

RESEARCH

Open Access



# The eigenvalue problem for a coupled system of singular $p$ -Laplacian differential equations involving fractional differential-integral conditions

Ying He\*

\*Correspondence:  
heying65332015@163.com  
School of Mathematics and  
Statistics, Northeast Petroleum  
University, Daqing, 163318,  
P.R. China

## Abstract

In this paper, we deal with a coupled system of singular  $p$ -Laplacian differential equations involving fractional differential-integral conditions. By employing Schauder's fixed point theorem and the upper and lower solution method, we establish an eigenvalue interval for the existence of positive solutions. As an application an example is presented to illustrate the main results.

**MSC:** 34B15

**Keywords:** upper and lower solutions;  $p$ -Laplacian operator; eigenvalue; fractional differential equation

## 1 Introduction

In this paper, we consider the following system of nonlinear fractional differential equations with different fractional derivatives:

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1}u_1))(t) = \lambda f_1(u_1(t), D^{\gamma_1}u_1(t), D^{\gamma_2}u_2(t)), & 0 < t < 1, \\ -D^{\beta_2}(\varphi_{p_2}(-D^{\alpha_2}u_2))(t) = f_2(t, u_1(t)), \\ D^{\alpha_i}u_i(0) = D^{\alpha_i}u_i(1) = 0, \\ D^{\gamma_i}u_i(0) = 0, \quad D^{\alpha_i-1}u_i(1) = \xi_i I^{\omega_i}(D^{\gamma_i}u_i(\eta_i)), \quad i = 1, 2, \end{cases} \quad (1.1)$$

where  $D^{\alpha_i}, D^{\beta_i}, D^{\gamma_i}$  ( $i = 1, 2$ ) are the standard Riemann-Liouville fractional derivatives,  $I^{\omega_i}$  is the Riemann-Liouville fractional integral,  $\varphi_{p_i}$  is the  $p$ -Laplacian operator defined by  $\varphi_{p_i}(s) = |s|^{p_i-2}s$ ,  $p_i > 2$  ( $i = 1, 2$ ), and the nonlinearity  $f_i(x, y, z)$  may be singular at  $x = 0$ ,  $y = 0$ ,  $z = 0$ .

Throughout this paper, we always suppose that:

- (s<sub>0</sub>)  $0 < \gamma_i \leq 1 < \alpha_i < \beta_i < 2$ ,  $\alpha_1 - \gamma_1 > 1$ ,  $\alpha_2 - \gamma_2 > 1$ ,  $\omega_i > 0$ ,  $\xi_i > 0$ ,  $\eta_i \in [0, 1]$  ( $i = 1, 2$ ).
- (s<sub>1</sub>)  $\Gamma(\alpha_i - \gamma_i + \omega_i) > \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1}$  ( $i = 1, 2$ ).
- (s<sub>2</sub>) Let  $q_i$  satisfies the relation  $\frac{1}{q_i} + \frac{1}{p_i} = 1$ , where  $p_i$  is given by (1.1), then  $1 < q_i < 2$ .

Fractional calculus provides an excellent tool for describing the hereditary properties of various materials and processes. Concerning the development of theory, method and application of fractional calculus, we refer the reader to the recent papers [1–8].

On the other hand, the study of coupled systems involving fractional differential equations is also important as such systems occur in various problems of applied nature. So considerable work has been done to study the existence result for them nowadays [9–12]. The authors got the existence solutions by the method of the fixed point theorem, the coincidence degree theorem, or Schauder's fixed point theorem.

The theory of upper and lower solutions is well known to be an effective method to deal with the existence of solutions for the boundary value problems of the fractional differential equations. In [13] the authors used the method of upper and lower solutions and investigated the existence of solutions for initial value problems. By the same method some people got the solutions of boundary value problems for fractional differential equations, such as [14, 15]. To the best of our knowledge, only few papers considered the existence of solutions by using the method of upper and lower solutions for boundary value problems with fractional coupled systems.

The aim of this paper is to deal with the eigenvalue problem for a coupled system of fractional differential equations involving differential-integral conditions. The novelty of this paper is that the nonlinear terms  $f_1, f_2$  in the system (1.1) involve different unknown functions  $u_1(t), u_2(t)$  and their Riemann-Liouville fractional derivatives with different orders, and  $f_i(x, y, z)$  may be singular at  $x = 0, y = 0, z = 0$ . We establish an eigenvalue interval for the existence of positive solutions by Schauder's fixed point theorem and the upper and lower solutions method.

