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# Limit cycle bifurcations in a planar piecewise quadratic system with multiple parameters

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## Abstract

This paper is concerned with the number of limit cycles bifurcating from a period annulus for some planar piecewise smooth non-Hamiltonian systems. We construct a planar piecewise quadratic system with multiple parameters, obtain its lower bound for the maximum number of limit cycles by using Melnikov function method, and find more limit cycles than (Li and Liu in *J. Math. Anal. Appl.* 428:1354–1367, 2015).

**Keywords:** Piecewise smooth system; Melnikov function method; Limit cycle

## 1 Introduction

In the last decades, the study of piecewise smooth systems has attracted great interest for their wider range of application in modeling real phenomena [2, 3]. Quite a few methods and interesting results have been obtained on limit cycle bifurcations of piecewise smooth systems. For example, the authors in [4, 5] studied the problem of homoclinic bifurcation of piecewise smooth systems and the authors in [6, 7] studied the problem of Hopf bifurcations of piecewise smooth systems. Many research works concerned planar piecewise quadratic systems with two zones separated by a straight line. For example, the authors in [8] studied the maximum number of limit cycles which can bifurcate from the periodic orbits of the quadratic isochronous centers perturbed inside discontinuous quadratic polynomial differential systems. By perturbing a center of discontinuous Bautin system, nine limit cycles have been found in [9] and ten limit cycles have been obtained in [10]. Recently, the authors in [11] claimed the lower bound for the Hilbert number is 16 in piecewise quadratic systems with two zones.

Roughly speaking, there are several methods to estimate the number of limit cycles of planar piecewise smooth systems. For example, by computing Lyapunov constants to study the maximal number of limit cycles obtained in switching systems, see [9, 10]. By using the averaging theory to study the periodic solutions of discontinuous piecewise systems, see [8, 12–14] etc. In [15], an expression of the first order Melnikov function is derived to study the number of limit cycles bifurcated from the periodic orbits of piecewise Hamiltonian systems. Later, the authors [16, 17] developed the Melnikov function method to near-Hamiltonian systems with multiple parameters. Specifically, for the following sys-

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tem:

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{cases} \begin{pmatrix} H_y^+(x,y,\lambda) + \varepsilon p^+(x,y,\lambda) \\ -H_x^+(x,y,\lambda) + \varepsilon q^+(x,y,\lambda) \end{pmatrix}, & x > 0, \\ \begin{pmatrix} H_y^-(x,y,\lambda) + \varepsilon p^-(x,y,\lambda) \\ -H_x^-(x,y,\lambda) + \varepsilon q^-(x,y,\lambda) \end{pmatrix}, & x \leq 0, \end{cases} \tag{1.1}$$

where  $0 < \varepsilon \ll \lambda \ll 1$ ,  $H^\pm$ ,  $p^\pm$ , and  $q^\pm$  are  $C^\infty$  functions in  $(x, y)$  and depend on small parameter  $\lambda$ . In this case, the first order Melnikov function  $M$  of (1.1) depends on parameter  $\lambda$  and it has an expansion of the form

$$M(h, \lambda) = M_0(h) + \lambda M_1(h) + \lambda^2 M_2(h) + O(\lambda^3). \tag{1.2}$$

The formulas for  $M_1$  and  $M_2$  were deduced in [17] under some conditions. When  $M_0(h)$  is not zero identically, then for  $0 < \lambda \ll 1$  one can study the number of limit cycles by using  $M_0(h)$ . When  $M_0(h) \equiv 0$  and  $M_1(h)$  is not zero identically, then for  $0 < \lambda \ll 1$  one can study the number of limit cycles by using  $M_1(h)$ , and so forth.

The authors [1] considered the following planar piecewise smooth system:

$$(\dot{x}, \dot{y}) = \begin{cases} (y(1 + ax) + \varepsilon P^+(x, y), -x(1 + ax) + \varepsilon Q^+(x, y)), & x > 0, \\ (y(1 + bx) + \varepsilon P^-(x, y), -x(1 + bx) + \varepsilon Q^-(x, y)), & x \leq 0, \end{cases} \tag{1.3}$$

where

$$P^\pm(x, y) = \sum_{i+j=0}^n p_{ij}^\pm x^i y^j, \quad Q^\pm(x, y) = \sum_{i+j=0}^n q_{ij}^\pm x^i y^j.$$

It is not hard to see that system (1.3)| $_{\varepsilon=0}$  has a first integral of the form  $H(x, y) = \frac{1}{2}(x^2 + y^2)$  and the origin is a center. Let  $L_h$  denote the periodic orbit of (1.3)| $_{\varepsilon=0}$ , given by  $L_h = L_h^+ \cup L_h^-$  for  $h \in (0, \frac{1}{2}\eta^2)$ , where

$$L_h^+ = \left\{ (x, y) \mid \frac{1}{2}(x^2 + y^2) = h, x > 0 \right\}, \quad L_h^- = \left\{ (x, y) \mid \frac{1}{2}(x^2 + y^2) = h, x \leq 0 \right\},$$

and

$$\eta = \begin{cases} \min\{-\frac{1}{a}, \frac{1}{b}\}, & a < 0, b > 0, \\ -\frac{1}{a}, & a < 0, b \leq 0, \\ \frac{1}{b}, & a \geq 0, b > 0, \\ +\infty, & a \geq 0, b \leq 0. \end{cases}$$

The authors in [1] gave a linear estimation of the maximum number (denoted by  $H(n)$ ) of limit cycles which bifurcate from any compact region of the period annulus of system (1.3) for all possible bounded coefficients  $p_{ij}^\pm$  and  $q_{ij}^\pm$  independent of the small parameter  $\varepsilon$  up to the first order averaging method, and proved the following results:

- (i) If  $ab \neq 0$  and  $a \neq -b$ , then  $H(n) = 2[\frac{n+1}{2}] + n + 1$ .
- (ii) If  $ab \neq 0$  and  $a = -b$ , then  $H(n) = [\frac{n+1}{2}] + n$ .
- (iii) If  $a \neq 0, b = 0$  or  $a = 0, b \neq 0$ , then  $H(n) = [\frac{n+1}{2}] + n + 1$ .

Clearly, for the case of  $n = 2$ , one has particularly

$$H(2) = \begin{cases} 5, & \text{for } ab \neq 0 \text{ and } a \neq -b, \\ 3, & \text{for } ab \neq 0 \text{ and } a = -b, \\ 4, & \text{for } a \neq 0, b = 0 \text{ or } a = 0, b \neq 0. \end{cases}$$

Inspired by [15, 17], we construct a system with multiple parameters and obtain its lower bound for the maximum number of limit cycles by using  $M_1(h)$  in (1.2). Our main result can be stated in the following.

**Theorem 1.1** *There is a system of the form (1.3) with  $n = 2$  and  $|\varepsilon|$  sufficiently small such that it has*

- (i) seven limit cycles for  $ab \neq 0$  and  $a \neq -b$ ;
- (ii) four limit cycles for  $ab \neq 0$  and  $a = -b$ ;
- (iii) five limit cycles for  $a \neq 0, b = 0$  or  $a = 0, b \neq 0$ .

We remark that for  $a = b = 0$  system (1.3) is a piecewise smooth near-Hamiltonian system and can have  $n$  limit cycles, which has already been studied in [15]. Comparing with [1], for the case of  $n = 2$ , our lower bound for the maximum number of limit cycles is one or two bigger for each case.

This paper is organized as follows. In Sect. 2, we introduce a second small parameter  $\lambda$  to (1.3) with  $n = 2$  and give some preliminaries. In Sect. 3, we calculate the function  $M_1(h)$  for each case and prove our main result.

