

RESEARCH

Open Access



Positive solutions to one-dimensional quasilinear impulsive indefinite boundary value problems

Peige Qin¹, Meiqiang Feng^{1*} and Ping Li¹

*Correspondence:

meiqiangfeng@sina.com

¹School of Applied Science, Beijing Information Science & Technology University, Beijing, People's Republic of China

Abstract

Consider the one-dimensional quasilinear impulsive boundary value problem involving the p -Laplace operator

$$\begin{cases} -(\phi_p(u'))' = \lambda\omega(t)f(u), & 0 < t < 1, \\ -\Delta u|_{t=t_k} = \mu I_k(u(t_k)), & k = 1, 2, \dots, n, \\ \Delta u'|_{t=t_k} = 0, & k = 1, 2, \dots, n, \\ u'(0) = 0, & u(1) = \int_0^1 g(t)u(t) dt, \end{cases}$$

where $\lambda, \mu > 0$ are two positive parameters, $\phi_p(s)$ is the p -Laplace operator, i.e., $\phi_p(s) = |s|^{p-2}s, p > 1, \omega(t)$ changes sign on $[0, 1]$. Several new results are obtained for the above quasilinear indefinite problem.

Keywords: Multiplicity of positive solutions; Indefinite weight function; p -Laplace operator; Quasilinear impulsive differential equation

1 Introduction

Impulsive differential equation is regarded as a critical mathematical tool to provide a natural description of observed evolution processes (see [1–4]). So the consideration of impulsive differential equations has gained prominence and many authors have begun to take a great interest in the subject of impulsive differential equations, for example, see [5–22] and the references cited therein.

Meanwhile, the p -Laplace operator equation is a typical quasilinear operator equation, which comes naturally from glaciology, nonlinear flow laws, and non-Newtonian mechanics (see [23, 24]). Recently, various existence, multiplicity, and uniqueness results of positive solutions for differential equations with one-dimensional p -Laplace operator have been considered [25–33]. Specially, Zhang and Ge [34] investigated the following second order one-dimensional p -Laplace operator equation

$$\begin{cases} -(\phi_p(u'(t)))' = f(t, u(t)), & t \neq t_k, t \in (0, 1), \\ \Delta u|_{t=t_k} = I_k(u(t_k)), & k = 1, 2, \dots, n, \\ u(0) = \sum_{i=1}^{m-2} a_i u(\xi_i), & u'(1) = 0, \end{cases} \quad (1.1)$$

where $\phi_p(s)$ is p -Laplace operator, i.e., $\phi_p(s) = |s|^{p-2}s, p > 1, (\phi_p)^{-1} = \phi_q, \frac{1}{p} + \frac{1}{q} = 1, t_k (k = 1, 2, \dots, n, \text{ where } n \text{ is a fixed positive integer})$ are fixed points with $0 < t_1 < t_2 < \dots < t_k < \dots < t_n < 1, \xi_i (i = 1, 2, \dots, m - 2) \in (0, 1)$ is given $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$ and $\xi_i \neq t_k, i = 1, 2, \dots, m - 2, k = 1, 2, \dots, n, \Delta u|_{t=t_k}$ denotes the jump of $u(t)$ at $t = t_k$, i.e.,

$$\Delta u|_{t=t_k} = u(t_k^+) - u(t_k^-),$$

where $u(t_k^+)$ and $u(t_k^-)$ represent the right-hand limit and left-hand limit of $u(t)$ at $t = t_k$, respectively. Applying the classical fixed-point index theorem for compact maps, the authors got several new multiplicity results of positive solutions.

On the other hand, we observe that many authors (see [35–49]) have paid more attention to a class of boundary value problems involving integral boundary conditions, which contains two-point, three-point, and general multi-point boundary value problems as exceptional cases, see [50–58] and the references cited therein.

However, in literature there are almost no papers on multiple positive solutions for second order impulsive nonlocal indefinite boundary value problems with one-dimensional p -Laplace operator and multiple parameters. More precisely, the study of $\lambda > 0, \mu > 0, p \neq 2, I_k \neq 0 (k = 1, 2, \dots, n)$ and ω changes sign is still open for the second order nonlocal boundary value problem

$$\begin{cases} -(\phi_p(u'))' = \lambda\omega(t)f(u), & 0 < t < 1, \\ -\Delta u|_{t=t_k} = \mu I_k(u(t_k)), & k = 1, 2, \dots, n, \\ \Delta u'|_{t=t_k} = 0, & k = 1, 2, \dots, n, \\ u'(0) = 0, \quad u(1) = \int_0^1 g(t)u(t) dt, \end{cases} \tag{1.2}$$

where $\lambda > 0$ and $\mu > 0$ are two parameters, $\omega(t)$ may change sign, $\phi_p(s)$ is a p -Laplace operator, i.e., $\phi_p(s) = |s|^{p-2}s, p > 1, (\phi_p)^{-1} = \phi_q, \frac{1}{p} + \frac{1}{q} = 1. t_k (k = 1, 2, \dots, n)$ (where n is a fixed positive integer) are fixed points with $0 = t_0 < t_1 < t_2 < \dots < t_k < \dots < t_n < t_{n+1} = 1, \Delta u|_{t=t_k}$ denotes the jump of $u(t)$ at $t = t_k$, i.e., $\Delta u|_{t=t_k} = u(t_k^+) - u(t_k^-)$, where $u(t_k^+)$ and $u(t_k^-)$ represent the right-hand limit and left-hand limit of $u(t)$ at $t = t_k$, respectively.

In addition, set $J = [0, 1], R_+ = [0, +\infty), R = (-\infty, +\infty)$, and let ω, f, I_k , and g satisfy the following conditions:

(H₁) $\omega : J \rightarrow R$ is continuous, and there exists a constant $\xi \in (0, 1)$ such that

$$\omega(t) \geq 0, \quad t \in [0, \xi], \quad \omega(t) \leq 0, \quad t \in [\xi, 1].$$

Moreover, $\omega(t)$ does not vanish identically on any subinterval of J .

(H₂) $f : R_+ \rightarrow R_+$ is continuous, and $f(u) > 0$ for all $u > 0$, there exists $0 < c \leq 1$ such that

$$f(x) \geq c\psi(x), \quad x \in R_+,$$

where $\psi(x) = \max\{f(y) : 0 \leq y \leq x\}$;

(H₃) $I_k \in C(R_+, R_+)$, and $I_k(u) > 0$ for all $u > 0$.

(H₄) $g \in L^1[0, 1]$ is nonnegative and $\eta \in [0, 1)$, where

$$\eta = \int_0^1 g(s) ds. \tag{1.3}$$

(H₅) There exist $0 < \theta_1 \leq +\infty, \theta_1 \neq p - 1, 0 < \theta_2 \leq +\infty, \theta_2 \neq 1$, and $k_1, k_2, k_3, k_4 > 0$ such that

$$k_1 u^{\theta_1} \leq f(u) \leq k_2 u^{\theta_1}, \quad k_3 u^{\theta_2} \leq I_k(u) \leq k_4 u^{\theta_2}.$$

(H₆) There exists a number $0 < \sigma < \xi$ such that

$$c^2 k_1 \sigma^{\theta_1} \int_{\sigma}^{\xi} \omega^+(t) dt \geq k_2 \xi^{\theta_1} \int_{\xi}^1 \omega^-(t) dt.$$

We define $\omega^+(t) = \max\{\omega(t), 0\}$, $\omega^-(t) = -\min\{\omega(t), 0\}$. Then $\omega(t) = \omega^+(t) - \omega^-(t)$.

