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Spectral properties and a Parseval's equality in the singular case for *q*-Dirac problem

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Abstract

This paper is devoted to studying a *q*-analog of the singular Dirac problem. First, we investigate some spectral properties of the problem. Then we prove the existence of a spectral function and establish a Parseval's equality, for the singular *q*-Dirac system in a Hilbert space. Although there were given some results for this type of problem, we think that Parseval's equality has not been studied yet.

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Keywords: q-Dirac problem; singularity; spectral function; Parseval's equality

1 Introduction

In 1910, Jackson introduced the q-derivative operator, D_q , different from the classical derivative, and its right-inverse, the q-integration [19, 20]. Then the q-calculus was based on these notations. This calculus has a lot of applications in different mathematical areas, such as calculus of variations, orthogonal polynomials, theory of relativity, quantum theory and statistical physics (see [1, 23, 29]). Furthermore, there are several physical models involving q-functions, q-derivatives, q-integrals and their related problems [9, 11, 12, 15, 28].

In the present paper, we study an analog of Dirac system when the differential operator is replaced by Jackson's q-difference operator D_q (definitions are given in the next section). Let us consider the q-problem which consists of the q-Dirac system

$$\begin{cases} -\frac{1}{q}D_q Y_2(x,\lambda) + p(x)Y_1(x,\lambda) = \lambda Y_1(x,\lambda), \\ -D_{q^{-1}}Y_1(x,\lambda) + r(x)Y_2(x,\lambda) = \lambda Y_2(x,\lambda), \end{cases} \quad 0 \le x \le a \le \infty,$$

$$(1.1)$$

and the boundary conditions

$$Y_1(0,\lambda) = Y_2(0,\lambda),$$
 (1.2)

$$Y_1(q^{-n-1},\lambda) = Y_2(q^{-n},\lambda), \quad n \in \mathbb{N},$$
(1.3)

where λ is the spectral parameter, $q \in (0, 1)$ is fixed, p(x) and r(x) are real-valued functions and continuous at zero, and $p(x), r(x) \in L^1_q(0, \infty)$.

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The limit-point and limit-circle classifications of the singular point, $x = \infty$ of the *q*-difference equation were defined in [8], and using Titchmarsh's technique, sufficient conditions that the singular point is in a limit-point case were given. In the case when q = 1, i.e. $D_q = \frac{d}{dx}$, the Dirac system (1.1) was studied in many works, and for more details we refer the reader to Refs. [10, 14, 16, 22, 25–27, 30]. In [2, 3], a *q*-analog of one dimensional Dirac system on a finite interval was investigated and the authors studied the existence and uniqueness of its solution, and some spectral properties. Also, the asymptotic formulas for the eigenvalues and the eigenfunctions were obtained in [18].

The paper is organized as follows. In Sect. 2, we introduce some q-notations and results that will be useful in the next sections. In Sect. 3, we study some spectral properties of the q-problem (1.1)–(1.3) by the theory of q-(basic) Sturm–Liouville problems [6]. Finally, in Sect. 4, we prove the existence of a spectral function for singular q-Dirac system (1.1), and a Parseval's equality is established for vector functions in a Hilbert space.

2 q-notations and results

In this section, we introduce some the required *q*-notations and *q*-results which will be used throughout the paper. Hereafter, $q \in (0, 1)$ is fixed (for some details, see [6]). We start with the *q*-shifted factorial for $\alpha \in \mathbb{R}$ and n = 1, 2, 3, ...:

$$(\alpha;q)_n := \prod_{k=0}^{n-1} (1-\alpha q^k).$$

A set $A \subseteq \mathbb{R}$ is called a *q*-geometric set if $qx \in A$ for all $x \in A$. The *q*-analogous of sine and cosine functions [4, 6, 13] are defined on \mathbb{C} by

$$\sin(x;q) := \sum_{m=0}^{\infty} \frac{(-1)^m q^{m(m+1)} (x(1-q))^{2m+1}}{(q;q)_{2m+1}},$$
$$\cos(x;q) := \sum_{m=0}^{\infty} \frac{(-1)^m q^{m^2} (x(1-q))^{2m}}{(q;q)_{2m}}.$$

Let f be a real- or complex-valued function defined on a q-geometric set A. The qdifference operator D_q , the Jackson q-derivative, is defined by

$$D_q f(x) := \frac{f(x) - f(qx)}{x - qx}, \quad x \in A \setminus \{0\}.$$

If $0 \in A$, the *q*-derivative at zero is defined by

$$D_q f(0) \coloneqq \lim_{m \to \infty} \frac{f(xq^m) - f(0)}{xq^m}, \quad x \in A,$$

if the limit exists and does not depend on *x*. Hence, for $x \in A$,

$$D_{q^{-1}}f(x) = (D_q f)(xq^{-1}).$$
(2.1)

In the *q*-derivative, as $q \rightarrow 1$, the *q*-derivative is reduced to the classical derivative.