## 2 Preliminaries

Consider the following piecewise quadratic polynomial system with multiple parameters:

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{cases} \begin{pmatrix} (y + \lambda H_{1y}^+)(1 + ax) + \varepsilon(P_0^+(x, y) + \lambda P_1^+(x, y)) \\ -(x + \lambda H_{1x}^+)(1 + ax) + \varepsilon(Q_0^+(x, y) + \lambda Q_1^+(x, y)) \end{pmatrix}, & x > 0, \\ \begin{pmatrix} (y + \lambda H_{1y}^-)(1 + bx) + \varepsilon(P_0^-(x, y) + \lambda P_1^-(x, y)) \\ -(x + \lambda H_{1x}^-)(1 + bx) + \varepsilon(Q_0^-(x, y) + \lambda Q_1^-(x, y)) \end{pmatrix}, & x \leq 0, \end{cases} \tag{2.1}$$

where  $0 < |\varepsilon| \ll \lambda \ll 1$ ,  $H_1^\pm(x, y) = \sum_{i+j=1}^2 h_{ij}^\pm x^i y^j$ , and

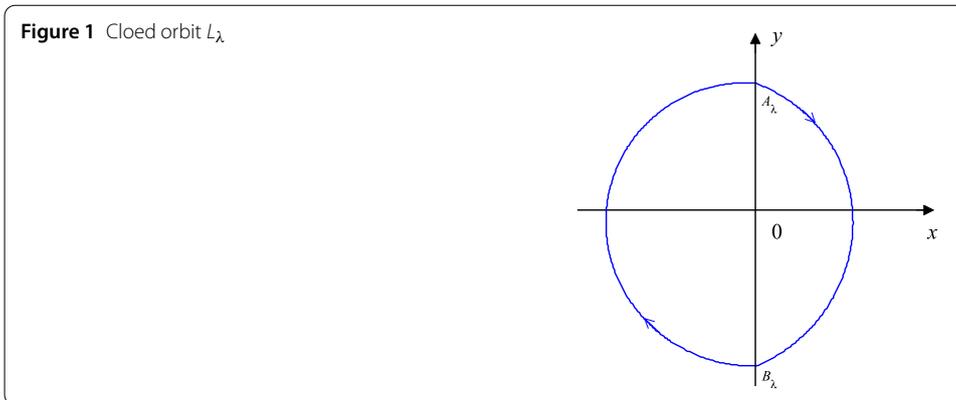
$$P_k^\pm(x, y) = \sum_{i+j=0}^2 p_{kij}^\pm x^i y^j, \quad Q_k^\pm(x, y) = \sum_{i+j=0}^2 q_{kij}^\pm x^i y^j, \quad k = 0, 1. \tag{2.2}$$

Obviously, (2.1) is a piecewise smooth near-integrable system. In the region  $\{L_h | h \in (0, \frac{1}{2}\eta^2)\}$ , system (2.1) is equivalent to the following near-Hamiltonian differential system:

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{cases} \begin{pmatrix} y + \lambda H_{1y}^+ + \varepsilon \left( \frac{P_0^+(x, y)}{1 + ax} + \lambda \frac{P_1^+(x, y)}{1 + ax} \right) \\ -x - \lambda H_{1x}^+ + \varepsilon \left( \frac{Q_0^+(x, y)}{1 + ax} + \lambda \frac{Q_1^+(x, y)}{1 + ax} \right) \end{pmatrix}, & 0 < x < \eta, \\ \begin{pmatrix} y + \lambda H_{1y}^- + \varepsilon \left( \frac{P_0^-(x, y)}{1 + bx} + \lambda \frac{P_1^-(x, y)}{1 + bx} \right) \\ -x - \lambda H_{1x}^- + \varepsilon \left( \frac{Q_0^-(x, y)}{1 + bx} + \lambda \frac{Q_1^-(x, y)}{1 + bx} \right) \end{pmatrix}, & -\eta < x \leq 0. \end{cases} \tag{2.3}$$

Therefore, by [15], the first order Melnikov function of (2.3) can be expressed as

$$M(h, \lambda) = \int_{A_\lambda B_\lambda} q^+ dx - p^+ dy + \frac{H_y^+(A_\lambda, \lambda)}{H_y^-(A_\lambda, \lambda)} \int_{B_\lambda A_\lambda} q^- dx - p^- dy, \tag{2.4}$$



where

$$\begin{aligned}
 H^\pm(x, y, \lambda) &= \frac{x^2 + y^2}{2} + \lambda H_1^\pm(x, y), \\
 p^+ &= \frac{P_0^+(x, y)}{1 + ax} + \lambda \frac{P_1^+(x, y)}{1 + ax}, & q^+ &= \frac{Q_0^+(x, y)}{1 + ax} + \lambda \frac{Q_1^+(x, y)}{1 + ax}, \\
 p^- &= \frac{P_0^-(x, y)}{1 + bx} + \lambda \frac{P_1^-(x, y)}{1 + bx}, & q^- &= \frac{Q_0^-(x, y)}{1 + bx} + \lambda \frac{Q_1^-(x, y)}{1 + bx},
 \end{aligned} \tag{2.5}$$

and  $A_\lambda = (0, a(h, \lambda))$ ,  $B_\lambda = (0, b(h, \lambda))$  with  $a(h, \lambda) > b(h, \lambda)$  satisfying  $H^+(A_\lambda) = H^+(B_\lambda) = h$ ,  $H^-(A_\lambda) = H^-(B_\lambda)$  for  $h \in (0, \frac{1}{2}\eta^2)$ .  $\widehat{A_\lambda B_\lambda}$  is an orbital arc starting from  $A_\lambda$  and ending at  $B_\lambda$  defined by  $H^+(x, y, \lambda) = h$ ,  $x > 0$ ;  $\widehat{B_\lambda A_\lambda}$  is an orbital arc starting from  $B_\lambda(h)$  and ending at  $A_\lambda(h)$  defined by  $H^-(x, y, \lambda) = H^-(B_\lambda(h))$ ,  $x \leq 0$ . Clearly, for given  $h \in (0, \frac{1}{2}\eta^2)$ ,  $\widehat{A_\lambda B_\lambda}$  and  $\widehat{B_\lambda A_\lambda}$  form a closed orbit  $L_\lambda$  with clockwise orientation(see Fig. 1).

By [17], for  $0 < \lambda \ll 1$ , (2.4) has an expansion of the form (1.2), where

$$M_0(h) = \int_{\widehat{AB}} \frac{Q_0^+}{1 + ax} dx - \frac{P_0^+}{1 + ax} dy + \int_{\widehat{BA}} \frac{Q_0^-}{1 + bx} dx - \frac{P_0^-}{1 + bx} dy, \tag{2.6}$$

with  $A = A_\lambda|_{\lambda=0}$ ,  $B = B_\lambda|_{\lambda=0}$ . Obviously, for given  $h \in (0, \frac{1}{2}\eta^2)$ ,  $\widehat{AB}$  and  $\widehat{BA}$  form a closed orbit  $L_0(h)$ , defined by  $\frac{1}{2}(x^2 + y^2) = h$ .

Suppose  $h_{0j}^- = h_{0j}^+$  ( $j = 1, 2$ ), so that the points on  $\widehat{A_\lambda B_\lambda}$  and  $\widehat{B_\lambda A_\lambda}$  satisfy

$H^\pm(x, y, \lambda) = h$ ,  $\pm x \geq 0$ ,  $h \in (0, \frac{1}{2}\eta^2)$ . Then, by Theorem 1.1 of [17],  $M_1(h)$  has the form

$$M_1(h) = M_{11}(h) + M_{12}(h) + M_{13}(h), \tag{2.7}$$

where

$$\begin{aligned}
 M_{11}(h) &= \int_{\widehat{AB}} \frac{Q_1^+}{1 + ax} dx - \frac{P_1^+}{1 + ax} dy + \int_{\widehat{BA}} \frac{Q_1^-}{1 + bx} dx - \frac{P_1^-}{1 + bx} dy, \\
 M_{12}(h) &= - \int_{\widehat{AB}} H_1^+ \left( \left( \frac{P_0^+}{1 + ax} \right)_x + \left( \frac{Q_0^+}{1 + ax} \right)_y \right) dt \\
 &\quad - \int_{\widehat{BA}} H_1^- \left( \left( \frac{P_0^-}{1 + bx} \right)_x + \left( \frac{Q_0^-}{1 + bx} \right)_y \right) dt, \\
 M_{13}(h) &= \mathcal{I} \left( \frac{P_0^+}{1 + ax} \right) \Big|_{\lambda=0} - \mathcal{I} \left( \frac{P_0^-}{1 + bx} \right) \Big|_{\lambda=0}
 \end{aligned} \tag{2.8}$$

with

$$\mathcal{I}(r) = r(0, a(h, \lambda)) \frac{\partial a}{\partial \lambda} - r(0, b(h, \lambda)) \frac{\partial b}{\partial \lambda} \tag{2.9}$$

for a  $C^\infty$  function  $r(x, y)$ .