## 2 Preliminaries and lemmas

**Lemma 2.1** ([16]) *Let  $h_i \in L^1(0, 1)$ , then the problem*

$$\begin{cases} -D^{\beta_i} v_i(t) = h_i(t), & 0 < t < 1, \\ v_i(0) = v_i(1) = 0, \end{cases}$$

*has the unique solution  $v_i(t) = \int_0^1 G(\beta_i, t, s) h_i(s) ds$  ( $i = 1, 2$ ), where*

$$G(\beta_i, t, s) = \begin{cases} \frac{1}{\Gamma(\beta_i)} [t(1-s)]^{\beta_i-1}, & t \leq s, \\ \frac{1}{\Gamma(\beta_i)} \{ [t(1-s)]^{\beta_i-1} - (t-s)^{\beta_i-1} \}, & s \leq t. \end{cases}$$

**Lemma 2.2** ([17]) *Let  $h_i \in L^1(0, 1)$ , then the fractional integral boundary value problem*

$$\begin{cases} -D^{\alpha_i-\gamma_i} v_i(t) = h_i(t), & 0 < t < 1, \\ v_i(0) = 0, & D^{\alpha_i-\gamma_i-1} v_i(1) = \xi_i I^{\omega_i} v_i(\eta_i), \quad i = 1, 2, \end{cases}$$

*has a unique solution  $v_i(t) = \int_0^1 H_i(t, s) h_i(s) ds$ , where*

$$H_i(t, s) = \begin{cases} \frac{[\Gamma(\alpha_i-\gamma_i+\omega_i)-\xi_i(\eta_i-s)^{\alpha_i-\gamma_i+\omega_i-1}][\Gamma(\alpha_i-\gamma_i+\omega_i)-\xi_i\eta_i^{\alpha_i-\gamma_i+\omega_i-1}](t-s)^{\alpha_i-\gamma_i-1}}{\Delta_i}, & s \leq t, s \leq \eta_i; \\ \frac{[\Gamma(\alpha_i-\gamma_i+\omega_i)-\xi_i(\eta_i-s)^{\alpha_i-\gamma_i+\omega_i-1}][\Gamma(\alpha_i-\gamma_i+\omega_i)-\xi_i\eta_i^{\alpha_i-\gamma_i+\omega_i-1}]}{\Delta_i}, & t \leq s \leq \eta_i; \\ \frac{\Gamma(\alpha_i-\gamma_i+\omega_i)[t^{\alpha_i-\gamma_i-1}-(t-s)^{\alpha_i-\gamma_i-1}]+\xi_i\eta_i^{\alpha_i-\gamma_i+\omega_i-1}(t-s)^{\alpha_i-\gamma_i-1}}{\Delta_i}, & \eta_i \leq s \leq t; \\ \frac{\Gamma(\alpha_i-\gamma_i+\omega_i)t^{\alpha_i-\gamma_i-1}}{\Delta_i}, & s \geq t, s \geq \eta_i, \end{cases}$$

*and  $\Delta_i = \Gamma(\alpha_i-\gamma_i)[\Gamma(\alpha_i-\gamma_i+\omega_i)-\xi_i\eta_i^{\alpha_i-\gamma_i+\omega_i-1}]$ .*

**Lemma 2.3** ([17, 18]) *The functions  $G(\beta_i, t, s)$  and  $H_i(t, s)$  have the following properties:*

(1)  $G(\beta_i, t, s) > 0$ ,  $H_i(t, s) > 0$ , for  $t, s \in (0, 1)$ .

(2)

$$\frac{t^{\beta_i-1}(1-t)s(1-s)^{\beta_i-1}}{\Gamma(\beta_i)} \leq G(\beta_i, t, s) \leq \frac{\beta_i-1}{\Gamma(\beta_i)} t^{\beta_i-1}(1-t), \quad \text{for } t, s \in [0, 1].$$

(3)

$$e_i t^{\alpha_i-\gamma_i-1} [1 - (1-s)^{\alpha_i-\gamma_i-1}] \leq H_i(t, s) \leq d_i t^{\alpha_i-\gamma_i-1}, \quad \text{for } t, s \in [0, 1],$$

$$\text{where } d_i = \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) + \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}], \quad e_i = \Gamma(\alpha_i - \gamma_i).$$

*Proof* From [18], we can see that  $G(\beta_i, t, s) > 0$  and (2) hold.

In the following, we will prove (3).