The right-inverse to D_q , the Jackson q-integration [20], is given by

$$\int_0^x f(t) d_q t := x(1-q) \sum_{m=0}^\infty q^m f(xq^m), \quad x \in A,$$

provided that the series converges, and

$$D_q \int_0^x f(t) \, d_q t = f(x),$$

moreover, if $\lim_{m\to\infty} f(xq^m) = f(0)$ for all $x \in A$ (in this case, we say f is q-regular at zero), then

$$\int_0^x D_q f(t) \, d_q t = f(x) - f(0). \tag{2.2}$$

Hahn [17] defined the *q*-integration for a function *f* over $[0, \infty)$ by

$$\int_0^\infty f(t) d_q t = (1-q) \sum_{m=-\infty}^\infty q^m f(q^m).$$

Furthermore, the following non-symmetric Leibniz formula holds:

$$D_q(fg)(x) = g(x)D_qf(x) + f(qx)D_qg(x).$$

If f and g are q-regular at zero, we get

$$\int_0^a g(x) D_q f(x) \, d_q x = (fg)(a) - (fg)(0) - \int_0^a f(qx) D_q g(x) \, d_q x.$$

The *q*-Wronskian of f(x) and g(x) is defined to be

$$W_q(f,g)(x) := f(x)D_qg(x) - g(x)D_qf(x), \quad x \in A.$$

 $\{Y_1, Y_2\}$ forms a fundamental set of solutions for (1.1) if their *q*-Wronskian does not vanish at any point of *A*.

For more details of *q*-calculus, we also refer the reader to Refs. [5, 7, 13, 24].

3 Spectral properties of the *q*-Dirac problem

In this section, we investigate some spectral properties of the q-Dirac problem (1.1)–(1.3). Further, the integral equations corresponding to the solution of (1.1) are presented.

Theorem 3.1 The vector eigenfunctions $Y(x, \lambda_1)$, $Y(x, \lambda_2)$ corresponding to the different eigenvalues λ_1 , λ_2 are orthogonal.

Proof Since the vector eigenfunctions

$$Y(x,\lambda_1) = (Y_1(x,\lambda_1), Y_2(x,\lambda_1)), \qquad Y(x,\lambda_2) = (Y_1(x,\lambda_2), Y_2(x,\lambda_2))$$

satisfy the q-system (1.1), then

$$\frac{1}{q} D_q Y_2(x, \lambda_1) + p(x) Y_1(x, \lambda_1) = \lambda_1 Y_1(x, \lambda_1),$$
(3.1)

$$-D_{q^{-1}}Y_1(x,\lambda_1) + r(x)Y_2(x,\lambda_1) = \lambda_1 Y_2(x,\lambda_1),$$
(3.2)

$$\frac{1}{q}D_{q}Y_{2}(x,\lambda_{2}) + p(x)Y_{1}(x,\lambda_{2}) = \lambda_{2}Y_{1}(x,\lambda_{2}),$$
(3.3)

$$-D_{q^{-1}}Y_1(x,\lambda_2) + r(x)Y_2(x,\lambda_2) = \lambda_2 Y_2(x,\lambda_2).$$
(3.4)

Multiplying (3.1)–(3.4) by $Y_1(x, \lambda_2)$, $Y_2(x, \lambda_2)$, $-Y_1(x, \lambda_1)$ and $-Y_2(x, \lambda_1)$, respectively, and applying (2.1) we have

$$D_q (Y_2(x,\lambda_1)Y_1(xq^{-1},\lambda_2) - Y_1(xq^{-1},\lambda_1)Y_2(x,\lambda_2))$$

= $(\lambda_1 - \lambda_2) (Y_1(x,\lambda_1)Y_1(x,\lambda_2) + Y_2(x,\lambda_1)Y_2(x,\lambda_2)).$

Thus, for each $n \in \mathbb{N}$,

$$\int_{0}^{q^{-n}} D_q (Y_2(x,\lambda_1)Y_1(xq^{-1},\lambda_2) - Y_1(xq^{-1},\lambda_1)Y_2(x,\lambda_2)) d_q x$$

= $(\lambda_1 - \lambda_2) \int_{0}^{q^{-n}} Y(x,\lambda_1)Y^T(x,\lambda_2) d_q x,$

where T is the transposition sign. This together with (2.2) yields

$$(Y_2(x,\lambda_1)Y_1(xq^{-1},\lambda_2) - Y_1(xq^{-1},\lambda_1)Y_2(x,\lambda_2))\Big|_{x=0}^{q^{-n}} = (\lambda_1 - \lambda_2) \int_0^{q^{-n}} Y(x,\lambda_1)Y^T(x,\lambda_2) d_q x,$$

therefore, from (1.2)-(1.3) we obtain

$$(\lambda_1 - \lambda_2) \int_0^{q^{-n}} Y(x, \lambda_1) Y^T(x, \lambda_2) d_q x = 0, \quad \forall n \in \mathbb{N},$$
(3.5)

since $\lambda_1 \neq \lambda_2$, consequently, $Y(x, \lambda_1)$ and $Y(x, \lambda_2)$ are orthogonal.

Theorem 3.2 The eigenvalues of the q-Dirac problem (1.1)-(1.3) are real.

Proof Suppose, on the contrary that λ^0 is a non-real eigenvalue of (1.1)–(1.3), and $Y(x, \lambda^0)$ is the corresponding vector eigenfunction of λ^0 . Then $\overline{Y(x, \lambda^0)}$ is the corresponding vector eigenfunction of $\overline{\lambda^0}$. Hence, it follows from $\lambda^0 \neq \overline{\lambda^0}$ and (3.5) with $\lambda_1 = \lambda^0$, $\lambda_2 = \overline{\lambda^0}$ that

$$\int_{0}^{q^{-n}} \left(\left| Y_{1}(x,\lambda^{0}) \right|^{2} + \left| Y_{2}(x,\lambda^{0}) \right|^{2} \right) d_{q}x = 0,$$

i.e., $Y(x, \lambda^0) \equiv 0$. This contradiction proves the theorem.

