta}+c_{2} \varphi_{0}^{\prime}(t) \\
& \leq \frac{c m \varphi^{\prime}(t)}{\beta}+\frac{c_{2} e^{\beta}}{2 \beta} \varphi^{\prime}(t),
\end{aligned}
$$

where

$$
\frac{e^{\beta}}{2 \beta}=\sup _{0<t<1} \frac{w_{0}(t)}{\varphi(t)}=\max _{0 \leq t \leq 1} \frac{w_{0}^{\prime}(t)}{\varphi^{\prime}(t)} .
$$

Let

$$
m_{0}:=\frac{c_{2} e^{\beta}}{2(\beta-c)} .
$$

Then, for every $m \geq m_{0},\left(A v_{m}\right)(t) \leq v_{m}(t),\left(A v_{m}\right)^{\prime}(t) \leq v_{m}^{\prime}(t)$, or equivalently, $A v_{m} \lesssim v_{m}$, i.e. $v_{m}$ is a supersolution of the operator equation $A u=u$.

Theorem 4.2 If (H1), (H5), (H6) and (H8) hold, then, for every $u \in P \backslash\{0\}$, the iterative sequence $\left\{A^{n} u\right\}$ converges to the unique positive solution of (1) by the norm of $C^{1}[0,1]$.

Proof By (H6) and (H8), we have $A(P \backslash\{0\}) \subset P \backslash\{0\}$. For every $u \in P \backslash\{0\}, A u$ is increasing in $[0,1],(A u)(0)=(A u)^{\prime}(1)-\alpha(A u)(1)=0$, and

$$
(A u)^{\prime}(t)=\frac{1}{\beta} \int_{0}^{t}(1-\alpha(1-s)) f\left(s, u(s), u^{\prime}(s)\right) \mathrm{d} s+\frac{\alpha}{\beta} \int_{t}^{1} s f\left(s, u(s), u^{\prime}(s)\right) \mathrm{d} s>0 .
$$

Therefore there are positive constants $c_{1}(u), c_{2}(u)$ such that

$$
c_{1}(u)(1-\beta t) e^{-\beta t} \leq(A u)^{\prime}(t) \leq c_{2}(u)(1-\beta t) e^{-\beta t}, \quad t \in[0,1] .
$$

Therefore

$$
c_{1}(u) \varphi(t) \leq(A u)(t) \leq c_{2}(u) \varphi(t), \quad t \in[0,1],
$$

and, in turn,

$$
\begin{equation*}
c_{1}(u) \varphi \lesssim A u \lesssim c_{2}(u) \varphi, \quad \forall u \in P \backslash\{0\} . \tag{12}
\end{equation*}
$$

This, along with Lemmas 4.3 and 4.4, implies that there are two positive constants constant $\varepsilon$ and $m$ such that $u_{0}:=\varepsilon \varphi$ and $\nu_{0}:=m \varphi$ are a subsolution and a supersolution of
the operator equation $A u=u$, respectively, and $u_{0} \lesssim A u \lesssim \nu_{0}$. By (H8), A:P $\rightarrow P$ is an increasing operator. Therefore, for every positive integer $n$,

$$
A^{n-1} u_{0} \lesssim A^{n} u \lesssim A^{n-1} v_{0} .
$$

As is well known, $\left\{A^{n} u_{0}\right\}$ and $\left\{A^{n} v_{0}\right\}$ converge to the maximum fixed point and the minimum fixed point in the ordering interval $\left[u_{0}, v_{0}\right]\left(:=\left\{u \in P: u_{0} \lesssim u \lesssim v_{0}\right\}\right)$, respectively. By Theorem 4.1, (1) has exactly one positive solution $u^{*}$, and thus $A$ has exactly one positive fixed point $u^{*}$. As a result of that, $\left\{A^{n} u_{0}\right\}$ and $\left\{A^{n} v_{0}\right\}$ has the same limit $u^{*}$. Thus the normality of $P$ implies that $\left\{A^{n} u\right\}$ converges to $u^{*}$ by the norm of $C^{1}[0,1]$.

An example for the uniqueness of positive solutions Let

$$
f(t, x, y):=x^{p}+y^{q},
$$

where $0<p, q<1$. Then (H1), (H5), (H6) and (H8) hold. By Theorem 4.2, for every $u_{0} \in$ $P \backslash\{0\}$, the iterative sequence

$$
u_{n+1}(t):=\int_{0}^{1} k(t, s)\left(u_{n}(s)^{p}+u_{n}^{\prime}(s)^{q}\right) \mathrm{d} s, \quad n=0,1,2, \ldots
$$

converges, by the norm of $E:=C^{1}[0,1]$, to the unique positive solution of Problem (1) with $f$ defined above.

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## Availability of data and materials

This paper focuses on theoretical analysis, not involving experiments and data.

## Competing interests

The author declares that they have no competing interests.
Authors' contributions
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