It is well accepted that the fixed point theorem in a cone is crucial in showing the existence of positive solutions of various boundary value problems for second order differential equations.

Lemma 1.1 (Theorem 2.3.4 of [59]) *Let Ω_1 and Ω_2 be two bounded open sets in a real Banach space E such that $0 \in \Omega_1$ and $\bar{\Omega}_1 \subset \Omega_2$. Let the operator $T : P \cap (\bar{\Omega}_2 \setminus \Omega_1) \rightarrow P$ be completely continuous, where P is a cone in E . Suppose that one of the two conditions*

(i) $\|Tx\| \leq \|x\|, \forall x \in P \cap \partial\Omega_1$ and $\|Tx\| \geq \|x\|, \forall x \in P \cap \partial\Omega_2$,

or

(ii) $\|Tx\| \geq \|x\|, \forall x \in P \cap \partial\Omega_1$, and $\|Tx\| \leq \|x\|, \forall x \in P \cap \partial\Omega_2$,

is satisfied. Then T has at least one fixed point in $P \cap (\bar{\Omega}_2 \setminus \Omega_1)$.

This paper is organized in the following fashion. In Sect. 2, we present some lemmas to be used in the subsequent sections. Section 3 is devoted to proving the multiplicity of positive solutions for problem (1.2), and we give an example to illustrate the main results in the final section.

2 Preliminaries

Let $J' = J \setminus \{t_1, t_2, \dots, t_n\}$. The basic space used in this paper $PC[0, 1] = \{u | u : J \rightarrow R \text{ is continuous at } t \neq t_k, \text{ left continuous at } t = t_k, \text{ and } u(t_k^+) \text{ exists}, k = 1, 2, \dots, n\}$. Then $PC[0, 1]$ is a real Banach space with the norm $\|\cdot\|_{PC}$ defined by $\|u\|_{PC} = \sup_{t \in J} |u(t)|$. By a solution of (1.2), we mean that a function $u \in PC[0, 1] \cap C^2(J')$ which satisfies (1.2).

In these main results, we will make use of the following lemmas.

Lemma 2.1 *Assume that (H₁)–(H₄) hold. Then $u \in PC[0, 1] \cap C^2(J')$ is a solution of problem (1.2) if and only if $u \in PC[0, 1]$ is a solution of the following impulsive integral equation:*

$$\begin{aligned} u(t) = & \frac{1}{1-\eta} \left[\int_0^1 g(t) \int_t^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) d\tau \right) ds dt \right. \\ & \left. + \mu \int_0^1 g(t) \left(\sum_{t \leq t_k} I_k(u(t_k)) \right) dt \right] \\ & + \int_t^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) d\tau \right) ds + \mu \sum_{t \leq t_k} I_k(u(t_k)). \end{aligned} \tag{2.1}$$

Proof The proof is similar to that of Lemma 3.1 in [38]. □

To establish the existence of multiple positive solutions in $PC[0, 1] \cap C^2(J')$ of problem (1.2), we denote

$$PC^+[0, 1] = \left\{ u \in PC[0, 1] : \min_{t \in J} u(t) \geq 0 \right\},$$

and a cone K in $PC[0, 1]$ by

$$K = \left\{ u \in PC^+[0, 1] : u \text{ is concave on } [0, \xi], \text{ and } u \text{ is convex on } [\xi, 1] \right\}. \tag{2.2}$$

Let $R > r > 0$, define $K_r = \{u \in K : \|u\| < r\}$, $K_{R,r} = \{u \in K : r < \|u\| < R\}$. Note that $\partial K_r = \{u \in K : \|u\| = r\}$, $\bar{K}_{R,r} = \{u \in K : r \leq \|u\| \leq R\}$.

We define a map $T : K \rightarrow PC[0, 1]$ by

$$\begin{aligned} (Tu)(t) = & \frac{1}{1-\eta} \left[\int_0^1 g(t) \int_t^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) d\tau \right) ds dt \right. \\ & \left. + \mu \int_0^1 g(t) \left(\sum_{t \leq t_k} I_k(u(t_k)) \right) dt \right] \\ & + \int_t^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) d\tau \right) ds + \mu \sum_{t \leq t_k} I_k(u(t_k)), \end{aligned} \tag{2.3}$$

where η is defined in (1.3).

Lemma 2.2 *From (2.1), we know that $u \in PC[0, 1]$ is a solution of problem (1.2) if and only if u is a fixed point of the map T .*

Lemma 2.3 *Assume that (H_1) – (H_6) hold. Then we have $T(K) \subset K$, and $T : K \rightarrow K$ is completely continuous.*

Proof From (2.3), we know that

$$(Tu)'(t) = -\phi_q \left(\int_0^t \lambda \omega(s) f(u(s)) ds \right). \tag{2.4}$$

Define $q(t) : J \rightarrow J$ as follows:

$$q(t) = \min \left\{ \frac{t}{\xi}, \frac{1-t}{1-\xi} \right\},$$

and $\min_{\sigma \leq t \leq \xi} q(t) = \frac{\sigma}{\xi}$, $\max_{\xi \leq t \leq 1} q(t) = 1$.

Firstly, for any $u \in K$, we have

$$\int_0^1 \omega(s) f(u(s)) ds \geq \int_0^\sigma \omega^+(s) f(u(s)) ds. \tag{2.5}$$

In fact, by (2.2), we know that $u(t) \geq 0$. Since $u \in K$, $u(0) \geq 0$, and $u(1) \geq 0$, we have

$$\begin{aligned} \frac{u(t) - u(0)}{t - 0} &\geq \frac{u(\xi) - u(0)}{\xi - 0}, \quad t \in [0, \xi] \Rightarrow u(t) \geq q(t)u(\xi), \quad t \in [0, \xi], \\ \frac{u(t) - u(1)}{t - 1} &\geq \frac{u(\xi) - u(1)}{\xi - 1}, \quad t \in [\xi, 1] \Rightarrow u(t) \leq q(t)u(\xi), \quad t \in [\xi, 1]. \end{aligned}$$

As we all know, ψ is nondecreasing on J , so we have

$$\psi(u(t)) \geq \psi(q(t)u(\xi)), \quad t \in [0, \xi], \quad \psi(u(t)) \leq \psi(q(t)u(\xi)), \quad t \in [\xi, 1].$$

So, it follows from (H_5) and (H_6) that

$$\begin{aligned} & \int_0^1 \omega(s)f(u(s)) \, ds - \int_0^\sigma \omega^+(s)f(u(s)) \, ds \\ &= \int_\sigma^\xi \omega^+(s)f(u(s)) \, ds - \int_\xi^1 \omega^-(s)f(u(s)) \, ds \\ &\geq c \int_\sigma^\xi \omega^+(s)\psi(u(s)) \, ds - \int_\xi^1 \omega^-(s)\psi(u(s)) \, ds \\ &\geq c \int_\sigma^\xi \omega^+(s)\psi(q(s)u(\xi)) \, ds - \int_\xi^1 \omega^-(s)\psi(q(s)u(\xi)) \, ds \\ &\geq c \int_\sigma^\xi \omega^+(s)f(q(s)u(\xi)) \, ds - \frac{1}{c} \int_\xi^1 \omega^-(s)f(q(s)u(\xi)) \, ds \\ &\geq ck_1 u^\theta(\xi) \frac{\sigma^\theta}{\xi^\theta} \int_\sigma^\xi \omega^+(s) \, ds - \frac{1}{c} k_2 u^\theta(\xi) \int_\xi^1 \omega^-(s) \, ds \\ &\geq u^\theta(\xi) \left(ck_1 \frac{\sigma^\theta}{\xi^\theta} \int_\sigma^\xi \omega^+(s) \, ds - \frac{1}{c} k_2 \int_\xi^1 \omega^-(s) \, ds \right) \\ &\geq 0. \end{aligned}$$