For each $n \in \mathbb{N}$, the characteristic function for the problem (1.1)–(1.3) is defined by

$$\Delta_n(\lambda) := Y_1(q^{-n-1}, \lambda) - Y_2(q^{-n}, \lambda).$$
(3.6)

Let $\zeta(x, \lambda) = (\zeta_1(x, \lambda), \zeta_2(x, \lambda))$ be the unique solution [2] of the *q*-Dirac system (1.1) under the initial conditions

$$\zeta_1(0,\lambda) = 1 = \zeta_2(0,\lambda).$$
 (3.7)

Obviously, $\zeta(x, \lambda)$ satisfies (1.2). In the following lemma, we present the integral equations corresponding to the solution $\zeta(x, \lambda)$.

Lemma 3.3 For the solution $\zeta(x, \lambda)$, the following integral equations hold:

$$\begin{aligned} \zeta_1(x,\lambda) \\ &= \cos(\lambda\sqrt{q}x;q) - \frac{1}{\sqrt{q}}\sin(\lambda\sqrt{q}x;q) \\ &+ \sqrt{q}\int_0^x \left\{\cos(\lambda\sqrt{q}t;q)\sin(\lambda\sqrt{q}x;q) - \sin(\lambda\sqrt{q}t;q)\cos(\lambda\sqrt{q}x;q)\right\}r(t)\zeta_1(t,\lambda)\,d_qt \\ &- \int_0^x \left\{\cos(\lambda qt;q)\cos(\lambda\sqrt{q}x;q) + \sqrt{q}\sin(\lambda qt;q)\sin(\lambda\sqrt{q}x;q)\right\}p(qt)\zeta_2(qt,\lambda)\,d_qt, \\ \zeta_2(x,\lambda) \end{aligned}$$

$$= q \sin(\lambda x; q) + \cos(\lambda x; q)$$

- $q \int_0^x \{\cos(\lambda x; q) \cos(\lambda \sqrt{q}t; q) + \sqrt{q} \sin(\lambda x; q) \sin(\lambda \sqrt{q}t; q)\} r(t)\zeta_1(t, \lambda) d_q t$
+ $q \int_0^x \{\cos(\lambda x; q) \sin(\lambda qt; q) - \sin(\lambda x; q) \cos(\lambda qt; q)\} p(qt)\zeta_2(qt, \lambda) d_q t.$

Proof For p(x) = r(x) = 0, the *q*-system (1.1) has two solutions

$$\psi_1(x,\lambda) = \left(\cos(\lambda\sqrt{q}x;q), q\sin(\lambda x;q)\right),$$

$$\psi_2(x,\lambda) = \left(-\sqrt{q}\sin(\lambda\sqrt{q}x;q), q\cos(\lambda x;q)\right),$$

with the *q*-Wronskian

$$W_q(\psi_1,\psi_2)(x,\lambda) = q. \tag{3.8}$$

Therefore, in the case when p(x) = r(x) = 0,

$$\zeta_g(x,\lambda) = \begin{bmatrix} c_1 \cos(\lambda \sqrt{q}x;q) - c_2 \sqrt{q} \sin(\lambda \sqrt{q}x;q) \\ c_1 q \sin(\lambda x;q) + c_2 q \cos(\lambda x;q) \end{bmatrix}^T$$
(3.9)

is a fundamental set of (1.1). Moreover, a particular solution $\zeta_p(x, \lambda) = (\zeta_1(x, \lambda), \zeta_2(x, \lambda))$ of the *q*-system (1.1) may be written as

$$\begin{cases} \zeta_1(x,\lambda) = v_1(x)\cos(\lambda\sqrt{q}x;q) - v_2(x)\sqrt{q}\sin(\lambda\sqrt{q}x;q),\\ \zeta_2(x,\lambda) = v_1(x)q\sin(\lambda x;q) + v_2(x)q\cos(\lambda x;q), \end{cases}$$
(3.10)

by *q*-analog of the method of variation of parameters, where $v_1(x)$, $v_2(x)$ are *q*-regular at zero. Substituting (3.10) into (1.1), we obtain the following system:

$$\begin{cases} \cos(\lambda q^{-\frac{1}{2}}x;q)D_{q^{-1}}v_1(x) - \sqrt{q}\sin(\lambda q^{-\frac{1}{2}}x;q)D_{q^{-1}}v_2(x) = -qp(x)\zeta_2(x,\lambda), \\ q\sin(\lambda x;q)D_{q^{-1}}v_1(x) + q\cos(\lambda x;q)D_{q^{-1}}v_2(x) = -qr(xq^{-1})\zeta_1(x,\lambda), \end{cases}$$

and hence by Cramer's rule and applying (3.8) we have

$$\begin{cases} D_{q^{-1}}\nu_1(x) = -qp(x)\cos(\lambda x;q)\zeta_2(x,\lambda) - r(xq^{-1})\sqrt{q}\sin(\lambda q^{-\frac{1}{2}}x;q)\zeta_1(xq^{-1},\lambda), \\ D_{q^{-1}}\nu_2(x) = qp(x)\sin(\lambda x;q)\zeta_2(x,\lambda) - r(xq^{-1})\cos(\lambda q^{-\frac{1}{2}}x;q)\zeta_1(xq^{-1},\lambda). \end{cases}$$
(3.11)