For  $s \leq t, s \leq \eta_i$ ,

$$\begin{aligned} H_i(t, s) &= \frac{1}{\Delta_i} \left\{ [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i (\eta_i - s)^{\alpha_i-\gamma_i+\omega_i-1}] t^{\alpha_i-\gamma_i-1} \right. \\ &\quad \left. - [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] (t-s)^{\alpha_i-\gamma_i-1} \right\} \\ &\geq \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] [t^{\alpha_i-\gamma_i-1} - (t-s)^{\alpha_i-\gamma_i-1}] \\ &\geq \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] [t^{\alpha_i-\gamma_i-1} - (t-ts)^{\alpha_i-\gamma_i-1}] \\ &= \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] t^{\alpha_i-\gamma_i-1} [1 - (1-s)^{\alpha_i-\gamma_i-1}] \\ &= \Gamma(\alpha_i - \gamma_i) t^{\alpha_i-\gamma_i-1} [1 - (1-s)^{\alpha_i-\gamma_i-1}] \\ &= e_i t^{\alpha_i-\gamma_i-1} [1 - (1-s)^{\alpha_i-\gamma_i-1}], \\ H_i(t, s) &= \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i (\eta_i - s)^{\alpha_i-\gamma_i+\omega_i-1}] t^{\alpha_i-\gamma_i-1} \\ &\quad - [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] (t-s)^{\alpha_i-\gamma_i-1} \\ &\leq \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) t^{\alpha_i-\gamma_i-1} + \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1} (t-s)^{\alpha_i-\gamma_i-1}] \\ &\leq \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) + \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] t^{\alpha_i-\gamma_i-1} \\ &= d_i t^{\alpha_i-\gamma_i-1}. \end{aligned}$$

For  $t \leq s \leq \eta_i$ ,

$$\begin{aligned} H_i(t, s) &= \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i (\eta_i - s)^{\alpha_i-\gamma_i+\omega_i-1}] t^{\alpha_i-\gamma_i-1} \\ &\geq \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] t^{\alpha_i-\gamma_i-1} \\ &\geq \frac{1}{\Delta_i} [\Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i-\gamma_i+\omega_i-1}] t^{\alpha_i-\gamma_i-1} [1 - (1-s)^{\alpha_i-\gamma_i-1}] \\ &= \Gamma(\alpha_i - \gamma_i) t^{\alpha_i-\gamma_i-1} [1 - (1-s)^{\alpha_i-\gamma_i-1}] \\ &= e_i t^{\alpha_i-\gamma_i-1} [1 - (1-s)^{\alpha_i-\gamma_i-1}], \end{aligned}$$

$$\begin{aligned}
 H_i(t, s) &= \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i (\eta_i - s)^{\alpha_i - \gamma_i + \omega_i - 1} \right] t^{\alpha_i - \gamma_i - 1} \\
 &\leq \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) t^{\alpha_i - \gamma_i - 1} + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} t^{\alpha_i - \gamma_i - 1} \right] \\
 &= \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} \right] t^{\alpha_i - \gamma_i - 1} \\
 &= d_i t^{\alpha_i - \gamma_i - 1}.
 \end{aligned}$$

For  $\eta_i \leq s \leq t$ ,

$$\begin{aligned}
 H_i(t, s) &= \frac{1}{\Delta_i} \left\{ \Gamma(\alpha_i - \gamma_i + \omega_i) \left[ t^{\alpha_i - \gamma_i - 1} - (t - s)^{\alpha_i - \gamma_i - 1} \right] + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} (t - s)^{\alpha_i - \gamma_i - 1} \right\} \\
 &\geq \frac{1}{\Delta_i} \left\{ \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} \right] t^{\alpha_i - \gamma_i - 1} \right. \\
 &\quad \left. - \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} \right] (t - s)^{\alpha_i - \gamma_i - 1} \right\} \\
 &= \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} \right] \left[ t^{\alpha_i - \gamma_i - 1} - (t - s)^{\alpha_i - \gamma_i - 1} \right] \\
 &\geq \Gamma(\alpha_i - \gamma_i) t^{\alpha_i - \gamma_i - 1} \left[ 1 - (1 - s)^{\alpha_i - \gamma_i - 1} \right] \\
 &= e_i t^{\alpha_i - \gamma_i - 1} \left[ 1 - (1 - s)^{\alpha_i - \gamma_i - 1} \right], \\
 H_i(t, s) &= \frac{1}{\Delta_i} \left\{ \Gamma(\alpha_i - \gamma_i + \omega_i) \left[ t^{\alpha_i - \gamma_i - 1} - (t - s)^{\alpha_i - \gamma_i - 1} \right] + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} (t - s)^{\alpha_i - \gamma_i - 1} \right\} \\
 &\leq \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) t^{\alpha_i - \gamma_i - 1} + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} (t - s)^{\alpha_i - \gamma_i - 1} \right] \\
 &\leq \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} \right] t^{\alpha_i - \gamma_i - 1} \\
 &= d_i t^{\alpha_i - \gamma_i - 1}.
 \end{aligned}$$