Secondly, if $t \in [0, \xi]$, we have

$$\int_0^t \omega(s)f(u(s)) \, ds = \int_0^t \omega^+(s)f(u(s)) \, ds \geq 0.$$

Since $p, q > 1$, we get

$$\begin{aligned} (Tu)''(t) &= \left(-\phi_q \left(\int_0^t \lambda \omega(s)f(u(s)) \, ds \right) \right)' \\ &= \left(- \left(\int_0^t \lambda \omega^+(s)f(u(s)) \, ds \right)^{q-1} \right)' \\ &= -(q-1) \left(\int_0^t \lambda \omega^+(s)f(u(s)) \, ds \right)^{q-2} \lambda \omega^+(t)f(u(t)) \\ &\leq 0. \end{aligned}$$

If $t \in [\xi, 1]$, then we have

$$\begin{aligned} \int_0^t \omega(s)f(u(s)) \, ds &= \int_0^\xi \omega^+(s)f(u(s)) \, ds - \int_\xi^t \omega^-(s)f(u(s)) \, ds \\ &\geq \int_0^\xi \omega^+(s)f(u(s)) \, ds - \int_\xi^1 \omega^-(s)f(u(s)) \, ds \\ &= \int_0^1 \omega(s)f(u(s)) \, ds \end{aligned}$$

$$\begin{aligned} &\geq \int_0^\sigma \omega^+(s)f(u(s)) \, ds \\ &\geq 0. \end{aligned}$$

And then, for $t \in [\xi, 1]$, it follows from $p, q > 1$ that

$$\begin{aligned} (Tu)''(t) &= \left(-\phi_q \left(\int_0^t \lambda \omega(s)f(u(s)) \, ds \right) \right)' \\ &= \left(-\phi_q \left(\int_0^\xi \lambda \omega^+(s)f(u(s)) \, ds - \int_\xi^t \lambda \omega^-(s)f(u(s)) \, ds \right) \right)' \\ &= \left(- \left(\int_0^\xi \lambda \omega^+(s)f(u(s)) \, ds - \int_\xi^t \lambda \omega^-(s)f(u(s)) \, ds \right)^{q-1} \right)' \\ &= -(q-1) \left(\int_0^\xi \lambda \omega^+(s)f(u(s)) \, ds - \int_\xi^t \lambda \omega^-(s)f(u(s)) \, ds \right)^{q-2} (-\lambda \omega^-(t)f(u(t))) \\ &\geq 0. \end{aligned}$$

Moreover, by direct calculating, we get $(Tu)(t) \geq 0$ for $t \in J$, $(Tu)''(t) \leq 0$ for $t \in [0, \xi]$, and $(Tu)''(t) \geq 0$ for $t \in [\xi, 1]$. Thus, $T(K) \subset K$.

Then it finally follows from the Arzelà–Ascoli theorem that the operator T is completely continuous. □

From Lemma 2.3, since $(Tu)'(t) \leq 0$, then T is nonincreasing for $u \in K$. It is not difficult to see that

$$\begin{aligned} \|Tu\|_{PC} &= (Tu)(0) \\ &= \frac{1}{1-\eta} \left[\int_0^1 g(0) \int_0^1 \phi_q \left(\int_0^s \lambda \omega(\tau)f(u(\tau)) \, d\tau \right) \, ds \, dt \right. \\ &\quad \left. + \mu \int_0^1 g(0) \left(\sum_{t \leq t_k} I_k(u(t_k)) \right) \, dt \right] \\ &\quad + \int_0^1 \phi_q \left(\int_0^s \lambda \omega(\tau)f(u(\tau)) \, d\tau \right) \, ds + \mu \sum_{k=1}^n I_k(u(t_k)). \end{aligned} \tag{2.6}$$

Lemma 2.4 *If (H_1) – (H_4) hold, then for $u \in K$ we get*

$$\|Tu\|_{PC} \leq \frac{1}{1-\eta} \phi_q \left(\int_0^\xi \lambda \omega^+(\tau)f(u(\tau)) \, d\tau \right) + \mu \frac{1}{1-\eta} \sum_{k=1}^n I_k(u(t_k)), \tag{2.7}$$

$$\|Tu\|_{PC} \geq \frac{(1 - \int_\xi^1 g(t) \, dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^\sigma \lambda \omega^+(\tau)f(u(\tau)) \, d\tau \right) + \mu \sum_{k=1}^n I_k(u(t_k)). \tag{2.8}$$

Proof By (2.6), for $u \in K$, we have

$$\begin{aligned} \|Tu\|_{PC} &= \frac{1}{1-\eta} \left[\int_0^1 g(t) \int_t^1 \phi_q \left(\int_0^s \lambda \omega(\tau)f(u(\tau)) \, d\tau \right) \, ds \, dt \right. \\ &\quad \left. + \mu \int_0^1 g(t) \left(\sum_{t \leq t_k} I_k(u(t_k)) \right) \, dt \right] \end{aligned}$$

$$\begin{aligned}
 & + \int_0^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) \, d\tau \right) ds + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 \leq & \frac{1}{1-\eta} \left[\int_0^1 g(t) \int_0^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) \, d\tau \right) ds dt \right. \\
 & \left. + \mu \int_0^1 g(t) \left(\sum_{k=1}^n I_k(u(t_k)) \right) dt \right] \\
 & + \int_0^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) \, d\tau \right) ds + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 = & \frac{1}{1-\eta} \int_0^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) \, d\tau \right) ds + \mu \frac{1}{1-\eta} \sum_{k=1}^n I_k(u(t_k)) \\
 = & \frac{1}{1-\eta} \left[\int_0^\xi \phi_q \left(\int_0^s \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) ds + \int_\xi^1 \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right. \right. \\
 & \left. \left. - \int_\xi^s \lambda \omega^-(\tau) f(u(\tau)) \, d\tau \right) ds + \mu \frac{1}{1-\eta} \sum_{k=1}^n I_k(u(t_k)) \right] \\
 \leq & \frac{1}{1-\eta} \left[\int_0^\xi \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) ds \right. \\
 & \left. + \int_\xi^1 \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) ds \right] \\
 & + \mu \frac{1}{1-\eta} \sum_{k=1}^n I_k(u(t_k)) \\
 = & \frac{1}{1-\eta} \int_0^1 \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) ds + \mu \frac{1}{1-\eta} \sum_{k=1}^n I_k(u(t_k)) \\
 = & \frac{1}{1-\eta} \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) + \mu \frac{1}{1-\eta} \sum_{k=1}^n I_k(u(t_k)).
 \end{aligned}$$

Then (2.7) holds.