Since $D_{q^{-1}}v_i(x) = (D_qv_i)(xq^{-1})$, it follows from replacing *x* by *xq* in (3.11) and integrating from 0 to *x* that

$$\begin{cases}
\nu_1(x) = c_1 - \sqrt{q} \int_0^x r(t) \sin(\lambda \sqrt{q}t;q) \zeta_1(t,\lambda) d_q t \\
-q \int_0^x p(qt) \cos(\lambda qt;q) \zeta_2(qt,\lambda) d_q t, \\
\nu_2(x) = c_2 - \int_0^x r(t) \cos(\lambda \sqrt{q}t;q) \zeta_1(t,\lambda) d_q t \\
+q \int_0^x p(qt) \sin(\lambda qt;q) \zeta_2(qt,\lambda) d_q t.
\end{cases}$$
(3.12)

Now, from (3.9) and (3.12), we can write the general solution of (1.1) as

$$\zeta_{1}(x,\lambda) = 2c_{1}\cos(\lambda\sqrt{q}x;q) - 2c_{2}\sqrt{q}\sin(\lambda\sqrt{q}x;q) + \sqrt{q} \int_{0}^{x} \{\cos(\lambda\sqrt{q}t;q)\sin(\lambda\sqrt{q}x;q) \\- \sin(\lambda\sqrt{q}t;q)\cos(\lambda\sqrt{q}x;q)\}r(t)\zeta_{1}(t,\lambda)d_{q}t - \int_{0}^{x} \{\cos(\lambda qt;q)\cos(\lambda\sqrt{q}x;q) \\+ \sqrt{q}\sin(\lambda qt;q)\sin(\lambda\sqrt{q}x;q)\}p(qt)\zeta_{2}(qt,\lambda)d_{q}t,$$
(3.13)
$$\zeta_{2}(x,\lambda) = 2c_{1}q\sin(\lambda x;q) + 2c_{2}q\cos(\lambda x;q)$$

$$-q \int_{0}^{x} \left\{ \cos(\lambda \sqrt{q}t;q) \cos(\lambda x;q) + \sqrt{q} \sin(\lambda \sqrt{q}t;q) \sin(\lambda x;q) \right\} r(t)\zeta_{1}(t,\lambda) d_{q}t$$
$$+q \int_{0}^{x} \left\{ \sin(\lambda qt;q) \cos(\lambda x;q) - \cos(\lambda qt;q) \sin(\lambda x;q) \right\} p(qt)\zeta_{2}(qt,\lambda) d_{q}t.$$
(3.14)

Using (3.7), (3.13) and (3.14) we obtain $c_1 = \frac{1}{2}$, $c_2 = \frac{1}{2q}$, and then the proof is complete.

In the following theorem, we prove another property of the eigenvalues of (1.1)-(1.3).

Theorem 3.4 The eigenvalues of the problem (1.1)-(1.3) are simple.

Proof The eigenvalues of (1.1)–(1.3) are the zeros of $\Delta_n(\lambda)$. From (3.6) we have

$$\frac{\partial \Delta_n(\lambda)}{\partial \lambda} = \frac{\partial Y_1(q^{-n-1}, \lambda)}{\partial \lambda} - \frac{\partial Y_2(q^{-n}, \lambda)}{\partial \lambda}, \quad n \in \mathbb{N}$$

Now, let $\lambda = \lambda^0$ be a double eigenvalue of (1.1)–(1.3) with the corresponding vector eigenfunction $Y(x, \lambda^0)$. Then $\Delta_n(\lambda^0) = 0$ and $\frac{\partial \Delta_n}{\partial \lambda}(\lambda^0) = 0$, i.e., for $n \in \mathbb{N}$, the system

$$\begin{cases} aY_1(q^{-n-1},\lambda^0) + bY_2(q^{-n},\lambda^0) = 0, \\ a\frac{\partial Y_1}{\partial\lambda}(q^{-n-1},\lambda^0) + b\frac{\partial Y_2}{\partial\lambda}(q^{-n},\lambda^0) = 0, \end{cases}$$

has the nontrivial solution (a, b) = (1, -1). Hence,

$$Y_1(q^{-n-1},\lambda^0)\frac{\partial Y_2}{\partial\lambda}(q^{-n},\lambda^0) - Y_2(q^{-n},\lambda^0)\frac{\partial Y_1}{\partial\lambda}(q^{-n-1},\lambda^0) = 0.$$
(3.15)

On the other hand, differentiating (1.1) with respect to λ , we get

$$\begin{cases} \frac{1}{q} D_q \left(\frac{\partial Y_2}{\partial \lambda}\right) + \left(p(x) - \lambda\right) \frac{\partial Y_1}{\partial \lambda} = Y_1, \\ -D_{q^{-1}} \left(\frac{\partial Y_1}{\partial \lambda}\right) + \left(r(x) - \lambda\right) \frac{\partial Y_2}{\partial \lambda} = Y_2. \end{cases}$$
(3.16)

Multiplying (1.1) and (3.16) by $\frac{\partial Y_1}{\partial \lambda}$, $\frac{\partial Y_2}{\partial \lambda}$, $-Y_1$ and $-Y_2$, respectively, and applying (2.1), we obtain

$$\frac{1}{q}D_q\left\{Y_1\left(xq^{-1},\lambda\right)\frac{\partial Y_2(x,\lambda)}{\partial\lambda}-Y_2(x,\lambda)\frac{\partial Y_1(xq^{-1},\lambda)}{\partial\lambda}\right\}=Y_1^2(x,\lambda)+\frac{1}{q^2}Y_2^2(x,\lambda).$$