For  $s \geq t, s \geq \eta_i$ ,

$$\begin{aligned}
 H_i(t, s) &= \frac{1}{\Delta_i} \Gamma(\alpha_i - \gamma_i + \omega_i) t^{\alpha_i - \gamma_i - 1} \\
 &\geq \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) - \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} \right] t^{\alpha_i - \gamma_i - 1} \left[ 1 - (1 - s)^{\alpha_i - \gamma_i - 1} \right] \\
 &= e_i t^{\alpha_i - \gamma_i - 1} \left[ 1 - (1 - s)^{\alpha_i - \gamma_i - 1} \right], \\
 H_i(t, s) &= \frac{1}{\Delta_i} \Gamma(\alpha_i - \gamma_i + \omega_i) t^{\alpha_i - \gamma_i - 1} \\
 &\leq \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) t^{\alpha_i - \gamma_i - 1} + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} t^{\alpha_i - \gamma_i - 1} \right] \\
 &= \frac{1}{\Delta_i} \left[ \Gamma(\alpha_i - \gamma_i + \omega_i) + \xi_i \eta_i^{\alpha_i - \gamma_i + \omega_i - 1} \right] t^{\alpha_i - \gamma_i - 1} \\
 &= d_i t^{\alpha_i - \gamma_i - 1}.
 \end{aligned}$$

From the above, the proof of (3) is completed. Clearly  $H_i(t, s) > 0$  for  $(t, s) \in (0, 1)$ , since (3) holds.  $\square$

**Lemma 2.4** ([17]) *Let  $h_1 \in L^1(0,1)$ , if  $(s_0)-(s_2)$  hold, then the fractional boundary value problem*

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}v_1))(t) = h_1(t), \\ D^{\alpha_1-\gamma_1}v_1(0) = D^{\alpha_1-\gamma_1}v_1(1) = 0, \\ v_1(0) = 0, \quad D^{\alpha_1-\gamma_1-1}v_1(1) = \xi_1 I^{\omega_1}(v_1(\eta_1)), \end{cases} \quad (2.1)$$

*has the unique positive solution*

$$v_1(t) = \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) h_1(\tau) d\tau \right)^{q_1-1} ds. \quad (2.2)$$

Now let us consider the following modified problem of the BVP (1.1):

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}v_1))(t) = \lambda f_1(I^{\gamma_1}v_1(t), v_1(t), v_2(t)), \\ -D^{\beta_2}(\varphi_{p_2}(-D^{\alpha_2-\gamma_2}v_2))(t) = f_2(t, I^{\gamma_1}v_1(t)), \\ D^{\alpha_i-\gamma_i}v_i(0) = D^{\alpha_i-\gamma_i}v_i(1) = 0, \\ v_i(0) = 0, \quad D^{\alpha_i-\gamma_i-1}v_i(1) = \xi_i I^{\omega_i}(v_i(\eta_i)), \quad i = 1, 2. \end{cases} \quad (2.3)$$

**Lemma 2.5** *Let  $u_i(t) = I^{\gamma_i}v_i(t)$ ,  $v_i(t) \in C[0,1]$  ( $i = 1, 2$ ). Then (1.1) can be transformed into (2.3). Moreover, if  $(v_1(t), v_2(t)) \in C[0,1] \times C[0,1]$  is a positive solution of the problem (2.3), then  $(I^{\gamma_1}v_1(t), I^{\gamma_2}v_2(t))$  is a positive solution of the problem (1.1).*

*Proof* Let  $u_i(t) = I^{\gamma_i}v_i(t)$ ,  $v_i(t) \in C[0,1]$ , by the definition of the Riemannn-Liouville fractional derivatives and integrals, we obtain

$$D^{\alpha_i}u_i(t) = D^{\alpha_i-\gamma_i}v_i(t), \quad D^{\alpha_i+1}u_i(t) = D^{\alpha_i-\gamma_i+1}v_i(t), \quad D^{\alpha_i-1}u_i(t) = D^{\alpha_i-\gamma_i-1}v_i(t). \quad (2.4)$$

Thus by applying (2.4), the BVP (1.1) reduces to the modified boundary value problem (2.3).