From (2.5) and (2.6), we have

$$\begin{aligned}
 \|Tu\|_{PC} = & \frac{1}{1-\eta} \left[\int_0^1 g(t) \int_t^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) \, d\tau \right) ds dt \right. \\
 & \left. + \mu \int_0^1 g(t) \left(\sum_{t \leq t_k} I_k(u(t_k)) \right) dt \right] \\
 & + \int_0^1 \phi_q \left(\int_0^s \lambda \omega(\tau) f(u(\tau)) \, d\tau \right) ds + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 = & \frac{1}{1-\eta} \left\{ \int_0^\xi g(t) \left[\int_t^\xi \phi_q \left(\int_0^s \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) ds \right. \right. \\
 & \left. \left. + \int_\xi^1 \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) \right] dt \right. \\
 & \left. + \int_\xi^1 g(t) \left[\int_t^1 \phi_q \left(\int_0^s \lambda \omega^-(\tau) f(u(\tau)) \, d\tau \right) ds \right. \right. \\
 & \left. \left. + \int_\xi^1 \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) \, d\tau \right) \right] dt \right\} + \mu \sum_{k=1}^n I_k(u(t_k)).
 \end{aligned}$$

$$\begin{aligned}
 & - \int_{\xi}^s \lambda \omega^{-}(\tau) f(u(\tau)) d\tau \Big] ds + \int_{\xi}^1 g(t) \int_t^1 \phi_q \left(\int_0^{\xi} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau \right. \\
 & \left. - \int_{\xi}^s \lambda \omega^{-}(\tau) f(u(\tau)) d\tau \right) ds dt \Big\} + \int_0^{\xi} \phi_q \left(\int_0^s \lambda \omega^{+}(\tau) f(u(\tau)) d\tau \right) ds \\
 & + \int_{\xi}^1 \phi_q \left(\int_0^{\xi} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau \right. \\
 & \left. - \int_{\xi}^s \lambda \omega^{-}(\tau) f(u(\tau)) d\tau \right) ds + \mu \frac{1}{1-\eta} \int_0^1 g(t) \sum_{t \leq t_k} I_k(u(t_k)) dt \\
 & + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 \geq & \frac{1}{1-\eta} \int_0^{\xi} g(t) \int_{\xi}^1 \phi_q \left(\int_0^{\xi} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau - \int_{\xi}^s \lambda \omega^{-}(\tau) f(u(\tau)) d\tau \right) ds dt \\
 & + \int_{\xi}^1 \phi_q \left(\int_0^{\xi} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau - \int_{\xi}^s \lambda \omega^{-}(\tau) f(u(\tau)) d\tau \right) ds \\
 & + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 = & \frac{1 - \int_{\xi}^1 g(t) dt}{1-\eta} \int_{\xi}^1 \phi_q \left(\int_0^{\xi} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau - \int_{\xi}^s \lambda \omega^{-}(\tau) f(u(\tau)) d\tau \right) ds \\
 & + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 \geq & \frac{1 - \int_{\xi}^1 g(t) dt}{1-\eta} \int_{\xi}^1 \phi_q \left(\int_0^{\xi} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau - \int_{\xi}^1 \lambda \omega^{-}(\tau) f(u(\tau)) d\tau \right) ds \\
 & + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 = & \frac{(1 - \int_{\xi}^1 g(t) dt)(1-\xi)}{1-\eta} \phi_q \left(\int_0^1 \lambda \omega(\tau) f(u(\tau)) d\tau \right) + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 \geq & \frac{(1 - \int_{\xi}^1 g(t) dt)(1-\xi)}{1-\eta} \phi_q \left(\int_0^{\sigma} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau \right) + \mu \sum_{k=1}^n I_k(u(t_k)) \\
 \geq & \frac{(1 - \int_{\xi}^1 g(t) dt)(1-\xi)}{1-\eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda \omega^{+}(\tau) f(u(\tau)) d\tau \right) + \mu \sum_{k=1}^n I_k(u(t_k)).
 \end{aligned}$$

Then (2.8) holds. □

3 Main results

Based on the lemmas mentioned above, we give the following theorems and their proofs.

Theorem 3.1 *Assume that (H₁)–(H₆) hold. If $\theta_1 > p - 1$ and $\theta_2 > 1$, there exist $\lambda_0 > 0$ and $\mu_0 > 0$ such that problem (1.2) admits two positive solutions for $\lambda \in [\lambda_0, +\infty)$, $\mu \in [\mu_0, +\infty)$.*

Proof Denote

$$A_1 = \frac{1}{\int_0^\xi \lambda \omega^+(\tau) d\tau} \phi_p\left(\frac{1-\eta}{2}\right), \quad A_2 = \frac{1-\eta}{2\mu n},$$

$$B_1 = \frac{1}{\int_{\frac{\sigma}{2}}^\sigma \lambda \omega^+(\tau) d\tau} \phi_p\left(\frac{1-\eta}{2\alpha(1-\xi)(1-\int_\xi^1 g(t) dt)}\right), \quad B_2 = \frac{1}{2n\mu\alpha}.$$

On the one hand, since $\theta_1 > p - 1$ and $\theta_2 > 1$, by (H_5) , we get

$$\lim_{u \rightarrow 0} \frac{f(u)}{\phi_p(u)} \leq \lim_{u \rightarrow 0} \frac{k_2 u^{\theta_1}}{u^{p-1}} = 0, \quad \lim_{u \rightarrow 0} \frac{I_k(u)}{u} \leq \lim_{u \rightarrow 0} \frac{k_4 u^{\theta_2}}{u} = 0.$$

Hence, there exists $r > 0$ such that

$$f(u) < A_1 \phi_p(u), \quad I_k(u) < A_2 u, \quad u \in [0, r].$$

Then from (2.7), for $u \in \partial K_r$, then $\|u\|_{PC} = r$ and $0 \leq u(t) \leq \|u\| = r$ for all $t \in J$. It is clear that $f(u(t)) < A_1 \phi_p(u(t))$ and $I_k(u(t)) < A_2 u(t)$ for all $t \in J$. Then from (2.7), for $u \in \partial K_r$, we get

$$\begin{aligned} \|Tu\|_{PC} &\leq \frac{1}{1-\eta} \phi_q\left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) d\tau\right) + \mu \frac{1}{1-\eta} \sum_{k=1}^n I_k(u(t_k)) \\ &< \frac{1}{1-\eta} \phi_q\left(\int_0^\xi \lambda \omega^+(\tau) A_1 \phi_p(u(\tau)) d\tau\right) + \mu \frac{1}{1-\eta} \sum_{k=1}^n A_2 u(t_k) \\ &\leq \frac{1}{1-\eta} \phi_q\left(\int_0^\xi \lambda \omega^+(\tau) A_1 \phi_p(\|u\|_{PC}) d\tau\right) + \mu \frac{1}{1-\eta} \sum_{k=1}^n A_2 \|u\|_{PC} \\ &= \frac{\|u\|_{PC}}{2} + \frac{\|u\|_{PC}}{2} \\ &= \|u\|_{PC}. \end{aligned}$$

Consequently,

$$\|Tu\|_{PC} < \|u\|_{PC}, \quad \forall u \in \partial K_r. \tag{3.1}$$

On the other hand, we denote $\delta(t) = \min\{\frac{t}{\xi}, \frac{\xi-t}{\xi}\}$, $t \in [0, \xi]$. If $u \in K$, then u is a nonnegative function on $[0, \xi]$. So we get

$$u(t) \geq \delta(t) \|u\|_{PC}, \quad t \in [0, \xi].$$

It follows that $u(t) \geq \alpha \|u\|_{PC}$, $t \in [\frac{\sigma}{2}, \sigma]$, where $\alpha = \min_{\frac{\sigma}{2} \leq t \leq \sigma} \delta(t)$.