Therefore, integrating with respect to *x* from 0 to q^{-n} , with applying (2.2), we have

$$\frac{1}{q} \left\{ Y_1(xq^{-1},\lambda) \frac{\partial Y_2(x,\lambda)}{\partial \lambda} - Y_2(x,\lambda) \frac{\partial Y_1(xq^{-1},\lambda)}{\partial \lambda} \right\} \Big|_{x=0}^{q^{-n}} \\
= \int_0^{q^{-n}} \left(Y_1^2(x,\lambda) + \frac{1}{q^2} Y_2^2(x,\lambda) \right) d_q x, \quad n \in \mathbb{N}.$$
(3.17)

According to Lemma 3.3, $\frac{\partial Y_1}{\partial \lambda}(0, \lambda^0) = \frac{\partial Y_2}{\partial \lambda}(0, \lambda^0) = 0$. Taking this and (3.15) into the left-side of (3.17), we obtain

$$\int_0^{q^{-n}} \left(Y_1^2(x,\lambda) + \frac{1}{q^2} Y_2^2(x,\lambda) \right) d_q x = 0, \quad n \in \mathbb{N}.$$

Consequently, $Y_1(x, \lambda^0) = Y_2(x, \lambda^0) \equiv 0$, i.e. $Y(x, \lambda^0) \equiv 0$. Thus, we arrive at the contradiction. The proof is complete.

4 Spectral function and Parseval's equality

Let $\lambda_{m,n}$, $m \ge 0$, $n \in \mathbb{N}$, be the eigenvalues of the *q*-Dirac problem (1.1)–(1.3) (i.e. the roots of $\Delta_n(\lambda)$) with the corresponding eigenfunctions

$$Y_{m,n}(x) = Y(x, \lambda_{m,n}) = (Y_1(x, \lambda_{m,n}), Y_2(x, \lambda_{m,n})).$$

If $f(x) = (f_1(x), f_2(x))$ is a vector function, $f_1, f_2 \in L^2_q(0, q^{-n})$, $n \in \mathbb{N}$, $Y_{m,n,i}(x) = Y_i(x, \lambda_{m,n})$, i = 1, 2, and

$$\alpha_{m,n,i}^2 = \int_0^{q^{-n}} Y_{m,n,i}^2(x) d_q x, \quad i = 1, 2,$$

then from [7] we have

$$\int_{0}^{q^{-n}} (f_1^2(x) + f_2^2(x)) d_q x = \sum_{m=-\infty}^{\infty} \sum_{i=1}^{2} \frac{1}{\alpha_{m,n,i}^2} \left(\int_{0}^{q^{-n}} f_i(x) Y_{m,n,i}(x) d_q x \right)^2.$$
(4.1)

Denote the non-decreasing step function ρ_n by

$$\rho_n(\lambda) = \begin{cases} -\sum_{\lambda < \lambda_{m,n} < 0} \sum_{i=1}^2 \frac{1}{\alpha_{m,n,i}^2}, & \lambda < 0, \\ \sum_{0 \le \lambda_{m,n} < \lambda} \sum_{i=1}^2 \frac{1}{\alpha_{m,n,i}^2}, & \lambda \ge 0. \end{cases}$$

Therefore, (4.1) can be written as

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$$\int_{0}^{q^{-n}} \left(f_1^2(x) + f_2^2(x) \right) d_q x = \int_{-\infty}^{\infty} \left(F_{1,n}^2(\lambda) + F_{2,n}^2(\lambda) \right) d\rho_n(\lambda), \tag{4.2}$$

where $F_{i,n}(\lambda) = \int_0^{q^{-n}} f_i(x) Y_i(x, \lambda) d_q x$, i = 1, 2.

Lemma 4.1 For any positive τ , the following inequality holds:

$$\sum_{\tau \le \lambda_{m,n} < \tau} \sum_{i=1}^{2} \frac{1}{\alpha_{m,n,i}^{2}} = \rho_{n}(\tau) - \rho_{n}(-\tau) < \frac{4}{\tau}.$$
(4.3)

Proof Since $\zeta_1(x, \lambda)$ and $\zeta_2(x, \lambda)$ are continuous at zero, it follows from (3.7) that there is a positive number τ and nearby zero such that

$$\frac{1}{\tau} \sum_{i=1}^{2} \left(\int_{0}^{\tau} \zeta_{i}(x,\lambda) \, d_{q}x \right)^{2} > \frac{1}{2}.$$
(4.4)

Denote the vector function $_{\tau}f(x) = (_{\tau}f_1(x), _{\tau}f_2(x))$ by

$$_{\tau}f_i(x) = \begin{cases} \frac{1}{\tau}, & 0 \le x \le \tau, \\ 0, & x > \tau. \end{cases}$$

Then, from (4.2) and (4.4), we obtain

$$\begin{split} \int_0^\tau \left({}_{\tau} f_1^2(x) + {}_{\tau} f_2^2(x) \right) d_q x &= \frac{2}{\tau} = \int_{-\infty}^\infty \sum_{i=1}^2 \left(\int_0^\tau \frac{1}{\tau} \zeta_i(x,\lambda) \, d_q x \right)^2 d\rho_n(\lambda) \\ &\geq \int_{-\tau}^\tau \sum_{i=1}^2 \left(\frac{1}{\tau} \int_0^\tau \zeta_i(x,\lambda) \, d_q x \right)^2 d\rho_n(\lambda) \\ &> \frac{1}{2} \left(\rho_n(\tau) - \rho_n(-\tau) \right), \end{split}$$

and we arrive at (4.3).