Consequently, if  $(v_1(t), v_2(t)) \in C[0,1] \times C[0,1]$  is a positive solution of the problem (2.3), then  $(I^{\gamma_1}v_1(t), I^{\gamma_2}v_2(t))$  is a positive solution of the problem (1.1).

It is well know that  $(v_1, v_2) \in C[0,1] \times C[0,1]$  is a solution of system (2.3), if and only if  $(v_1, v_2) \in C[0,1] \times C[0,1]$  is a solution of the following nonlinear integral equation system:

$$\begin{cases} v_1(t) = \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1}v_1(\tau), v_1(\tau), v_2(\tau)) d\tau \right)^{q_1-1} ds, \\ v_2(t) = \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1}v_1(\tau)) d\tau \right)^{q_2-1} ds. \end{cases} \quad (2.5)$$

Now define an operator

$$(Av_1)(t) = \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1}v_1(\tau)) d\tau \right)^{q_2-1} ds.$$

Then the integral system (2.5) is equivalent to the following nonlinear integral-differential equation:

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}v_1))(t) = \lambda f_1(I^{\gamma_1}v_1(t), v_1(t), Av_1(t)), \\ D^{\alpha_1-\gamma_1}v_1(0) = D^{\alpha_1-\gamma_1}v_1(1) = 0, \\ v_1(0) = 0, \quad D^{\alpha_1-\gamma_1-1}v_1(1) = \xi_1 I^{\omega_1}(v_1(\eta_1)), \end{cases} \quad (2.6)$$

i.e. the operator equation

$$v_1(t) = \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} v_1(\tau), v_1(\tau), (Av_1)(t)) d\tau \right)^{q_1-1} ds. \quad \square$$

**Definition 2.1** A continuous function  $\Psi(t)$  is called a lower solution of the problem (2.6) if it satisfies

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Psi))(t) \leq \lambda f_1(I^{\gamma_1}\Psi(t), \Psi(t), A\Psi(t)), \\ D^{\alpha_1-\gamma_1}\Psi(0) \geq 0, \quad D^{\alpha_1-\gamma_1}\Psi(1) \geq 0, \\ \Psi(0) \geq 0, \quad D^{\alpha_1-\gamma_1-1}\Psi(1) \geq \xi_1 I^{\omega_1}(\Psi(\eta_1)), \end{cases}$$

where

$$(A\Psi)(t) = \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1}\Psi(\tau)) d\tau \right)^{q_2-1} ds.$$

**Definition 2.2** A continuous function  $\Phi(t)$  is called an upper solution of the problem (2.6) if it satisfies

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Phi))(t) \geq \lambda f_1(I^{\gamma_1}\Phi(t), \Phi(t), A\Phi(t)), \\ D^{\alpha_1-\gamma_1}\Phi(0) \leq 0, \quad D^{\alpha_1-\gamma_1}\Phi(1) \leq 0, \\ \Phi(0) \leq 0, \quad D^{\alpha_1-\gamma_1-1}\Phi(1) \leq \xi_1 I^{\omega_1}(\Phi(\eta_1)), \end{cases}$$

where

$$(A\Phi)(t) = \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1}\Phi(\tau)) d\tau \right)^{q_2-1} ds.$$

**Lemma 2.6** (Maximal principle) *If  $v_1 \in C([0, 1], R)$  satisfies*

$$v_1(0) = 0, \quad D^{\alpha_1-\gamma_1-1}v_1(1) = \xi_1 I^{\omega_1}(v_1(\eta_1))$$

*and  $-D^{\alpha_1-\gamma_1}v_1(t) \geq 0$  for any  $t \in [0, 1]$ , then  $v_1(t) \geq 0, t \in [0, 1]$*

*Proof* By Lemma 2.3, the conclusion is obvious, we omit the proof.  $\square$

### 3 Main results

To establish the existence of a solution to the boundary value problem (1.1), we need to make the following assumptions.