Since $\theta_1 > p - 1$ and $\theta_2 > 1$, by (H_5) , we have

$$\lim_{u \rightarrow +\infty} \frac{f(u)}{\phi_p(u)} \geq \lim_{u \rightarrow +\infty} \frac{k_1 u^{\theta_1}}{u^{p-1}} = +\infty, \quad \lim_{u \rightarrow +\infty} \frac{I_k(u)}{u} \geq \lim_{u \rightarrow +\infty} \frac{k_3 u^{\theta_2}}{u} = +\infty.$$

Furthermore, there exists $0 < r < R'$ such that

$$f(u) \geq B_1\phi_p(u), \quad I_k(u) \geq B_2u, \quad u \in [R', +\infty),$$

Choose $R \geq \frac{R'}{\alpha}$. Then, for any $u \in \partial K_R$, we have $\min_{\frac{\sigma}{2} \leq t \leq \sigma} u(t) \geq \min_{\frac{\sigma}{2} \leq t \leq \sigma} \delta(t)\|u\|_{PC} = \alpha R \geq R'$, and $f(u(t)) \geq B_1u^{p-1}(t), I_k(u(t)) \geq B_2u(t), t \in [\frac{\sigma}{2}, \sigma]$.

Then by (2.8), for $u \in \partial K_R$, we have

$$\begin{aligned} \|Tu\|_{PC} &\geq \frac{(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda \omega^+(\tau) f(u(\tau)) d\tau \right) + \mu \sum_{k=1}^n I_k(u(t_k)) \\ &\geq \frac{(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda \omega^+(\tau) B_1\phi_p(u(\tau)) d\tau \right) + \mu \sum_{k=1}^n B_2u(t_k) \\ &\geq \frac{(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda \omega^+(\tau) B_1\phi_p(\alpha\|u\|_{PC}) d\tau \right) + \mu \sum_{k=1}^n B_2\alpha\|u\|_{PC} \\ &= \frac{\alpha(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \|u\|_{PC} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda \omega^+(\tau) B_1 d\tau \right) + \mu n B_2 \alpha \|u\|_{PC} \\ &\geq \frac{1}{2} \|u\|_{PC} + \frac{1}{2} \|u\|_{PC} \\ &= \|u\|_{PC}. \end{aligned}$$

Consequently,

$$\|Tu\|_{PC} \geq \|u\|_{PC}, \quad \forall u \in \partial K_R. \tag{3.2}$$

In addition, choose a number $r' \in (0, r)$. Noticing that $f(u) > 0$ for all $u > 0$ and $I_k(u) > 0$ for all $u > 0$, we can define

$$\begin{aligned} f_{r'} &= \min\{f(u) : \alpha r' \leq u \leq r'\}, \quad I_{kr'} = \min\{I_k : \alpha r' \leq u \leq r'\}, \\ I_{r'} &= \min\{I_{kr'} : k = 1, 2, \dots, n\}. \end{aligned}$$

Let $\lambda_0 = \frac{1}{\int_{\frac{\sigma}{2}}^{\sigma} \omega^+(\tau) f_{r'} d\tau} \phi_p \left(\frac{r'(1-\eta)}{2(1-\int_{\xi}^1 g(t) dt)(1-\xi)} \right), \mu_0 = \frac{r'}{2nI_{r'}}$. Thus we have

$$\begin{aligned} \frac{(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda_0 \omega^+(\tau) f_{r'} d\tau \right) &= \frac{1}{2} r', \\ \mu_0 n I_{r'} &= \frac{1}{2} r'. \end{aligned}$$

If $u \in \partial K_{r'}$, then $\|u\|_{PC} = r'$ and $\alpha r' = \min_{\frac{\sigma}{2} \leq t \leq \sigma} \delta(t)\|u\|_{PC} \leq u(t) \leq \|u\|_{PC} = r', t \in [\frac{\sigma}{2}, \sigma]$. It is clear that $f(u(t)) \geq f_{r'}$ and $I_k(u(t)) \geq I_{r'}, t \in [\frac{\sigma}{2}, \sigma]$.

Then from (2.8), for $u \in \partial K_{r'}$, we have

$$\begin{aligned} \|Tu\|_{PC} &\geq \frac{(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda \omega^+(\tau) f(u(\tau)) d\tau \right) + \mu \sum_{k=1}^n I_k(u(t_k)) \\ &\geq \frac{(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda \omega^+(\tau) f_{r'} d\tau \right) + \mu \sum_{k=1}^n I_{r'} \\ &\geq \frac{(1 - \int_{\xi}^1 g(t) dt)(1 - \xi)}{1 - \eta} \phi_q \left(\int_{\frac{\sigma}{2}}^{\sigma} \lambda_0 \omega^+(\tau) f_{r'} d\tau \right) + \mu_0 n I_{r'} \\ &= \frac{1}{2} r' + \frac{1}{2} r' \\ &= r' = \|u\|_{PC}. \end{aligned}$$

Consequently,

$$\|Tu\|_{PC} \geq \|u\|_{PC}, \quad \forall u \in \partial K_{r'}. \tag{3.3}$$

Therefore, applying Lemma 1.1 to (3.1), (3.2), and (3.3) yields that T has two fixed points $u_1 \in \overline{K}_R \setminus \overline{K}_r$ and $u_2 \in K_r \setminus K_{r'}$. Thus, if $\theta_1 > p - 1$ and $\theta_2 > 1$, there exist $\lambda_0 > 0$ and $\mu_0 > 0$ such that problem (1.2) admits two positive solutions for $\lambda \in [\lambda_0, +\infty)$ and $\mu \in [\mu_0, +\infty)$. The proof of Theorem 3.1 is completed. \square

Theorem 3.2 *Assume that (H_1) – (H_6) hold. If $0 < \theta_1 < p - 1$ and $0 < \theta_2 < 1$, there exist $\lambda^0 > 0$ and $\mu^0 > 0$ such that problem (1.2) admits two positive solutions for $\lambda \in (0, \lambda^0]$ and $\mu \in (0, \mu^0]$.*

Proof On the one hand, since $0 < \theta_1 < p - 1$ and $0 < \theta_2 < 1$, by (H_5) , we get

$$\lim_{u \rightarrow 0} \frac{f(u)}{\phi_p(u)} \geq \lim_{u \rightarrow 0} \frac{k_1 u^{\theta_1}}{u^{p-1}} = +\infty, \quad \lim_{u \rightarrow 0} \frac{I_k(u)}{u} \geq \lim_{u \rightarrow 0} \frac{k_3 u^{\theta_2}}{u} = +\infty.$$

Hence, there exists $r_1 > 0$ such that

$$f(u) > B_1 \phi_p(u), \quad I_k(u) > B_2 u, \quad u \in [0, r_1].$$

Then we have $\min\{f(u) : \alpha r_1 \leq u \leq r_1\} > B_1 \phi_p(u)$ and $\min\{I_k(u) : \alpha r_1 \leq u \leq r_1\} > B_2 u$.