The following lemmas were proved in [21].

Lemma 4.2 Let $\{v_n\}_{n=1}^{\infty}$ be a uniformly bounded sequence of real non-decreasing function of λ on a finite interval [a, b]. Then there exist a subsequence $\{v_{n_k}\}_{k=1}^{\infty}$ and a non-decreasing function v such that, for $\lambda \in [a, b]$, $\lim_{k \to \infty} v_{n_k}(\lambda) = v(\lambda)$.

Lemma 4.3 Assume $\{v_n\}_{n=1}^{\infty}$ is a real uniformly bounded sequence of real non-decreasing function of λ on a finite interval [a,b], and suppose for $\lambda \in [a,b]$, $\lim_{n\to\infty} v_n(\lambda) = v(\lambda)$. If g is any continuous function of λ on [a,b], then $\lim_{n\to\infty} \int_a^b g(\lambda) dv_n(\lambda) = \int_a^b g(\lambda) dv(\lambda)$.

Now, let ρ be any non-decreasing function of λ on the interval $(-\infty, \infty)$. We define by $L^2_{\rho}(-\infty, \infty) \times L^2_{\rho}(-\infty, \infty)$ the Hilbert space of all vector functions $g = (g_1, g_2) : (-\infty, \infty) \times (-\infty, \infty) \rightarrow \mathbb{R}$ which g_1, g_2 are measurable with respect to the Lebesgue–Stieltjes measure defined by ρ , such that $\int_{-\infty}^{\infty} g_i(\lambda) d\rho(\lambda) < \infty$, i = 1, 2, with inner product

$$\langle g,h\rangle_{\rho} := \int_{-\infty}^{\infty} (g_1(\lambda)h_1(\lambda) + g_2(\lambda)h_2(\lambda)) d\rho(\lambda).$$

In the following theorem, we prove the main result of this section.

Theorem 4.4 For the q-Dirac problem (1.1)–(1.3), there exists a non-decreasing function $\rho(\lambda)$ on the interval $(-\infty, \infty)$ such that satisfies the following property:

If $f = (f_1, f_2)$ is a vector function, $f_i \in L^2_q(0, q^{-n})$, i = 1, 2, then there exists a function $F = (F_1, F_2) \in L^2_\rho(-\infty, \infty) \times L^2_\rho(-\infty, \infty)$ such that

$$\lim_{n\to\infty}\int_{-\infty}^{\infty}\left\{F_1(\lambda)+F_2(\lambda)-\int_0^{q^{-n}}\left(f_1(x)Y_1(x,\lambda)+f_2(x)Y_2(x,\lambda)\right)d_qx\right\}d\rho(\lambda)=0,$$

and the Parseval's equality holds:

$$\int_0^\infty \left(f_1^2(x)+f_2^2(x)\right)d_qx=\int_{-\infty}^\infty \left(F_1^2(\lambda)+F_2^2(\lambda)\right)d\rho(\lambda).$$

The function ρ is called *the spectral function* for the *q*-problem (1.1)–(1.3).

Proof Assume that the vector function $f_{\eta}(x) = (f_{\eta,1}(x), f_{\eta,2}(x))$ satisfies the following conditions:

- (1) $f_{\eta}(0) = (1, 1);$
- (2) $f_{\eta}(x)$ vanishes outside $[0, q^{-\eta}] \times [0, q^{-\eta}], q^{-\eta} < q^{-n};$
- (3) $f_{\eta,i}(x)$ and $D_q f_{\eta,i}(x)$, i = 1, 2, are *q*-regular at zero.

According to (4.2), we can write

$$\int_{0}^{q^{-\eta}} \left(f_{\eta,1}^2(x) + f_{\eta,1}^2(x) \right) d_q x = \int_{-\infty}^{\infty} \left(F_1^2(\lambda) + F_2^2(\lambda) \right) d\rho(\lambda), \tag{4.5}$$

where

$$F_i(\lambda) = \int_0^{q^{-\eta}} f_{\eta,i}(x) Y_i(x,\lambda) d_q x, \quad i=1,2.$$

Since $Y(x, \lambda) = (Y_1(x, \lambda), Y_2(x, \lambda))$ satisfies the *q*-system (1.1), we have

$$\begin{cases} Y_1(x,\lambda) = \frac{1}{\lambda} (\frac{1}{q} D_q Y_2(x,\lambda) + p(x) Y_1(x,\lambda)), \\ Y_2(x,\lambda) = \frac{1}{\lambda} (-D_{q^{-1}} Y_1(x,\lambda) + r(x) Y_2(x,\lambda)). \end{cases}$$

Denote

$$\begin{split} F_{n,1}(\lambda) &:= \frac{1}{\lambda} \int_0^{q^{-n}} f_{\eta,1}(x) \bigg(\frac{1}{q} D_q Y_2(x,\lambda) + p(x) Y_1(x,\lambda) \bigg) d_q x, \\ F_{n,2}(\lambda) &:= \frac{1}{\lambda} \int_0^{q^{-n}} f_{\eta,2}(x) \big(-D_{q^{-1}} Y_1(x,\lambda) + r(x) Y_2(x,\lambda) \big) d_q x. \end{split}$$