Since the authors in [18] have proved the equivalence of the Melnikov function method and the averaging method, by using  $M_0(h)$  we can obtain the same number of limit cycles as that obtained by using the first order averaging method in [1]. By formula (15) of [1], it is not hard to obtain the following lemma that gives the necessary and sufficient conditions for  $M_0(h) \equiv 0$ .

**Lemma 2.1** *For  $ab \neq 0$  and  $a \neq -b$ ,  $M_0(h) \equiv 0$  if and only if*

$$\begin{aligned} p_{000}^- &= p_{000}^+, & q_{001}^+ &= \frac{1}{a}(p_{002}^+ + q_{011}^+), & q_{001}^- &= \frac{1}{b}(p_{002}^- + q_{011}^-), \\ p_{010}^+ &= ap_{000}^+ + \frac{1}{a}p_{020}^+, & p_{010}^- &= bp_{000}^- + \frac{1}{b}p_{020}^-, & & \\ p_{020}^- &= -\frac{b}{a}(p_{002}^+ + p_{020}^+ + q_{011}^+) - p_{002}^- - q_{011}^-. \end{aligned} \tag{2.10}$$

For  $ab \neq 0$  and  $a = -b$ ,  $M_0(h) \equiv 0$  if and only if

$$\begin{aligned} p_{000}^- &= p_{000}^+, & q_{001}^- &= \frac{1}{a}(p_{002}^+ + q_{011}^+ - p_{002}^- - q_{011}^-) - q_{001}^+, \\ p_{010}^- &= \frac{1}{a}(p_{002}^- + q_{011}^- - p_{002}^+ - q_{011}^+) - p_{010}^+, & & \\ p_{020}^- &= p_{002}^+ + p_{020}^+ + q_{011}^+ - p_{002}^- - q_{011}^-. \end{aligned} \tag{2.11}$$

For  $a \neq 0, b = 0$ ,  $M_0(h) \equiv 0$  if and only if

$$\begin{aligned} p_{000}^- &= p_{000}^+, & p_{002}^- &= -2p_{020}^- - q_{011}^-, & q_{001}^+ &= \frac{1}{a}(p_{002}^+ + q_{011}^+), \\ p_{010}^+ &= ap_{000}^+ + \frac{1}{a}p_{020}^+, & p_{010}^- &= -\frac{1}{a}(p_{002}^+ + p_{020}^+ + q_{011}^+) - q_{001}^-. \end{aligned} \tag{2.12}$$

For  $b \neq 0, a = 0$ ,  $M_0(h) \equiv 0$  if and only if

$$\begin{aligned} p_{000}^- &= p_{000}^+, & p_{002}^+ &= -2p_{020}^+ - q_{011}^+, & q_{001}^- &= \frac{1}{b}(p_{002}^- + q_{011}^-), \\ p_{010}^- &= bp_{000}^- + \frac{1}{b}p_{020}^-, & p_{010}^+ &= -\frac{1}{b}(p_{002}^- + p_{020}^- + q_{011}^-) - q_{001}^+. \end{aligned} \tag{2.13}$$

### 3 Proof of the main result

In this section we prove Theorem 1.1. By (2.7), we know that  $M_1(h) = M_{11}(h) + M_{12}(h) + M_{13}(h)$ . In the following, we first divide three cases to calculate  $M_{1i}(h)$  ( $i = 1, 2, 3$ ).

*Case 1.  $ab \neq 0$  and  $a \neq -b$*

Suppose that (2.10) holds, so that  $M_0(h) \equiv 0$ . Let  $\sqrt{2h} = r$ . Then  $L_0(h)$  can be represented as  $x = r \cos \theta, y = r \sin \theta, r \in (0, \eta), \theta \in [-\frac{\pi}{2}, \frac{3\pi}{2}]$ . Then, by (2.8), we rewrite

$$M_{11}(h) = M_{11}^+(h) + M_{11}^-(h),$$

where

$$M_{11}^+(h) = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{\sum_{i+j=0}^2 r^{i+j+1} (q_{1ij}^+ \cos^i \theta \sin^{j+1} \theta + p_{1ij}^+ \cos^{i+1} \theta \sin^j \theta)}{1 + ar \cos \theta} d\theta \tag{3.1}$$

and

$$\begin{aligned} M_{11}^-(h) &= \int_{\frac{\pi}{2}}^{\frac{3\pi}{2}} \frac{\sum_{i+j=0}^2 r^{i+j+1} (q_{1ij}^- \cos^i \theta \sin^{j+1} \theta + p_{1ij}^- \cos^{i+1} \theta \sin^j \theta)}{1 + br \cos \theta} d\theta, \\ &= \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{\sum_{i+j=0}^2 (-r)^{i+j+1} (q_{1ij}^- \cos^i \theta \sin^{j+1} \theta + p_{1ij}^- \cos^{i+1} \theta \sin^j \theta)}{1 - br \cos \theta} d\theta. \end{aligned} \tag{3.2}$$

For the sake of convenience, introduce some notations as follows:

$$I_{ij}^+(r) = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{a^j r^j \cos^j \theta}{(1 + ar \cos \theta)^i} d\theta, \quad I_{ij}^-(r) = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{(-b)^j r^j \cos^j \theta}{(1 - br \cos \theta)^i} d\theta, \tag{3.3}$$

where  $ab \neq 0$  and  $i \in \mathbb{Z}, j \in \mathbb{N}$ .

By [1] and some simple definite integral calculations, we have

$$I_{2,0}^+(r) = \frac{I_{1,0}^+(r) - 2ar}{1 - a^2 r^2}, \quad I_{2,0}^-(r) = \frac{I_{1,0}^-(r) + 2br}{1 - b^2 r^2}, \tag{3.4}$$

where

$$I_{1,0}^+(r) = J(a, r), \quad I_{1,0}^-(r) = J(-b, r),$$

with

$$J(\nu, r) = \begin{cases} \frac{4}{\sqrt{1-\nu^2 r^2}} \left( \frac{\pi}{2} - \arctan\left(\sqrt{\frac{1+\nu r}{1-\nu r}}\right) \right), & \nu < 0, r \in (0, -\frac{1}{\nu}), \\ \frac{4}{\sqrt{1-\nu^2 r^2}} \arctan\left(\sqrt{\frac{1-\nu r}{1+\nu r}}\right), & \nu > 0, r \in (0, \frac{1}{\nu}), \\ 2, & \nu > 0, r = \frac{1}{\nu}, \\ \frac{2}{\sqrt{\nu^2 r^2 - 1}} \ln(\nu r + \sqrt{\nu^2 r^2 - 1}), & \nu > 0, r \in (\frac{1}{\nu}, +\infty). \end{cases}$$

Moreover, noting that  $a^j r^j \cos^j \theta = (1 + ar \cos \theta - 1)^j$ , then by using the binomial expansion

$$(1 + ar \cos \theta - 1)^j = \sum_{m=0}^j C_j^m (-1)^{j-m} (1 + ar \cos \theta)^m, \quad j \in \mathbb{N},$$

it is easy to deduce the following relationship:

$$I_{ij}^\pm(r) = \sum_{m=0}^j C_j^m (-1)^{j-m} I_{i-m,0}^\pm(r), \quad i \in \mathbb{Z}, j \in \mathbb{N}. \tag{3.5}$$

It is direct that

$$\begin{aligned} I_{0,0}^+(r) &= \pi, & I_{-1,0}^+(r) &= \pi + 2ar, & I_{-2,0}^+(r) &= \pi + 4ar + \frac{1}{2} \pi a^2 r^2, \\ I_{0,0}^-(r) &= \pi, & I_{-1,0}^-(r) &= \pi - 2br, & I_{-2,0}^-(r) &= \pi - 4br + \frac{1}{2} \pi b^2 r^2. \end{aligned} \tag{3.6}$$

In the following we will use  $I_{ij}^\pm$  instead of  $I_{ij}^\pm(r)$  for simplicity. Now, coming back to  $M_{11}^\pm(h)$ , (3.1) and (3.2) can be read as

$$M_{11}^+(h) = \frac{\gamma_{13}^+}{a^3} I_{1,3}^+ + \frac{\gamma_{12}^+}{a^2} I_{1,2}^+ + \frac{\gamma_{11}^+ r^2 + p_{100}^+}{a} I_{1,1}^+ + \gamma_{10}^+ r^2 I_{1,0}^+, \tag{3.7}$$

$$M_{11}^-(h) = \frac{\gamma_{13}^-}{b^3} I_{1,3}^- + \frac{\gamma_{12}^-}{b^2} I_{1,2}^- + \frac{\gamma_{11}^- r^2 + p_{100}^-}{b} I_{1,1}^- + \gamma_{10}^- r^2 I_{1,0}^-, \tag{3.8}$$

where

$$\begin{aligned} \gamma_{13}^\pm &= p_{120}^\pm - p_{102}^\pm - q_{111}^\pm, & \gamma_{12}^\pm &= p_{110}^\pm - q_{101}^\pm, \\ \gamma_{11}^\pm &= p_{102}^\pm + q_{111}^\pm, & \gamma_{10}^\pm &= q_{101}^\pm. \end{aligned} \tag{3.9}$$

Obviously,  $\gamma_{1i}^\pm$  ( $i = 0, 1, 2, 3$ ) can be taken as free parameters.