If $u \in \partial K_{r_1}$, then $\|u\|_{PC} = r_1$ and $\alpha r_1 = \min_{\frac{\sigma}{2} \leq t \leq \sigma} \delta(t) \|u\|_{PC} \leq u(t) \leq \|u\|_{PC} = r_1, t \in [\frac{\sigma}{2}, \sigma]$. It is easy to see that $f(u(t)) > B_3 \phi_p(u(t)), I_k(u(t)) > B_4 u(t), t \in [\frac{\sigma}{2}, \sigma]$. Then from (2.8), for $u \in \partial K_{r_1}$, similar to (3.2), we have

$$\|Tu\|_{PC} > \|u\|_{PC}, \quad \forall u \in \partial K_{r_1}. \tag{3.4}$$

On the other hand, since $0 < \theta_1 < p - 1$ and $0 < \theta_2 < 1$, by (H_5) , we have

$$\lim_{u \rightarrow +\infty} \frac{f(u)}{\phi_p(u)} \leq \lim_{u \rightarrow +\infty} \frac{k_2 u^{\theta}}{u^{p-1}} = 0, \quad \lim_{u \rightarrow +\infty} \frac{I_k(u)}{u} \leq \lim_{u \rightarrow +\infty} \frac{k_4 u^{\theta}}{u} = 0.$$

Furthermore, there exists $0 < r_1 < R'_1 < +\infty$ such that

$$f(u) \leq \frac{A_1}{2}\phi_p(u), \quad I_k(u) \leq \frac{A_2}{2}u, \quad u \in [R'_1, +\infty).$$

Let $M_1 = \max\{f(u) : 0 \leq u \leq R'_1\}$ and $M_2 = \max\{I_k : 0 \leq u \leq R'_1, k = 1, 2, \dots, n\}$. It implies that

$$f(u) \leq \frac{A_1}{2}\phi_p(u) + M_1, \quad I_k(u) \leq \frac{A_2}{2}u + M_2, \quad u \in [0, +\infty).$$

Choose $R_1 \geq \{R'_1, \frac{2\phi_q(2 \int_0^\xi \lambda \omega^+(\tau)M_1 d\tau)}{1-\eta}, 4\mu nM_2\}$. If $u \in \partial K_{R_1}$, then $\|u\| = R_1$ and $0 \leq u(t) \leq R_1, t \in J$. It is easy to see that $f(u(t)) \leq \frac{A_1}{2}\phi_p(u(t)) + M_1, I_k(u(t)) \leq \frac{A_2}{2}u(t) + M_2, t \in J$. Then from (2.7), for $u \in \partial K_{R_1}$, we have

$$\begin{aligned} \|Tu\|_{PC} &\leq \frac{1}{1-\eta}\phi_q\left(\int_0^\xi \lambda \omega^+(\tau)f(u(\tau)) d\tau\right) + \mu \sum_{k=1}^n I_k(u(t_k)) \\ &\leq \frac{1}{1-\eta}\phi_q\left(\int_0^\xi \lambda \omega^+(\tau)\left(\frac{A_1}{2}\phi_p(u(\tau)) + M_1\right) d\tau\right) + \mu \sum_{k=1}^n \left(\frac{A_2}{2}u(t_k) + M_2\right) \\ &\leq \frac{1}{1-\eta}\phi_q\left(\int_0^\xi \lambda \omega^+(\tau)\frac{A_1}{2}\phi_p(\|u\|_{PC}) d\tau + \int_0^\xi \lambda \omega^+(\tau)M_1 d\tau\right) \\ &\quad + \mu \sum_{k=1}^n \frac{A_2}{2}\|u\|_{PC} + \mu nM_2 \\ &\leq \frac{1}{1-\eta}\phi_q\left(\frac{1}{2}\phi_p\left(\frac{\|u\|_{PC}(1-\eta)}{2}\right) + \frac{1}{2}\phi_p\left(\frac{R_1(1-\eta)}{2}\right)\right) + \frac{\|u\|_{PC}}{4} + \frac{R_1}{4} \\ &= \frac{1}{2}R_1 + \frac{1}{2}R_1 \\ &= R_1 = \|u\|_{PC}. \end{aligned}$$

Consequently,

$$\|Tu\|_{PC} \leq \|u\|_{PC}, \quad \forall u \in \partial K_{R_1}. \tag{3.5}$$

In addition, choosing a number $r'_1 \in (0, r_1)$, we can define

$$\begin{aligned} f^{r'_1} &= \max\{f(u) : 0 < u \leq r'_1\}, \quad I_k^{r'_1} = \max\{I_k(u) : 0 < u \leq r'_1\}, \\ I^{r'_1} &= \max\{I_k^{r'_1} : k = 1, 2, \dots, n\}. \end{aligned}$$

Let $\lambda^0 = \frac{1}{\int_0^\xi \omega^+(\tau)f^{r'_1} d\tau}\phi_p\left(\frac{r'_1(1-\eta)}{2}\right)$ and $\mu^0 = \frac{r'_1}{2nr'_1}$. It is clear that

$$\frac{1}{1-\eta}\phi_q\left(\int_0^\xi \lambda^0 \omega^+(\tau)f^{r'_1} d\tau\right) \leq \frac{1}{2}r'_1, \quad \mu^0 nI^{r'_1} \leq \frac{1}{2}r'_1.$$

If $u \in \partial K_{r'_1}$, then $\|u\|_{PC} = r'_1$ and $0 \leq u(t) \leq \|u\|_{PC} = r'_1, t \in J$. It is clear that $f(u(t)) \leq f^{r'_1}, I_k(u(t)) \leq I^{r'_1}, t \in J$. Then from (2.7), for $u \in \partial K_{r'_1}$, we have

$$\begin{aligned} \|Tu\|_{PC} &\leq \frac{1}{1-\eta} \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f(u(\tau)) d\tau \right) + \mu \sum_{k=1}^n I_k(u(t_k)) \\ &\leq \frac{1}{1-\eta} \phi_q \left(\int_0^\xi \lambda \omega^+(\tau) f^{r'_1} d\tau \right) + \mu \sum_{k=1}^n I^{r'_1} \\ &\leq \frac{1}{1-\eta} \phi_q \left(\int_0^\xi \lambda^0 \omega^+(\tau) f^{r'_1} d\tau \right) + \mu^0 n I^{r'_1} \\ &= \frac{1}{2} r'_1 + \frac{1}{2} r'_1 \\ &= r'_1 = \|u\|_{PC}. \end{aligned}$$

Consequently,

$$\|Tu\|_{PC} \leq \|u\|_{PC}, \quad \forall u \in \partial K_{r'_1}. \tag{3.6}$$

Therefore, applying Lemma 1.1 to (3.4), (3.5), and (3.6) yields that T has two fixed points $u'_1 \in \bar{K}_{R_1} \setminus \bar{K}_{r_1}$ and $u'_2 \in K_{r_1} \setminus K_{r'_1}$. Thus, if $0 < \theta_1 < p - 1$ and $0 < \theta_2 < 1$, there exist $\lambda^0 > 0$ and $\mu^0 > 0$ such that problem (1.2) admits two positive solutions for $\lambda \in (0, \lambda^0]$ and $\mu \in (0, \mu^0]$. The proof of Theorem 3.2 is finished. \square

Remark 3.1 If $I_k = 0$ ($k = 1, 2, \dots, n$), even for the case $g(t) \equiv 0$ on J , the results of the present paper are still novel.

Remark 3.2 Comparing with Li, Feng, and Qin [60], the main features of this paper are as follows:

- (i) $p > 1$ is considered, not only $p \equiv 2$.
- (ii) $I_k \neq 0$ ($k = 1, 2, \dots, n$) is considered.
- (iii) The basic space $PC[0, 1]$ is available, not $C[0, 1]$.

4 An example

We give an example to illustrate our main conclusions.

Example 4.1 Let $p = \frac{3}{2}, n = 1, t_1 = \frac{1}{2}$. Consider the following problem:

$$\begin{cases} -(\phi_p(u'))' = \lambda \omega(t)(u + \sin u), & 0 < t < 1, \\ -\Delta u|_{t=t_1} = \mu I_1(u(t_1)), \\ \Delta u'|_{t=t_1} = 0, \\ u'(0) = 0, \quad u(1) = \int_0^1 g(t)u(t) dt, \end{cases} \tag{4.1}$$

where

$$\omega(t) = \begin{cases} 12(\frac{2}{3} - t), & t \in [0, \frac{2}{3}], \\ \frac{2}{3} - t, & t \in [\frac{2}{3}, 1], \end{cases} \quad I_1(u) = u^2, \quad g(t) = t.$$

From the definition of $\omega(t)$ and $g(t)$, we know that $\xi = \frac{1}{2}$ and $\eta = \int_0^1 t dt = \frac{1}{2}$. From $p = \frac{3}{2}$, we can get that $q = 3$.