Since $f_{\eta}(x)$ vanishes in a neighborhood of (q^{-n}, q^{-n}) , and $f_{\eta}(0) = Y(0, \lambda) = (1, 1)$, using *q*-integration by parts we get

$$\begin{split} F_{n,1}(\lambda) &= \frac{1}{\lambda} \int_0^{q^{-n}} \left\{ \frac{1}{q} Y_2(x,\lambda) D_q f_{\eta,1}(x) + p(x) f_{\eta,1}(x) Y_1(x,\lambda) \right\} d_q x, \\ F_{n,2}(\lambda) &= \frac{1}{\lambda} \int_0^{q^{-n}} \left\{ -Y_1(x,\lambda) D_{q^{-1}} f_{\eta,2}(x) + r(x) f_{\eta,2}(x) Y_2(x,\lambda) \right\} d_q x. \end{split}$$

Applying (4.2), we have, for any $\tau > 0$,

$$\begin{split} &\int_{|\lambda|>\tau} F_{n,1}^2(\lambda) \, d\rho_n(\lambda) \\ &\leq \frac{1}{\tau^2} \int_{|\lambda|>\tau} \left\{ \int_0^{q^{-n}} \left\{ \frac{1}{q} Y_2(x,\lambda) D_q f_{\eta,1}(x) \right. \\ &\quad + p(x) f_{\eta,1}(x) Y_1(x,\lambda) \right\} \, d_q x \right\}^2 \, d\rho_n(\lambda) \\ &\leq \frac{1}{\tau^2} \int_{-\infty}^\infty \left\{ \int_0^{q^{-n}} \left\{ \frac{1}{q} Y_2(x,\lambda) D_q f_{\eta,1}(x) \right. \\ &\quad + p(x) f_{\eta,1}(x) Y_1(x,\lambda) \right\} \, d_q x \right\}^2 \, d\rho_n(\lambda) \\ &= \frac{1}{\tau^2} \left\{ \int_{-\infty}^\infty \left(\int_0^{q^{-n}} \frac{1}{q} Y_2(x,\lambda) D_q f_{\eta,1}(x) \, d_q x \right)^2 \, d\rho_n(\lambda) \right\} \end{split}$$

$$+\int_{-\infty}^{\infty}\left(\int_{0}^{q^{-n}}Y_{1}(x,\lambda)p(x)f_{\eta,1}(x)\,d_{q}x\right)^{2}d\rho_{n}(\lambda)+M_{1}\bigg\},$$

where

$$M_{1} = \frac{2}{q} \int_{-\infty}^{\infty} \left\{ \int_{0}^{q^{-n}} Y_{1}(x,\lambda) p(x) f_{\eta,1}(x) d_{q}x \right\} \left\{ \int_{0}^{q^{-n}} Y_{2}(x,\lambda) D_{q}f_{\eta,1}(x) d_{q}x \right\} d\rho_{n}(\lambda).$$

Hence, from (4.2) we obtain

$$\int_{|\lambda|>\tau} F_{n,1}^2(\lambda) \, d\rho_n(\lambda) \\ \leq \frac{1}{\tau^2} \bigg\{ \int_0^{q^{-n}} \left(p(x) f_{\eta,1}(x) \right)^2 d_q x + \int_0^{q^{-n}} \left(\frac{1}{q} D_q f_{\eta,1}(x) \right)^2 d_q x + M_1 \bigg\}.$$
(4.6)

Similarly, we have

$$\int_{|\lambda|>\tau} F_{n,2}^{2}(\lambda) d\rho_{n}(\lambda) \\
\leq \frac{1}{\tau^{2}} \left\{ \int_{0}^{q^{-n}} \left(D_{q^{-1}} f_{\eta,2}(x) \right)^{2} d_{q}x + \int_{0}^{q^{-n}} \left(r(x) f_{\eta,2}(x) \right)^{2} d_{q}x + M_{2} \right\},$$
(4.7)

where

$$M_{2} = -2 \int_{-\infty}^{\infty} \left\{ \int_{0}^{q^{-n}} Y_{1}(x,\lambda) D_{q^{-1}} f_{\eta,2}(x) d_{q}x \right\} \left\{ \int_{0}^{q^{-n}} Y_{2}(x,\lambda) r(x) f_{\eta,2}(x) d_{q}x \right\} d\rho_{n}(\lambda).$$

Therefore, it follows from (4.5)-(4.7) that

$$\begin{aligned} \left| \int_{0}^{q^{-\eta}} \left(f_{\eta,1}^{2}(x) + f_{\eta,2}^{2}(x) \right) d_{q}x - \int_{-\tau}^{\tau} \left(F_{n,1}^{2}(\lambda) + F_{n,2}^{2}(\lambda) \right) d\rho_{n}(\lambda) \\ &= \int_{|\lambda| > \tau} \left(F_{n,1}^{2}(\lambda) + F_{n,2}^{2}(\lambda) \right) d\rho_{n}(\lambda) \\ &< \frac{1}{\tau^{2}} \int_{0}^{q^{-\eta}} \left\{ \left(p(x) f_{\eta,1}(x) \right)^{2} + \left(\frac{1}{q} D_{q} f_{\eta,1}(x) \right)^{2} + \left(D_{q^{-1}} f_{\eta,2}(x) \right)^{2} \\ &+ \left(r(x) f_{\eta,2}(x) \right)^{2} + M_{1} + M_{2} \right\} d_{q}x. \end{aligned}$$