By (3.5) we have

$$\begin{aligned} I_{1,1}^\pm &= -I_{1,0}^\pm + I_{0,0}^\pm, & I_{1,2}^\pm &= I_{1,0}^\pm - 2I_{0,0}^\pm + I_{-1,0}^\pm, \\ I_{1,3}^\pm &= -I_{1,0}^\pm + 3I_{0,0}^\pm - 3I_{-1,0}^\pm + I_{-2,0}^\pm. \end{aligned} \tag{3.10}$$

Inserting (3.6) and (3.10) into (3.7) and (3.8) respectively yields

$$M_{11}^+(h) = d_{11}^+ (\pi - I_{1,0}^+) + d_{12}^+ r^2 I_{1,0}^+ + b_{11}^+ r + b_{12}^+ r^2, \tag{3.11}$$

$$M_{11}^-(h) = d_{11}^- (\pi - I_{1,0}^-) + d_{12}^- r^2 I_{1,0}^- - b_{11}^- r + b_{12}^- r^2, \tag{3.12}$$

where

$$\begin{aligned} d_{11}^+ &= \frac{p_{100}^+}{a} - \frac{\gamma_{12}^+}{a^2} + \frac{\gamma_{13}^+}{a^3}, & d_{12}^+ &= \gamma_{10}^+ - \frac{\gamma_{11}^+}{a}, \\ b_{11}^+ &= \frac{2\gamma_{12}^+}{a} - \frac{2\gamma_{13}^+}{a^2}, & b_{12}^+ &= \frac{\pi}{a} \left( \frac{\gamma_{13}^+}{2} + \gamma_{11}^+ \right), \\ d_{11}^- &= \frac{p_{100}^-}{b} - \frac{\gamma_{12}^-}{b^2} + \frac{\gamma_{13}^-}{b^3}, & d_{12}^- &= \gamma_{10}^- - \frac{\gamma_{11}^-}{b}, \\ b_{11}^- &= \frac{2\gamma_{12}^-}{b} - \frac{2\gamma_{13}^-}{b^2}, & b_{12}^- &= \frac{\pi}{b} \left( \frac{\gamma_{13}^-}{2} + \gamma_{11}^- \right). \end{aligned} \tag{3.13}$$

Clearly,  $d_{1i}^\pm, b_{1i}^\pm$  ( $i = 1, 2$ ) can be taken as free parameters.

Next, we calculate  $M_{12}(h)$ . Note that along the curve  $L_0(h)$ ,  $dt = -\frac{1}{x} dy$ . Hence, by (2.8), we have

$$M_{12}(h) = M_{12}^+(h) + M_{12}^-(h),$$

where

$$M_{12}^+(h) = - \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} H_1^+(r \cos \theta, r \sin \theta) \left( \frac{P_{0x}^+ + Q_{0y}^+}{1 + a r \cos \theta} - \frac{a P_0^+}{(1 + a r \cos \theta)^2} \right) d\theta, \tag{3.14}$$

$$M_{12}^-(h) = - \int_{\frac{\pi}{2}}^{\frac{3\pi}{2}} H_1^-(r \cos \theta, r \sin \theta) \left( \frac{P_{0x}^- + Q_{0y}^-}{1 + b r \cos \theta} - \frac{b P_0^-}{(1 + b r \cos \theta)^2} \right) d\theta. \tag{3.15}$$

Through a direct computation, we obtain

$$M_{12}^+(h) = - \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \left[ \frac{a_{10}^+ r^2 + (a_{11}^+ r^2 + \tilde{a}_{11}^+) r \cos \theta + a_{12}^+ r^2 \cos^2 \theta + a_{13}^+ r^3 \cos^3 \theta}{1 + ar \cos \theta} - a((a_{20}^+ r^4 + \tilde{a}_{20}^+ r^2) + (a_{21}^+ r^2 + \tilde{a}_{21}^+) r \cos \theta + (a_{22}^+ r^2 + \tilde{a}_{22}^+) r^2 \cos^2 \theta + a_{23}^+ r^3 \cos^3 \theta + a_{24}^+ r^4 \cos^4 \theta) / ((1 + ar \cos \theta)^2) \right] d\theta,$$

and

$$M_{12}^-(h) = - \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \left[ \frac{a_{10}^- r^2 - (a_{11}^- r^2 + \tilde{a}_{11}^-) r \cos \theta + a_{12}^- r^2 \cos^2 \theta - a_{13}^- r^3 \cos^3 \theta}{1 - br \cos \theta} - b((a_{20}^- r^4 + \tilde{a}_{20}^- r^2) - (a_{21}^- r^2 + \tilde{a}_{21}^-) r \cos \theta + (a_{22}^- r^2 + \tilde{a}_{22}^-) r^2 \cos^2 \theta - a_{23}^- r^3 \cos^3 \theta + a_{24}^- r^4 \cos^4 \theta) / ((1 - br \cos \theta)^2) \right] d\theta,$$

where

$$\begin{aligned} a_{10}^\pm &= h_{02}^\pm (p_{010}^\pm + q_{001}^\pm) + h_{01}^\pm (p_{011}^\pm + 2q_{002}^\pm), & \tilde{a}_{11}^\pm &= h_{10}^\pm (p_{010}^\pm + q_{001}^\pm), \\ a_{11}^\pm &= h_{02}^\pm (2p_{020}^\pm + q_{011}^\pm) + h_{11}^\pm (p_{011}^\pm + 2q_{002}^\pm), & a_{13}^\pm &= h_{20}^\pm (2p_{020}^\pm + q_{011}^\pm) - a_{11}^\pm, \\ a_{12}^\pm &= h_{20}^\pm (p_{010}^\pm + q_{001}^\pm) + h_{10}^\pm (2p_{020}^\pm + q_{011}^\pm) - a_{10}^\pm, & \tilde{a}_{20}^\pm &= h_{01}^\pm p_{001}^\pm + h_{02}^\pm p_{000}^\pm, \\ a_{20}^\pm &= h_{02}^\pm p_{002}^\pm, & \tilde{a}_{21}^\pm &= h_{10}^\pm p_{000}^\pm, & a_{21}^\pm &= h_{01}^\pm p_{011}^\pm + h_{02}^\pm p_{010}^\pm + h_{11}^\pm p_{001}^\pm + h_{10}^\pm p_{002}^\pm, \\ \tilde{a}_{22}^\pm &= (h_{20}^\pm - h_{02}^\pm) p_{000}^\pm - h_{01}^\pm p_{001}^\pm + h_{10}^\pm p_{010}^\pm, & a_{23}^\pm &= h_{10}^\pm p_{020}^\pm + h_{20}^\pm p_{010}^\pm - a_{21}^\pm, \\ a_{22}^\pm &= (h_{20}^\pm - 2h_{02}^\pm) p_{002}^\pm + h_{02}^\pm p_{020}^\pm + h_{11}^\pm p_{011}^\pm, & a_{24}^\pm &= h_{20}^\pm p_{020}^\pm - h_{02}^\pm p_{002}^\pm - a_{22}^\pm. \end{aligned} \tag{3.16}$$