Since f is nondecreasing, then $c = 1$. For fixed $k_1 = 1, k_2 = 2, \theta_1 = 1, k_3 = k_4 = 1, \theta_2 = 2, \sigma = \frac{1}{4}$, we can prove that (H_5) holds.

In fact,

$$\begin{aligned} \frac{1}{2} \int_{\frac{1}{2}}^{\frac{2}{3}} 12 \left(\frac{2}{3} - \tau \right) d\tau &= 6 \int_{\frac{1}{2}}^{\frac{2}{3}} \left(\frac{2}{3} - \tau \right) d\tau \\ &= 6 \left(\frac{2}{3} \tau - \frac{\tau^2}{2} \right) \Big|_{\frac{1}{2}}^{\frac{2}{3}} d\tau \\ &= \frac{1}{12}, \end{aligned}$$

and

$$2 \times \frac{2}{3} \int_{\frac{2}{3}}^1 \left(\tau - \frac{2}{3} \right) d\tau = \frac{4}{3} \left(\frac{\tau^2}{2} - \frac{2}{3} \tau \right) \Big|_{\frac{2}{3}}^1 = \frac{2}{27}.$$

Obviously, $\frac{1}{12} > \frac{2}{27}$. Thus

$$\frac{1}{2} \int_{\frac{1}{2}}^{\frac{2}{3}} 12 \left(\frac{2}{3} - \tau \right) d\tau \geq \frac{4}{3} \int_{\frac{2}{3}}^1 \left(\tau - \frac{2}{3} \right) d\tau.$$

This shows that (H_6) holds.

Let $\lambda_0 = \frac{12}{7} \sqrt{\frac{3}{13}} \left(\frac{1}{8} + \sin \frac{1}{8} \right)^{-1}, \mu_0 = 16$. Then it follows from Theorem 3.1 that problem (4.1) admits two positive solutions for $\lambda \in \left[\frac{12}{7} \sqrt{\frac{3}{13}} \left(\frac{1}{8} + \sin \frac{1}{8} \right)^{-1}, +\infty \right), \mu \in [16, \infty)$.

Acknowledgements

The authors are grateful to anonymous referees for their constructive comments and suggestions which have greatly improved this paper.

Funding

This work is sponsored by the National Natural Science Foundation of China (11301178), the Beijing Natural Science Foundation (1163007), the Scientific Research Project of Construction for Scientific and Technological Innovation Service Capacity (KM201611232017), the key research and cultivation project of the improvement of scientific research level of BISTU (2018ZDPY18/521823903), and the teaching reform project of BISTU (2018JGYB32).

Availability of data and materials

Not applicable.

Ethics approval and consent to participate

Not applicable.

Competing interests

The authors declare that there is no conflict of interests regarding the publication of this manuscript. The authors declare that they have no competing interests.

Consent for publication

Not applicable.

Authors' contributions

All authors contributed equally and read and approved the final version of the manuscript.

Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

References

1. Liu, X., Willms, A.: Impulsive controllability of linear dynamical systems with applications to maneuvers of spacecraft. *Math. Probl. Eng.* **2**, 277–299 (1996)
2. Erbe, L.H., Freedman, H.I., Liu, X., Wu, J.: Comparison principles for impulsive parabolic equations with applications to models of single species growth. *J. Aust. Math. Soc. Ser. B* **32**, 382–400 (1991)
3. Pasquero, S.: Ideality criterion for unilateral constraints in time-dependent impulsive mechanics. *J. Math. Phys.* **46**, 112904 (2005)
4. Guo, Y.: Globally robust stability analysis for stochastic Cohen-Grossberg neural networks with impulse control and time-varying delays. *Ukr. Math. J.* **69**, 1049–1060 (2017)
5. Liu, Y., O'Regan, D.: Multiplicity results using bifurcation techniques for a class of boundary value problems of impulsive differential equations. *Commun. Nonlinear Sci. Numer. Simul.* **16**, 1769–1775 (2011)
6. Zhang, X., Feng, M.: Nontrivial convex solutions on a parameter of impulsive differential equation with Monge–Ampère operator. *Bound. Value Probl.* **2017**, 172 (2017)
7. Zhang, H., Liu, L., Wu, Y.: Positive solutions for n th-order nonlinear impulsive singular integro-differential equations on infinite intervals in Banach spaces. *Nonlinear Anal.* **70**, 772–787 (2009)
8. Pang, H., Zhu, Y., Cui, M.: The method of upper and lower solutions to impulsive differential equation with Sturm–Liouville integral boundary conditions. *Differ. Equ. Dyn. Syst.* (2018). <https://doi.org/10.1007/s12591-018-0428-4>
9. Feng, M., Pang, H.: A class of three-point boundary-value problems for second order impulsive integro-differential equations in Banach spaces. *Nonlinear Anal.* **70**, 64–82 (2009)
10. Wang, M., Feng, M.: Infinitely many singularities and denumerably many positive solutions for a second-order impulsive Neumann boundary value problem. *Bound. Value Probl.* **2017**, 50 (2017)
11. Tian, Y., Zhang, X.: Existence and continuity of positive solutions on a parameter for second-order impulsive differential equations. *Bound. Value Probl.* **2016**, 163 (2016)
12. Liu, J., Zhao, Z.: An application of variational methods to second-order impulsive differential equation with derivative dependence. *Electron. J. Differ. Equ.* **2014**, 62 (2014)
13. Hao, X., Liu, L.: Mild solution of semilinear impulsive integro-differential evolution equation in Banach spaces. *Math. Methods Appl. Sci.* **40**, 4832–4841 (2017)
14. Zhou, J., Li, Y.: Existence and multiplicity of solutions for some Dirichlet problems with impulsive effects. *Nonlinear Anal.* **71**, 2856–2865 (2009)
15. Jiao, L., Zhang, X.: Multi-parameter second-order impulsive indefinite boundary value problems. *Adv. Differ. Equ.* **2018**, 158 (2018)
16. Nieto, J., O'Regan, D.: Variational approach to impulsive differential equations. *Nonlinear Anal., Real World Appl.* **10**, 680–690 (2009)
17. Liu, J., Zhao, Z.: Multiple solutions for impulsive problems with non-autonomous perturbations. *Appl. Math. Lett.* **64**, 143–149 (2017)
18. Tian, Y., Ge, W.: Variational methods to Sturm–Liouville boundary value problem for impulsive differential equations. *Nonlinear Anal.* **72**, 277–287 (2010)
19. Wang, Y., Zhao, Z.: Existence and multiplicity of solutions for a second-order impulsive differential equation via variational methods. *Adv. Differ. Equ.* **2017**, 46 (2017)
20. Zhang, X., Tian, Y.: Sharp conditions for the existence of positive solutions for a second-order singular impulsive differential equation. *Appl. Anal.* (2017). <https://doi.org/10.1080/00036811.2017.1370542>
21. Zhang, X., Feng, M.: Transformation techniques and fixed point theories to establish the positive solutions of second order impulsive differential equations. *J. Comput. Appl. Math.* **271**, 117–129 (2014)
22. Li, P., Feng, M., Wang, M.: A class of singular n -dimensional impulsive Neumann systems. *Adv. Differ. Equ.* **2018**, 100 (2018)
23. Bobisud, L.E.: Steady state turbulent flow with reaction. *Rocky Mt. J. Math.* **21**, 993–1007 (1991)
24. Glowinski, R., Rappaz, J.: Approximation of a nonlinear elliptic problem arising in a non-Newtonian fluid flow model in glaciology. *Math. Model. Numer. Anal.* **37**, 175–186 (2003)
25. Zhao, Z.: Fixed points of τ - ϕ -convex operators and applications. *Appl. Math. Lett.* **23**, 561–566 (2010)
26. Sun, F., Liu, L., Wu, Y.: Infinitely many sign-changing solutions for a class of biharmonic equation with p -Laplacian and Neumann boundary condition. *Appl. Math. Lett.* **73**, 128–135 (2017)
27. Zhang, X., Feng, M., Ge, W.: Symmetric positive solutions for p -Laplacian fourth-order differential equations with integral boundary conditions. *J. Comput. Appl. Math.* **222**, 561–573 (2008)
28. Feng, M., Zhang, X., Ge, W.: Exact number of solutions for a class of two-point boundary value problems with one-dimensional p -Laplacian. *J. Math. Anal. Appl.* **338**, 784–792 (2008)
29. Zhang, X., Feng, M.: Existence of a positive solution for one-dimensional singular p -Laplacian problems and its parameter dependence. *J. Math. Anal. Appl.* **413**, 566–582 (2014)
30. Jiang, J., Liu, L., Wu, Y.: Positive solutions for p -Laplacian fourth-order differential system with integral boundary conditions. *Discrete Dyn. Nat. Soc.* **2012**, Article ID 293734 (2012)
31. Zhang, X., Liu, L., Wu, Y., Caccetta, L.: Entire large solutions for a class of Schrödinger systems with a nonlinear random operator. *J. Math. Anal. Appl.* **423**, 1650–1659 (2015)
32. Kong, D., Liu, L., Wu, Y.: Triple positive solutions of a boundary value problem for nonlinear singular second order differential equations of mixed type with p -Laplacian. *Comput. Math. Appl.* **58**, 1425–1432 (2009)
33. Xu, F., Liu, L., Wu, Y.: Multiple positive solutions of four-point nonlinear boundary value problems for higher-order p -Laplacian operator with all derivatives. *Nonlinear Anal.* **71**, 4309–4319 (2009)
34. Zhang, X., Ge, W.: Impulsive boundary value problems involving the one-dimensional p -Laplacian. *Nonlinear Anal.* **70**, 1692–1701 (2009)
35. Feng, M., Ji, D., Ge, W.: Positive solutions for a class of boundary value problem with integral boundary conditions in Banach spaces. *J. Comput. Appl. Math.* **222**, 351–363 (2008)
36. Zhang, X., Feng, M., Ge, W.: Existence result of second-order differential equations with integral boundary conditions at resonance. *J. Math. Anal. Appl.* **353**, 311–319 (2009)