$$(4.8)$$

On the other hand, according to Lemma 4.1, the set $\{\rho_n(\lambda)\}$ is bounded. Thus, by Lemmas 4.2 and 4.3, there is a subsequence $\{n_k\}$ such that $\{\rho_{n_k}(\lambda)\}$ converges to a monotone function $\rho(\lambda)$. Passing to the limit with respect to $\{n_k\}$ in (4.8), we obtain

$$\begin{split} \left| \int_{0}^{q^{-\eta}} \left(f_{\eta,1}^{2}(x) + f_{\eta,2}^{2}(x) \right) d_{q}x - \int_{-\tau}^{\tau} \left(F_{\eta,1}^{2}(\lambda) + F_{\eta,2}^{2}(\lambda) \right) d\rho(\lambda) \right| \\ & < \frac{1}{\tau^{2}} \int_{0}^{q^{-\eta}} \left\{ \left(p(x) f_{\eta,1}(x) \right)^{2} + \left(\frac{1}{q} D_{q} f_{\eta,1}(x) \right)^{2} + \left(D_{q^{-1}} f_{\eta,2}(x) \right)^{2} \\ & + \left(r(x) f_{\eta,2}(x) \right)^{2} + M_{1} + M_{2} \right\} d_{q}x. \end{split}$$

So,

$$\int_{0}^{q^{-\eta}} \left(f_{\eta,1}^{2}(x) + f_{\eta,2}^{2}(x) \right) d_{q}x = \int_{-\infty}^{\infty} \left(F_{n,1}^{2}(\lambda) + F_{n,2}^{2}(\lambda) \right) d\rho(\lambda)$$

as $\tau \to \infty$. Now, let $f = (f_1, f_2)$ be an arbitrary vector function in $L^2_q(0, \infty) \times L^2_q(0, \infty)$. We know that there exists a sequence $\{f_\eta(x) = (f_{\eta,1}(x), f_{\eta,2}(x))\}$ satisfying the conditions (1)–(3) such that

$$\lim_{\eta\to\infty}\int_0^\infty \left(f_i(x)-f_{\eta,i}(x)\right)^2 d_q x=0, \quad i=1,2.$$

Then

$$\int_0^\infty \left(f_{\eta,1}^2(x)+f_{\eta,2}^2(x)\right)d_qx=\int_{-\infty}^\infty \left(F_{\eta,1}^2(\lambda)+F_{\eta,2}^2(\lambda)\right)d\rho(\lambda),$$

where $F_{\eta,i}(\lambda) = \int_0^\infty f_{\eta,i}(x) Y_i(x,\lambda) d_q x$. Since for i = 1, 2,

$$\int_0^\infty \left(f_{\eta_1,i}(x) - f_{\eta_2,i}(x)\right)^2 d_q x \to 0$$

as $\eta_1, \eta_2 \rightarrow \infty$, we get

$$\int_{-\infty}^{\infty} \left(F_{\eta_1,i}(\lambda) - F_{\eta_2,i}(\lambda) \right)^2 d\rho(\lambda) = \int_0^{\infty} \left(f_{\eta_1,i}(x) - f_{\eta_2,i}(x) \right)^2 d_q x \to 0, \quad i = 1, 2, 2, 3$$

as $\eta_1, \eta_2 \to \infty$. This is means that there is a limit vector function $F = (F_1, F_2)$ such that by the completeness of the space $L^2_\rho(-\infty, \infty) \times L^2_\rho(-\infty, \infty)$,

$$\int_0^\infty \left(f_1^2(x)+f_2^2(x)\right)d_qx=\int_{-\infty}^\infty \left(F_1^2(\lambda)+F_2^2(\lambda)\right)d\rho(\lambda).$$

Now, it remains to show that the function $\widetilde{F}_\eta(\lambda) \coloneqq (\widetilde{F}_{\eta,1},\widetilde{F}_{\eta,2})$ with

$$\widetilde{F}_{\eta,i}(\lambda) := \int_0^{q^{-\eta}} f_i(x) Y_i(x,\lambda) \, d_q x,$$

as $\eta \to \infty$, converges to $F = (F_1, F_2)$ in $L^2_{\rho}(-\infty, \infty) \times L^2_{\rho}(-\infty, \infty)$. For this purpose, assume that $s = (s_1, s_2)$ is another function in $L^2_q(0, \infty) \times L^2_q(0, \infty)$, and by a similar argument, $S(\lambda)$ is defined by *s*. Clearly,

$$\int_0^\infty (f_i(x) - s_i(x))^2 d_q x = \int_{-\infty}^\infty (F_i(\lambda) - S_i(\lambda))^2 d\rho(\lambda), \quad i = 1, 2.$$

For i = 1, 2, set

$$s_i(x) = egin{cases} f_i(x), & x \in [0, q^{-\eta}], \ 0, & x \in (q^{-\eta}, \infty). \end{cases}$$

Then

$$\int_{-\infty}^{\infty} \left(F_i(\lambda) - \widetilde{F}_{\eta,i}(\lambda) \right)^2 d\rho(\lambda) = \int_{q^{-\eta}}^{\infty} f_i^2(x) d_q x, \quad i = 1, 2,$$

as $\eta \to \infty$. Consequently, \widetilde{F}_{η} converges to F in $L^2_{\rho}(-\infty,\infty) \times L^2_{\rho}(-\infty,\infty)$ as $\eta \to \infty$. This completes the proof.

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