Further, by (3.3), one achieves

$$M_{12}^+(h) = N^+(a, r), \quad M_{12}^-(h) = N^-(b, r),$$

where

$$\begin{aligned} N^\pm(v, r) &= -a_{10}^\pm r^2 I_{1,0}^\pm - \frac{(a_{11}^\pm r^2 + \tilde{a}_{11}^\pm)}{v} I_{1,1}^\pm - \frac{a_{12}^\pm}{v^2} I_{1,2}^\pm - \frac{a_{13}^\pm}{v^3} I_{1,3}^\pm + v(a_{20}^\pm r^4 + \tilde{a}_{20}^\pm r^2) I_{2,0}^\pm \\ &+ v \left( \frac{a_{21}^\pm r^2 + \tilde{a}_{21}^\pm}{v} I_{2,1}^\pm + \frac{a_{22}^\pm r^2 + \tilde{a}_{22}^\pm}{v^2} I_{2,2}^\pm + \frac{a_{23}^\pm}{v^3} I_{2,3}^\pm + \frac{a_{24}^\pm}{v^4} I_{2,4}^\pm \right). \end{aligned}$$

In view of (3.5), we have

$$\begin{aligned} I_{2,1}^\pm &= -I_{2,0}^\pm + I_{1,0}^\pm, & I_{2,3}^\pm &= -I_{2,0}^\pm + 3I_{1,0}^\pm - 3I_{0,0}^\pm + I_{-1,0}^\pm, \\ I_{2,2}^\pm &= I_{2,0}^\pm - 2I_{1,0}^\pm + I_{0,0}^\pm, & I_{2,4}^\pm &= I_{2,0}^\pm - 4I_{1,0}^\pm + 6I_{0,0}^\pm - 4I_{-1,0}^\pm + I_{-2,0}^\pm. \end{aligned} \tag{3.17}$$

It follows from (3.10) and (3.17) that

$$M_{12}^+(h) = k_1^+ r^4 I_{2,0}^+ + k_2^+ r^2 I_{2,0}^+ + k_3^+ r^2 I_{1,0}^+ + k_4^+ (\pi - I_{1,0}^+) + k_5^+ r + k_6^+ r^2, \tag{3.18}$$

$$M_{12}^-(h) = k_1^- r^4 I_{2,0}^- + k_2^- r^2 I_{2,0}^- + k_3^- r^2 I_{1,0}^- + k_4^- (\pi - I_{1,0}^-) - k_5^- r + k_6^- r^2, \tag{3.19}$$

where

$$k_i^+ = m_i^+(a), \quad k_i^- = m_i^-(b), \quad i = 1, 2, \dots, 6, \tag{3.20}$$

with

$$\begin{aligned} m_1^\pm(v) &= va_{20}^\pm, \\ m_2^\pm(v) &= -\frac{a_{24}^\pm}{v} + a_{23}^\pm + \frac{a_{22}^\pm}{v} - a_{21}^\pm - v\tilde{a}_{22}^\pm - v^2\tilde{a}_{21}^\pm + v\tilde{a}_{20}^\pm, \\ m_3^\pm(v) &= -\frac{2a_{22}^\pm}{v} + a_{21}^\pm + \frac{a_{11}^\pm}{v} - a_{10}^\pm, \\ m_4^\pm(v) &= \frac{3a_{24}^\pm}{v^3} - \frac{2a_{23}^\pm}{v^2} + \frac{\tilde{a}_{22}^\pm}{v} - \frac{a_{13}^\pm}{v^3} + \frac{a_{12}^\pm}{v^2} - \frac{\tilde{a}_{11}^\pm}{v}, \\ m_5^\pm(v) &= -\frac{6a_{24}^\pm}{v^2} + \frac{4a_{23}^\pm}{v} + \frac{2a_{13}^\pm}{v^2} - \frac{2a_{12}^\pm}{v} - 2\tilde{a}_{22}^\pm + 2v\tilde{a}_{21}^\pm, \\ m_6^\pm(v) &= \frac{\pi}{2v}(a_{24}^\pm + 2a_{22}^\pm - a_{13}^\pm - 2a_{11}^\pm). \end{aligned} \tag{3.21}$$

Now we are in the position to calculate  $M_{13}(h)$ . Recall that

$$H^+(0, a(h, \lambda), \lambda) = H^+(0, b(h, \lambda), \lambda) = h, \quad a(h, \lambda) > b(h, \lambda).$$

Thus, we have from (2.5)

$$a(h, \lambda) = \frac{-h_{01}^+ \lambda + \sqrt{\Delta}}{1 + 2h_{02}^+ \lambda}, \quad b(h, \lambda) = \frac{-h_{01}^+ \lambda - \sqrt{\Delta}}{1 + 2h_{02}^+ \lambda},$$

where

$$\Delta = h_{01}^{+2} \lambda^2 + 4hh_{02}^+ \lambda + 2h.$$

Consequently,

$$a(h, \lambda)|_{\lambda=0} = \sqrt{2h}, \quad b(h, \lambda)|_{\lambda=0} = -\sqrt{2h}, \tag{3.22}$$

and

$$\left. \frac{\partial a}{\partial \lambda} \right|_{\lambda=0} = -h_{01}^+ - h_{02}^+ \sqrt{2h}, \quad \left. \frac{\partial b}{\partial \lambda} \right|_{\lambda=0} = -h_{01}^+ + h_{02}^+ \sqrt{2h}. \tag{3.23}$$

Therefore, by (2.8) and (2.10), we obtain

$$M_{13}(h) = 2h_{01}^+(p_{001}^- - p_{001}^+)r + 2h_{02}^+(p_{002}^- - p_{002}^+)r^3. \tag{3.24}$$

Noting that  $h_{02}^- = h_{02}^+$ , by (3.16), (3.20) and (3.21), (3.24) reads

$$M_{13}(h) = 2h_{01}^+(p_{001}^- - p_{001}^+)r + 2\left(\frac{1}{b}k_1^- - \frac{1}{a}k_1^+\right)r^3. \tag{3.25}$$

Hence, combining (3.11), (3.12), (3.18), (3.19), and (3.25), we find that

$$\begin{aligned}
 M_1(h) &= l_1 \left( r^4 I_{2,0}^+ - \frac{2}{a} r^3 \right) + l_2 r^2 I_{2,0}^+ + l_3 r^2 I_{1,0}^+ + l_4 (\pi - I_{1,0}^+) + l_5 r + l_6 r^2 \\
 &\quad + l_7 \left( r^4 I_{2,0}^- + \frac{2}{b} r^3 \right) + l_8 r^2 I_{2,0}^- + l_9 r^2 I_{1,0}^- + l_{10} (\pi - I_{1,0}^-),
 \end{aligned} \tag{3.26}$$

where

$$\begin{aligned}
 l_1 &= k_1^+, & l_2 &= k_2^+, & l_3 &= k_3^+ + d_{12}^+, & l_4 &= k_4^+ + d_{11}^+, \\
 l_5 &= k_5^+ - k_5^- + b_{11}^+ - b_{11}^- + 2h_{01}^+ (p_{001}^- - p_{001}^+), & l_6 &= k_6^+ + k_6^- + b_{12}^+ + b_{12}^-, \\
 l_7 &= k_1^-, & l_8 &= k_2^-, & l_9 &= k_3^- + d_{12}^-, & l_{10} &= k_4^- + d_{11}^-.
 \end{aligned} \tag{3.27}$$

Case 2.  $ab \neq 0$  and  $a = -b$

Suppose that (2.11) holds, so that  $M_0(h) \equiv 0$ . If  $a = -b$ , then  $I_{i,0}^- = I_{i,0}^+$  ( $i = 1, 2$ ). By (3.26), we have

$$M_1(h) = \tilde{l}_1 \left( r^4 I_{2,0}^+ - \frac{2}{a} r^3 \right) + \tilde{l}_2 r^2 I_{2,0}^+ + \tilde{l}_3 r^2 I_{1,0}^+ + \tilde{l}_4 (\pi - I_{1,0}^+) + \tilde{l}_5 r + \tilde{l}_6 r^2, \tag{3.28}$$

where

$$\begin{aligned}
 \tilde{l}_1 &= l_1 + l_7, & \tilde{l}_2 &= l_2 + l_8, & \tilde{l}_3 &= l_3 + l_9, \\
 \tilde{l}_4 &= l_4 + l_{10}, & \tilde{l}_5 &= l_5, & \tilde{l}_6 &= l_6.
 \end{aligned} \tag{3.29}$$

Case 3.  $a \neq 0, b = 0$  or  $b \neq 0, a = 0$

Suppose that (2.12) holds, so that  $M_0(h) \equiv 0$ . Note that, for  $a \neq 0, b = 0, M_{11}^+(h), M_{12}^+(h)$ , and  $M_{13}(h)$  are identical to (3.11), (3.18), and (3.24) respectively. Hence, in order to give  $M_1(h)$ , it suffices to calculate  $M_{11}^-(h)$  and  $M_{12}^-(h)$ .