(H<sub>1</sub>)  $f_1(x, y, z) : (0, +\infty)^3 \rightarrow [0, +\infty]$  is continuous and non-increasing in  $x, y, z > 0$ , respectively, and for all  $r \in (0, 1)$ , there exists a constant  $\varepsilon > 0$ , such that, for any  $(x, y, z) \in (0, +\infty)^3$ , we have

$$f_1(rx, ry, rz) \leq r^{-\varepsilon} f_1(x, y, z).$$

(H<sub>2</sub>)  $f_2(t, x) : [0, 1] \times [0, +\infty) \rightarrow [0, +\infty]$  is continuous and non-decreasing in  $x > 0$ , and there exists a constant  $0 < \sigma < \frac{1}{q_2-1}$ , such that, for any  $r \in (0, 1)$ ,  $(t, x) \in [0, 1] \times [0, +\infty)$ ,

we have

$$f_2(t, rx) \geq r^\sigma f_2(t, x).$$

**Remark** For  $r \geq 1$ , and  $x, y, z > 0$ , we have

$$f_1(rx, ry, rz) \geq r^{-\varepsilon} f_1(x, y, z), \quad (3.1)$$

$$f_2(t, rx) \leq r^\sigma f_2(t, x). \quad (3.2)$$

**Theorem 3.1** Suppose  $(H_1)$  and  $(H_2)$  hold, and the following condition is satisfied:

$(H_3)$   $f_1(1, 1, 1) \neq 0$ , and

$$0 < \int_0^1 f_1\left(\frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} t^{\alpha_1 - 1}, t^{\alpha_1 - \gamma_1 - 1}, bt^{\alpha_2 - \gamma_2 - 1}\right) dt < +\infty,$$

where

$$\begin{aligned} b &= e_2 \int_0^1 [1 - (1-s)^{\alpha_2 - \gamma_2 - 1}] s^{(\beta_2 - 1)(q_2 - 1)} (1-s)^{q_2 - 1} ds \\ &\quad \times \left( \frac{1}{\Gamma(\beta_2)} \int_0^1 \tau (1-\tau)^{\beta_2 - 1} f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1 - 1}\right) d\tau \right)^{q_2 - 1}, \\ e_2 &= \Gamma(\alpha_2 - \gamma_2). \end{aligned}$$

Then there exists a constant  $\lambda^* > 0$  such that for any  $\lambda \in (\lambda^*, +\infty)$ , the BVP (1.1) has at least one positive solution  $(u_1(t), u_2(t))$ , and, moreover, there exist two constants  $0 < l < 1$  and  $L > 1$  such that

$$\begin{aligned} l \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} t^{\alpha_1 - 1} &\leq u_1(t) \leq L \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} t^{\alpha_1 - 1}, \\ b l^{\sigma(q_2 - 1)} \frac{\Gamma(\alpha_2 - \gamma_2)}{\Gamma(\alpha_2)} t^{\alpha_2 - 1} &\leq u_2(t) \leq L^{\sigma(q_2 - 1)} a \frac{\Gamma(\alpha_2 - \gamma_2)}{\Gamma(\alpha_2)} t^{\alpha_2 - 1}, \end{aligned}$$

where

$$\begin{aligned} a &= d_2 \left( \frac{\beta_2 - 1}{\Gamma(\beta_2)} \int_0^1 f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1 - 1}\right) d\tau \right)^{q_2 - 1}, \\ d_2 &= \frac{1}{\Delta_2} [\Gamma(\alpha_2 - \gamma_2 + \omega_2) + \xi_2 \eta_2^{\alpha_2 - \gamma_2 + \omega_2 - 1}], \\ \Delta_2 &= \Gamma(\alpha_2 - \gamma_2) [\Gamma(\alpha_2 - \gamma_2 + \omega_2) - \xi_2 \eta_2^{\alpha_2 - \gamma_2 + \omega_2 - 1}]. \end{aligned}$$

*Proof* Let  $E = C[0, 1]$ , and define a subset  $P$  of  $E$  as follows:  $P = \{v_1(t) \in E : \text{there exists a constant } 0 < l < 1 \text{ such that } lt^{\alpha_1 - \gamma_1 - 1} \leq v_1(t) \leq l^{-1} t^{\alpha_1 - \gamma_1 - 1}, t \in [0, 1]\}$ . Clearly,  $P$  is a non-empty set, since  $t^{\alpha_1 - \gamma_1 - 1} \in P$ . Also

$$I^{\gamma_1} t^{\alpha_1 - \gamma_1 - 1} = \frac{1}{\Gamma(\gamma_1)} \int_0^t (t-s)^{\gamma_1 - 1} s^{\alpha_1 - \gamma_1 - 1} ds = \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} t^{\alpha_1 - 1}.$$