37. Zhang, X., Ge, W.: Symmetric positive solutions of boundary value problems with integral boundary conditions. *Appl. Math. Comput.* **219**, 3553–3564 (2012)
38. Feng, M., Du, B., Ge, W.: Impulsive boundary value problems with integral boundary conditions and one-dimensional p -Laplacian. *Nonlinear Anal.* **70**, 3119–3126 (2009)
39. Ahmad, B., Alsaedi, A., Alghamdi, B.S.: Analytic approximation of solutions of the forced Duffing equation with integral boundary conditions. *Nonlinear Anal., Real World Appl.* **9**, 1727–1740 (2008)
40. Zhang, X., Yang, X., Ge, W.: Positive solutions of n th-order impulsive boundary value problems with integral boundary conditions in Banach spaces. *Nonlinear Anal.* **71**, 5930–5945 (2009)
41. Kong, L.: Second order singular boundary value problems with integral boundary conditions. *Nonlinear Anal.* **72**, 2628–2638 (2010)
42. Jiang, J., Liu, L., Wu, Y.: Positive solutions for second order impulsive differential equations with Stieltjes integral boundary conditions. *Adv. Differ. Equ.* **2012**, 124 (2012)
43. Karakostas, G.L., Tsamatos, P.C.: Multiple positive solutions of some Fredholm integral equations arisen from nonlocal boundary-value problems. *Electron. J. Differ. Equ.* **2002**, 30 (2002)
44. Liu, L., Sun, F., Zhang, X., Wu, Y.: Bifurcation analysis for a singular differential system with two parameters via to degree theory. *Nonlinear Anal.* **22**, 31–50 (2017)
45. Jiang, J., Liu, L., Wu, Y.: Second-order nonlinear singular Sturm–Liouville problems with integral boundary problems. *Appl. Math. Comput.* **215**, 1573–1582 (2009)
46. Hao, X., Liu, L., Wu, Y.: Positive solutions for second order impulsive differential equations with integral boundary conditions. *Commun. Nonlinear Sci. Numer. Simul.* **16**, 101–111 (2011)
47. Hao, X., Zuo, M., Liu, L.: Multiple positive solutions for a system of impulsive integral boundary value problems with sign-changing nonlinearities. *Appl. Math. Lett.* **82**, 24–31 (2018)
48. Mao, J., Zhao, Z.: The existence and uniqueness of positive solutions for integral boundary value problems. *Bull. Malays. Math. Sci. Soc.* **34**, 153–164 (2011)
49. Liu, L., Hao, X., Wu, Y.: Positive solutions for singular second order differential equations with integral boundary conditions. *Math. Comput. Model.* **57**, 836–847 (2013)
50. Feng, M., Ge, W.: Positive solutions for a class of m -point singular boundary value problems. *Math. Comput. Model.* **46**, 375–383 (2007)
51. Lin, X., Zhao, Z.: Iterative technique for a third-order differential equation with three-point nonlinear boundary value conditions. *Electron. J. Qual. Theory* **2016**, 12 (2016)
52. Hao, X., Xu, N., Liu, L.: Existence and uniqueness of positive solutions for fourth-order m -point nonlocal boundary value problems with two parameters. *Rocky Mt. J. Math.* **43**, 1161–1180 (2013)
53. Jiang, J., Liu, L., Wu, Y.: Symmetric positive solutions to singular system with multi-point coupled boundary conditions. *Appl. Math. Comput.* **220**, 536–548 (2013)
54. Liu, J., Zhao, Z.: Multiple positive solutions for second-order three-point boundary-value problems with sign changing nonlinearities. *Electron. J. Differ. Equ.* **2012**, 152 (2012)
55. Liu, B., Li, J., Liu, L.: Existence and uniqueness for an m -point boundary value problem at resonance on infinite intervals. *Comput. Math. Appl.* **64**, 1677–1690 (2012)
56. Liu, L., Liu, B., Wu, Y.: Nontrivial solutions for higher-order m -point boundary value problem with a sign-changing nonlinear term. *Appl. Math. Comput.* **217**, 3792–3800 (2010)
57. Hao, X., Liu, L., Wu, Y.: On positive solutions of m -point nonhomogeneous singular boundary value problem. *Nonlinear Anal.* **73**, 2532–2540 (2010)
58. Zhang, X., Liu, L.: A necessary and sufficient condition of positive solutions for nonlinear singular differential systems with four-point boundary conditions. *Appl. Math. Comput.* **215**, 3501–3508 (2010)
59. Guo, D., Lakshmikantham, V.: *Nonlinear Problems in Abstract Cones*. Academic Press, New York (1988)
60. Li, P., Feng, M., Qin, P.: A class of nonlocal indefinite differential systems. *Bound. Value Probl.* **2018**, 81 (2018)

Submit your manuscript to a SpringerOpen[®] journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► [springeropen.com](https://www.springeropen.com)