We have from (3.2)

$$\begin{aligned}
 M_{11}^-(h) &= \int_{\frac{\pi}{2}}^{\frac{3\pi}{2}} \sum_{i+j=0}^2 r^{i+j+1} (q_{1ij}^- \cos^i \theta \sin^{j+1} \theta + p_{1ij}^- \cos^{i+1} \theta \sin^j \theta) d\theta \\
 &= \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \sum_{i+j=0}^2 (-r)^{i+j+1} (q_{1ij}^- \cos^i \theta \sin^{j+1} \theta + p_{1ij}^- \cos^{i+1} \theta \sin^j \theta) d\theta \\
 &= -\gamma_{13}^- r^3 \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^3 \theta d\theta + \gamma_{12}^- r^2 \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^2 \theta d\theta \\
 &\quad - (\gamma_{11}^- r^2 + p_{100}^-) r \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \theta d\theta + \gamma_{10}^- r^2 \pi.
 \end{aligned} \tag{3.30}$$

Through a direct computation,

$$\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^3 \theta d\theta = \frac{4}{3}, \quad \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^2 \theta d\theta = \frac{\pi}{2}, \quad \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \theta d\theta = 2. \tag{3.31}$$

Thus, (3.30) becomes

$$M_{11}^-(h) = -2p_{100}^- r + \left( \pi \gamma_{10}^- + \frac{\pi}{2} \gamma_{12}^- \right) r^2 - \left( \frac{4}{3} \gamma_{13}^- + 2\gamma_{11}^- \right) r^3. \tag{3.32}$$

By (3.15), together with (3.31), we have

$$\begin{aligned} M_{12}^-(h) &= - \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} H_1^-(r \cos(\theta + \pi), r \sin(\theta + \pi)) (P_{0x}^- + Q_{0y}^-)(r \cos(\theta + \pi), r \sin(\theta + \pi)) d\theta \\ &= -\pi a_{10}^- r^2 + 2(a_{11}^- r^3 + \tilde{a}_{11}^- r) - \frac{\pi}{2} a_{12}^- r^2 + \frac{4}{3} a_{13}^- r^3 \\ &= 2\tilde{a}_{11}^- r - \frac{\pi}{2} (2a_{10}^- + a_{12}^-) r^2 + \left( 2a_{11}^- + \frac{4}{3} a_{13}^- \right) r^3. \end{aligned} \tag{3.33}$$

Combining (3.11), (3.18), (3.24), (3.32), and (3.33), one can obtain

$$M_1(h) = \bar{l}_1 r^4 I_{2,0}^+ + \bar{l}_2 r^2 I_{2,0}^+ + \bar{l}_3 r^2 I_{1,0}^+ + \bar{l}_4 (\pi - I_{1,0}^+) + \bar{l}_5 r + \bar{l}_6 r^2 + \bar{l}_7 r^3, \tag{3.34}$$

where

$$\begin{aligned} \bar{l}_1 &= k_1^+, & \bar{l}_2 &= k_2^+, & \bar{l}_3 &= k_3^+ + d_{12}^+, & \bar{l}_4 &= k_4^+ + d_{11}^+, \\ \bar{l}_5 &= k_5^+ + 2\tilde{a}_{11}^- + b_{11}^+ - 2p_{100}^- + 2h_{01}^+ (p_{001}^- - p_{001}^+), \\ \bar{l}_6 &= k_6^+ - \frac{\pi}{2} (2a_{10}^- + a_{12}^-) + b_{12}^+ + \pi \gamma_{10}^- + \frac{\pi}{2} \gamma_{12}^-, \\ \bar{l}_7 &= 2a_{11}^- + \frac{4}{3} a_{13}^- - \frac{4}{3} \gamma_{13}^- - 2\gamma_{11}^- + 2h_{02}^+ p_{002}^-. \end{aligned}$$

Similarly, suppose that (2.13) holds to ensure  $M_0(h) \equiv 0$ . Then, for the case  $b \neq 0, a = 0$ , we can obtain

$$M_1(h) = \widehat{l}_1 r^4 I_{2,0}^- + \widehat{l}_2 r^2 I_{2,0}^- + \widehat{l}_3 r^2 I_{1,0}^- + \widehat{l}_4 (\pi - I_{1,0}^-) + \widehat{l}_5 r + \widehat{l}_6 r^2 + \widehat{l}_7 r^3, \tag{3.35}$$

where

$$\begin{aligned} \widehat{l}_1 &= k_1^-, & \widehat{l}_2 &= k_2^-, & \widehat{l}_3 &= k_3^- + d_{12}^-, & \widehat{l}_4 &= k_4^- + d_{11}^-, \\ \widehat{l}_5 &= -k_5^- - 2\tilde{a}_{11}^+ - b_{11}^- + 2p_{100}^+ + 2h_{01}^+ (p_{001}^- - p_{001}^+), \\ \widehat{l}_6 &= k_6^- - \frac{\pi}{2} (2a_{10}^+ + a_{12}^+) + b_{12}^- + \pi \gamma_{10}^+ + \frac{\pi}{2} \gamma_{12}^+, \\ \widehat{l}_7 &= -2a_{11}^+ - \frac{4}{3} a_{13}^+ + \frac{4}{3} \gamma_{13}^+ + 2\gamma_{11}^+ - 2h_{02}^+ p_{002}^+. \end{aligned}$$

We can prove the following theorem.

**Theorem 3.1** *Suppose that  $M_0(h) \equiv 0$  and  $M_1(h)$  is not zero identically. Denote by  $Z_1(2)$  the maximum number of zeros of  $M_1(h)$  with  $0 < \lambda \ll 1$ . Then*

$$Z_1(2) = \begin{cases} 7, & \text{for } ab \neq 0 \text{ and } a \neq -b, \\ 4, & \text{for } ab \neq 0 \text{ and } a = -b, \\ 5, & \text{for } a \neq 0, b = 0 \text{ or } a = 0, b \neq 0. \end{cases}$$

*Proof* First, for the case  $ab \neq 0$  and  $a \neq -b$ , we study the number of zeros of  $M_1(h)$  in (3.26). We introduce the following coefficients:

$$\begin{aligned} c_1 &= h_{02}^+ p_{002}^+, & c_2 &= h_{01}^+ p_{011}^+, & c_3 &= d_{12}^+, & c_4 &= h_{01}^+ q_{002}^+, & c_5 &= b_{11}^+ - b_{11}^-, \\ c_6 &= h_{02}^- p_{002}^-, & c_7 &= h_{01}^- p_{011}^-, & c_8 &= d_{12}^-, & c_9 &= h_{01}^- q_{002}^-, & c_{10} &= b_{12}^+ + b_{12}^-. \end{aligned}$$

Since  $p_{1ij}^\pm$  and  $q_{1ij}^\pm$  are independent of  $p_{0ij}^\pm$  and  $q_{0ij}^\pm$ , so by (3.13) it is easy to see  $c_i$  ( $i = 1, 2, \dots, 10$ ) can be taken as free parameters as long as  $h_{0i}^\pm \neq 0$  ( $i = 1, 2$ ). Under condition (2.10), for  $ab \neq 0$ , one can obtain by (3.16), (3.20), (3.21), and (3.27)

$$\det \frac{\partial(l_1, l_1, \dots, l_{10})}{\partial(c_1, c_2, \dots, c_{10})} = \frac{16}{ab} \neq 0.$$

Similar to the proof of Corollary 2.4.1 in [19], one knows that  $l_i$  ( $i = 1, 2, \dots, 10$ ) in (3.26) can be taken as free parameters.