Now define the operator  $T_\lambda$  in  $E$

$$(T_\lambda v_1)(t) = \lambda^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} v_1(\tau), v_1(\tau), Av_1(\tau)) d\tau \right)^{q_1-1} ds, \quad (3.3)$$

where

$$Av_1(t) = \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} v_1(\tau)) d\tau \right)^{q_2-1} ds.$$

We assert that  $T_\lambda$  is well defined and  $T_\lambda(P) \subset P$ . In fact, for any  $v_1(t) \in P$ , there exists a positive number  $0 < l_{v_1} < 1$  such that  $l_{v_1} t^{\alpha_1-\gamma_1-1} \leq v_1(t) \leq l_{v_1}^{-1} t^{\alpha_1-\gamma_1-1}$ ,  $t \in [0, 1]$ . It follows from Lemma 2.3 and  $(H_2)$  that

$$\begin{aligned} Av_1(t) &= \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} v_1(\tau)) d\tau \right)^{q_2-1} ds, \\ &\int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} v_1(\tau)) d\tau \\ &\leq \int_0^1 G(\beta_2, s, \tau) f_2\left(\tau, l_{v_1}^{-1} \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \\ &\leq l_{v_1}^{-\sigma} \frac{\beta_2 - 1}{\Gamma(\beta_2)} \int_0^1 s^{\beta_2-1} (1-s) f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \\ &\leq l_{v_1}^{-\sigma} \frac{\beta_2 - 1}{\Gamma(\beta_2)} \int_0^1 f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau, \end{aligned}$$

and

$$\begin{aligned} &\int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} v_1(\tau)) d\tau \\ &\geq \int_0^1 G(\beta_2, s, \tau) f_2\left(\tau, l_{v_1} \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \\ &\geq l_{v_1}^{\sigma} \int_0^1 G(\beta_2, s, \tau) f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \\ &\geq l_{v_1}^{\sigma} \frac{s^{\beta_2-1} (1-s)}{\Gamma(\beta_2)} \int_0^1 \tau (1-\tau)^{\beta_2-1} f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau. \end{aligned}$$

Then,

$$\begin{aligned} Av_1(t) &\leq \int_0^1 H_2(t, s) \left( l_{v_1}^{-\sigma} \frac{\beta_2 - 1}{\Gamma(\beta_2)} \int_0^1 f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \right)^{q_2-1} ds \\ &\leq d_2 t^{\alpha_2-\gamma_2-1} l_{v_1}^{-\sigma(q_2-1)} \left( \frac{\beta_2 - 1}{\Gamma(\beta_2)} \int_0^1 f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \right)^{q_2-1} \\ &= a l_{v_1}^{-\sigma(q_2-1)} t^{\alpha_2-\gamma_2-1}, \end{aligned} \quad (3.4)$$

where

$$a = d_2 \left( \frac{\beta_2 - 1}{\Gamma(\beta_2)} \int_0^1 f_2\left(\tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \right)^{q_2-1}$$



and

$$\begin{aligned}
 Av_1(t) &\geq \int_0^1 H_2(t,s) \left( l_{v_1}^\sigma \frac{s^{\beta_2-1}(1-s)}{\Gamma(\beta_2)} \int_0^1 \tau(1-\tau)^{\beta_2-1} f_2 \left( \tau, \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} t^{\alpha_1-1} \right) d\tau \right)^{q_2-1} ds \\
 &\geq e_2 t^{\alpha_2-\gamma_2-1} l_{v_1}^{\sigma(q_2-1)} \int_0^1 s^{(\beta_2-1)(q_2-1)} (1-s)^{q_2-1} [1 - (1-s)^{\alpha_2-\gamma_2-1}] ds \\
 &\quad \times \left( \int_0^1 \frac{1}{\Gamma(\beta_2)} \tau(1-\tau)^{\beta_2-1} f_2 \left( \tau, \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1} \right) d\tau \right)^{q_2-1} \\
 &= b l_{v_1}^{\sigma(q_2-1)} t^{\alpha_2-\gamma_2-1}, \tag{3.5}
 \end{aligned}$$

where

$$\begin{aligned}
 b &= e_2 \int_0^1 [1 - (1-s)^{\alpha_2-\gamma_2-1}] s^{(\beta_2-1)(q_2-1)} (1-s)^{q_2-1} ds \\
 &\quad \times \left( \frac{1}{\Gamma(\beta_2)} \int_0^1 \tau(1-\tau)^{\beta_2-1} f_2 \left( \tau, \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1} \right) d\tau \right)^{q_2-1}.
 \end{aligned}$$