For  $0 < r \ll 1$ , we have the following Taylor expansions:

$$\begin{aligned} \pi - I_{1,0}^+ &= 2ar - \frac{\pi}{2}a^2r^2 + \frac{4}{3}a^3r^3 - \frac{3\pi}{8}a^4r^4 + \frac{16}{15}a^5r^5 - \frac{5\pi}{16}a^6r^6 + \frac{32}{35}a^7r^7 + O(r^8), \\ \pi - I_{1,0}^- &= -2br - \frac{\pi}{2}b^2r^2 - \frac{4}{3}b^3r^3 - \frac{3\pi}{8}b^4r^4 - \frac{16}{15}b^5r^5 - \frac{5\pi}{16}b^6r^6 - \frac{32}{35}b^7r^7 + O(r^8), \\ r^2 I_{1,0}^+ &= \pi r^2 - 2ar^3 + \frac{1}{2}\pi a^2r^4 - \frac{4}{3}a^3r^5 + \frac{3}{8}\pi a^4r^6 - \frac{16}{15}a^5r^7 + O(r^8), \\ r^2 I_{1,0}^- &= \pi r^2 + 2br^3 + \frac{\pi}{2}b^2r^4 + \frac{4}{3}b^3r^5 + \frac{3\pi}{8}b^4r^6 + \frac{16}{15}b^5r^7 + O(r^8), \\ r^2 I_{2,0}^+ &= \pi r^2 - 4ar^3 + \frac{3\pi}{2}a^2r^4 - \frac{16}{3}a^3r^5 + \frac{15\pi}{8}a^4r^6 - \frac{32}{5}a^5r^7 + O(r^8), \\ r^2 I_{2,0}^- &= \pi r^2 + 4br^3 + \frac{3\pi}{2}b^2r^4 + \frac{16}{3}b^3r^5 + \frac{15\pi}{8}b^4r^6 + \frac{32}{5}b^5r^7 + O(r^8). \end{aligned} \tag{3.36}$$

Inserting (3.36) into (3.26), we get

$$M_1(h) = \sum_{i \geq 1} A_i r^i, \quad 0 < r \ll 1, \tag{3.37}$$

where

$$\begin{aligned} A_1 &= 2al_4 + l_5 - 2bl_{10}, \\ A_2 &= \pi \left( l_2 + l_3 - \frac{1}{2}a^2l_4 + l_8 + l_9 - \frac{1}{2}b^2l_{10} \right) + l_6, \\ A_3 &= -\frac{2}{a}l_1 - 4al_2 - 2al_3 + \frac{4}{3}a^3l_4 + \frac{2}{b}l_7 + 4bl_8 + 2bl_9 - \frac{4}{3}b^3l_{10}, \\ A_4 &= \pi \left( l_1 + \frac{3}{2}a^2l_2 + \frac{1}{2}a^2l_3 - \frac{3}{8}a^4l_4 + l_7 + \frac{3}{2}b^2l_8 + \frac{1}{2}b^2l_9 - \frac{3}{8}b^4l_{10} \right), \\ A_5 &= -4al_1 - \frac{16}{3}a^3l_2 - \frac{4}{3}a^3l_3 + \frac{16}{15}a^5l_4 + 4bl_7 + \frac{16}{3}b^3l_8 + \frac{4}{3}b^3l_9 - \frac{16}{15}b^5l_{10}, \\ A_6 &= \pi \left( \frac{3}{2}a^2l_1 + \frac{15}{8}a^4l_2 + \frac{3}{8}a^4l_3 - \frac{5}{16}a^6l_4 + \frac{3}{2}b^2l_7 + \frac{15}{8}b^4l_8 + \frac{3}{8}b^4l_9 - \frac{5}{16}b^6l_{10} \right), \end{aligned} \tag{3.38}$$

$$\begin{aligned}
 A_7 &= -\frac{16}{3}a^3l_1 - \frac{32}{5}a^5l_2 - \frac{16}{15}a^5l_3 + \frac{32}{35}a^7l_4 + \frac{16}{3}b^3l_7 + \frac{32}{5}b^5l_8 + \frac{16}{15}b^5l_9 - \frac{32}{35}b^7l_{10}, \\
 A_8 &= \pi \left( \frac{15}{8}a^4l_1 + \frac{35}{16}a^6l_2 + \frac{5}{16}a^6l_3 - \frac{35}{128}a^8l_4 + \frac{15}{8}b^4l_7 \right. \\
 &\quad \left. + \frac{35}{16}b^6l_8 + \frac{5}{16}b^6l_9 - \frac{35}{128}b^8l_{10} \right)
 \end{aligned}$$

and  $A_i$  ( $i \geq 9$ ) are linear combinations of  $l_i$  ( $i = 1, 2, \dots, 10$ ).

By direct computation, for  $ab \neq 0$  and  $a \neq -b$ , we have by (3.38)

$$\det \frac{\partial(A_1, A_2, \dots, A_8)}{\partial(l_2, l_3, l_4, l_5, l_6, l_8, l_9, l_{10})} = \frac{\pi^3}{30,240} a^8 b^8 (a+b)^9 \neq 0. \tag{3.39}$$

Fix  $l_1$  and  $l_7$ . Take  $l_2 = -l_3 = -\frac{1}{a^2}l_1$ ,  $l_8 = -l_9 = -\frac{1}{b^2}l_7$ , and  $l_4 = l_5 = l_6 = l_{10} = 0$  such that  $A_1 = A_2 = \dots = A_8 = 0$ . Thus, by (3.39), (3.38) has the inverse  $l_i = l_i(A_1, A_2, \dots, A_8)$ ,  $i = 1, 2, \dots, 10$ , and consequently  $A_i = 0$  ( $i \geq 9$ ) as  $A_1 = A_2 = \dots = A_8 = 0$ . It follows that (3.38) can be rewritten as

$$M_1(h) = \sum_{i \geq 1}^8 A_i(1 + P_i(r))r^i, \quad 0 < r \ll 1, \tag{3.40}$$

where  $P_i(r) = O(r)$ ,  $i = 1, 2, \dots, 8$ . Hence, by Rolle’s theorem, (3.40) implies that  $M_1(h)$  has at most seven zeros in  $h$  for  $0 < \sqrt{2h} \ll 1$ .

On the other hand, (3.39) implies that  $A_1, A_2, \dots, A_8$  can be taken as free parameters. Letting  $\delta = (l_2, l_3, l_4, l_5, l_6, l_8, l_9, l_{10})$  and taking  $\delta_0 = (-\frac{1}{a^2}l_1, \frac{1}{a^2}l_1, 0, 0, 0, -\frac{1}{b^2}l_7, \frac{1}{b^2}l_7, 0)$ , we can choose proper value  $\delta$  near  $\delta_0$  such that

$$0 < A_1 \ll -A_2 \ll A_3 \ll -A_4 \ll A_5 \ll -A_6 \ll A_7 \ll -A_8 \ll 1,$$

which ensures that  $M_1(h)$  has seven zeros in  $h$  for  $0 < \sqrt{2h} \ll 1$ .

Second, consider the case  $ab \neq 0$  and  $a = -b$ . Obviously,  $\tilde{l}_i$  ( $i = 1, 2, \dots, 6$ ) in (3.29) can be taken as free parameters.

Inserting (3.36) into (3.28), we get

$$M_1(h) = \sum_{i \geq 1} \tilde{A}_i r^i, \quad 0 < r \ll 1, \tag{3.41}$$

where

$$\begin{aligned}
 \tilde{A}_1 &= 2a\tilde{a}\tilde{l}_4 + \tilde{l}_5, & \tilde{A}_2 &= \pi \left( \tilde{l}_2 + \tilde{l}_3 - \frac{1}{2}a^2\tilde{l}_4 \right) + \tilde{l}_6, \\
 \tilde{A}_3 &= -\frac{2}{a}\tilde{l}_1 - 4a\tilde{a}\tilde{l}_2 - 2a\tilde{l}_3 + \frac{4}{3}a^3\tilde{l}_4, & \tilde{A}_4 &= \pi \left( \tilde{l}_1 + \frac{3}{2}a^2\tilde{l}_2 + \frac{1}{2}a^2\tilde{l}_3 - \frac{3}{8}a^4\tilde{l}_4 \right), \\
 \tilde{A}_5 &= -4a\tilde{a}\tilde{l}_1 - \frac{16}{3}a^3\tilde{l}_2 - \frac{4}{3}a^3\tilde{l}_3 + \frac{16}{15}a^5\tilde{l}_4
 \end{aligned} \tag{3.42}$$

and  $\tilde{A}_i$  ( $i \geq 6$ ) are linear combinations of  $\tilde{l}_i$  ( $i = 1, 2, \dots, 6$ ). Moreover, for  $ab \neq 0$  and  $a = -b$ , we have by (3.42)

$$\det \frac{\partial(\tilde{A}_1, \tilde{A}_2, \dots, \tilde{A}_5)}{\partial(\tilde{l}_2, \tilde{l}_3, \tilde{l}_4, \tilde{l}_5, \tilde{l}_6)} = -\frac{2\pi}{45} a^8 \neq 0. \tag{3.43}$$

Similar to the above case,  $\tilde{A}_i = 0$  ( $i \geq 6$ ) if  $\tilde{A}_1 = \tilde{A}_2 = \dots = \tilde{A}_5 = 0$ . Thus,  $M_1(h)$  in (3.41) has at most four zeros in  $h$  for  $0 < \sqrt{2h} \ll 1$ .

Also, (3.43) implies that  $\tilde{A}_1, \tilde{A}_2, \dots, \tilde{A}_5$  can be taken as free parameters. Let  $\tilde{\delta} = (\tilde{l}_2, \tilde{l}_3, \tilde{l}_4, \tilde{l}_5, \tilde{l}_6)$  and take  $\tilde{\delta}_0 = (-\frac{1}{a^2}\tilde{l}_1, \frac{1}{a^2}\tilde{l}_1, 0, 0, 0)$ . Then  $\tilde{A}_1 = \tilde{A}_2 = \dots = \tilde{A}_5 = 0$  if  $\tilde{\delta} = \tilde{\delta}_0$ . Hence, we can choose proper value  $\tilde{\delta}$  near  $\tilde{\delta}_0$  such that

$$0 < \tilde{A}_1 \ll -\tilde{A}_2 \ll \tilde{A}_3 \ll -\tilde{A}_4 \ll \tilde{A}_5 \ll 1,$$

which ensures that  $M_1(h)$  has four zeros in  $h$  for  $0 < \sqrt{2h} \ll 1$ .

For the case  $a \neq 0, b = 0$ , it is easy to see  $\bar{l}_i$  ( $i = 1, 2, \dots, 7$ ) in (3.34) can be taken as free parameters. Then, by inserting (3.36) into (3.34), we get the expansion

$$M_1(h) = \sum_{i \geq 1} \bar{A}_i r^i, \quad 0 < r \ll 1, \tag{3.44}$$

where

$$\begin{aligned} \bar{A}_1 &= 2a\bar{l}_4 + \bar{l}_5, & \bar{A}_4 &= \pi \left( \bar{l}_1 + \frac{3}{2}a^2\bar{l}_2 + \frac{1}{2}a^2\bar{l}_3 - \frac{3}{8}a^4\bar{l}_4 \right), \\ \bar{A}_2 &= \pi \left( \bar{l}_2 + \bar{l}_3 - \frac{1}{2}a^2\bar{l}_4 \right) + \bar{l}_6, & \bar{A}_5 &= -4a\bar{l}_1 - \frac{16}{3}a^3\bar{l}_2 - \frac{4}{3}a^3\bar{l}_3 + \frac{16}{15}a^5\bar{l}_4, \\ \bar{A}_3 &= -4a\bar{l}_2 - 2a\bar{l}_3 + \frac{4}{3}a^3\bar{l}_4 + \bar{l}_7, & \bar{A}_6 &= \pi \left( \frac{3}{2}a^2\bar{l}_1 + \frac{15}{8}a^4\bar{l}_2 + \frac{3}{8}a^4\bar{l}_3 - \frac{5}{16}a^6\bar{l}_4 \right) \end{aligned} \tag{3.45}$$

and  $\bar{A}_i$  ( $i \geq 7$ ) are linear combinations of  $\bar{l}_i$  ( $i = 1, 2, \dots, 7$ ). By calculation, for  $a \neq 0$  and  $b = 0$ , we have by (3.45)

$$\det \frac{\partial(\bar{A}_1, \bar{A}_2, \dots, \bar{A}_6)}{\partial(\bar{l}_2, \bar{l}_3, \bar{l}_4, \bar{l}_5, \bar{l}_6, \bar{l}_7)} = -\frac{\pi^2}{240} a^{11} \neq 0. \tag{3.46}$$

By using the similar analysis, one can obtain that  $M_1(h)$  in (3.44) has at most five zeros in  $h$  for  $0 < \sqrt{2h} \ll 1$ . Moreover, (3.46) implies that  $\bar{A}_1, \bar{A}_2, \dots, \bar{A}_6$  can be taken as free parameters. Let  $\bar{\delta} = (\bar{l}_2, \bar{l}_3, \bar{l}_4, \bar{l}_5, \bar{l}_6, \bar{l}_7)$  and take  $\bar{\delta}_0 = (-\frac{1}{a^2}\bar{l}_1, \frac{1}{a^2}\bar{l}_1, 0, 0, 0, -\frac{2}{a}\bar{l}_1)$ . Then  $\bar{A}_1 = \bar{A}_2 = \dots = \bar{A}_5 = \bar{A}_6 = 0$  if  $\bar{\delta} = \bar{\delta}_0$ . Hence, we can choose proper value  $\bar{\delta}$  near  $\bar{\delta}_0$  such that

$$0 < \bar{A}_1 \ll -\bar{A}_2 \ll \bar{A}_3 \ll -\bar{A}_4 \ll \bar{A}_5 \ll -\bar{A}_6 \ll 1,$$

which ensures that  $M_1(h)$  has five zeros in  $h$  for  $0 < \sqrt{2h} \ll 1$ . In the case of  $b \neq 0, a = 0$ , the proof is similar. Theorem 3.1 is proved.  $\square$

*Proof of Theorem 1.1* It is not hard to see that system (2.1) can be rewritten as

$$(\dot{x}, \dot{y}) = \begin{cases} (y(1+ax) + \lambda F^+(x, y), -x(1+ax) + \lambda G^+(x, y)), & x > 0, \\ (y(1+bx) + \lambda F^-(x, y), -x(1+bx) + \lambda G^-(x, y)), & x \leq 0, \end{cases} \quad (3.47)$$

where

$$\begin{pmatrix} F^+(x, y) \\ G^+(x, y) \end{pmatrix} = \begin{pmatrix} H_{1y}^+(1+ax) + \sigma P_0^+(x, y) + \varepsilon P_1^+(x, y) \\ -H_{1x}^+(1+ax) + \sigma Q_0^+(x, y) + \varepsilon Q_1^+(x, y) \end{pmatrix}, \quad x > 0,$$

and

$$\begin{pmatrix} F^-(x, y) \\ G^-(x, y) \end{pmatrix} = \begin{pmatrix} H_{1y}^-(1+bx) + \sigma P_0^-(x, y) + \varepsilon P_1^-(x, y) \\ -H_{1x}^-(1+bx) + \sigma Q_0^-(x, y) + \varepsilon Q_1^-(x, y) \end{pmatrix}, \quad x \leq 0,$$

with  $0 < |\varepsilon| \ll \lambda \ll 1$  and  $\sigma = \frac{\varepsilon}{\lambda}$ . Obviously,  $0 < |\sigma| \ll 1$ .

By Theorem 3.1, there exists  $\lambda_0 > 0$  such that, for any  $\lambda \in (0, \lambda_0]$ ,  $M(h, \lambda)$  for system (3.47) has  $k$  ( $k = 7, 4, 5$  for each case) zeros in  $h$  for  $0 < \sqrt{2h} \ll 1$ . It follows that, for any  $\lambda \in (0, \lambda_0]$  and  $0 < |\varepsilon| \ll \lambda$ , system (3.47) can have  $k$  limit cycles. That is to say, for any  $\lambda \in (0, \lambda_0]$ , there exist  $\varepsilon_0$  and  $\sigma_0 = \frac{\varepsilon_0}{\lambda}$  satisfying  $0 < |\varepsilon_0| \ll \lambda$  and  $0 < |\sigma_0| \ll 1$  such that system (3.47) can have  $k$  limit cycles. Note that system (3.47) has the form of (2.1) with  $n = 2$ . The proof is then completed.  $\square$

#### Acknowledgements

The authors would like to thank the anonymous referees for their valuable suggestions, which have greatly helped in improving the presentation of this paper.

#### Funding

This work was supported by the National Natural Science Foundation of China (Nos. 11931016 and Nos. 11771296).

#### Availability of data and materials

Not applicable.

#### Competing interests

The authors declare that they have no competing interests.

#### Authors' contributions

The two authors worked together in the derivation of the mathematical results. All authors read and approved the final manuscript.

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#### Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Received: 9 March 2020 Accepted: 8 July 2020 Published online: 17 July 2020

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