Since  $0 < \sigma < \frac{1}{q_2-1}$ , and by Lemma 2.3 and  $(H_1)$ ,  $(H_3)$ , we also have

$$\begin{aligned}
 (T_\lambda v_1)(t) &= \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(l^{\gamma_1} v_1(\tau), v_1(\tau), Av_1(\tau)) d\tau \right)^{q_1-1} ds \\
 &\leq \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) \right. \\
 &\quad \times f_1 \left( l_{v_1} \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, l_{v_1} \tau^{\alpha_1-\gamma_1-1}, b l_{v_1}^{\sigma(q_2-1)} \tau^{\alpha_2-\gamma_2-1} \right) d\tau \Big)^{q_1-1} ds \\
 &\leq \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) \right. \\
 &\quad \times f_1 \left( l_{v_1} \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, l_{v_1} \tau^{\alpha_1-\gamma_1-1}, b l_{v_1} \tau^{\alpha_2-\gamma_2-1} \right) d\tau \Big)^{q_1-1} ds \\
 &\leq \lambda^{q_1-1} l_{v_1}^{-\varepsilon(q_1-1)} \int_0^1 H_1(t,s) \left( \int_0^1 \frac{\beta_1-1}{\Gamma(\beta_1)} s^{\beta_1-1} (1-s) \right. \\
 &\quad \times f_1 \left( \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, b \tau^{\alpha_2-\gamma_2-1} \right) d\tau \Big)^{q_1-1} ds \\
 &\leq \lambda^{q_1-1} l_{v_1}^{-\varepsilon(q_1-1)} d_1 t^{\alpha_1-\gamma_1-1} \left( \int_0^1 s^{(\beta_1-1)(q_1-1)} (1-s)^{q_1-1} ds \right) \\
 &\quad \times \left( \frac{\beta_1-1}{\Gamma(\beta_1)} \int_0^1 f_1 \left( \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, b \tau^{\alpha_2-\gamma_2-1} \right) d\tau \right)^{q_1-1} \\
 &\leq \lambda^{q_1-1} l_{v_1}^{-\varepsilon(q_1-1)} \\
 &\quad \times d_1 \left( \frac{\beta_1-1}{\Gamma(\beta_1)} \int_0^1 f_1 \left( \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, b \tau^{\alpha_2-\gamma_2-1} \right) d\tau \right)^{q_1-1} t^{\alpha_1-\gamma_1-1} \\
 &< +\infty. \tag{3.6}
 \end{aligned}$$

On the other hand, as  $0 < \sigma < \frac{1}{q_2-1}$ , from Lemma 2.3 and (3.1), we have

$$\begin{aligned}
 (T_\lambda v_1)(t) &= \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} v_1(\tau), v_1(\tau), A v_1(\tau)) d\tau \right)^{q_1-1} ds \\
 &\geq \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) \right. \\
 &\quad \times f_1 \left( l_{v_1}^{-1} \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, l_{v_1}^{-1} \tau^{\alpha_1-\gamma_1-1}, a l_{v_1}^{-\sigma(q_2-1)} \tau^{\alpha_2-\gamma_2-1} \right) d\tau \Big)^{q_1-1} ds \\
 &\geq \lambda^{q_1-1} \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) \right. \\
 &\quad \times f_1 \left( l_{v_1}^{-1} \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, l_{v_1}^{-1} \tau^{\alpha_1-\gamma_1-1}, a l_{v_1}^{-1} \tau^{\alpha_2-\gamma_2-1} \right) d\tau \Big)^{q_1-1} ds \\
 &\geq \lambda^{q_1-1} l_{v_1}^{\varepsilon(q_1-1)} \int_0^1 H_1(t,s) \left( \frac{s^{\beta_1-1}(1-s)}{\Gamma(\beta_1)} \int_0^1 \tau(1-\tau)^{\beta_1-1} \right. \\
 &\quad \times f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, a \tau^{\alpha_2-\gamma_2-1} \right) d\tau \Big)^{q_1-1} ds \\
 &\geq \lambda^{q_1-1} l_{v_1}^{\varepsilon(q_1-1)} e_1 t^{\alpha_1-\gamma_1-1} \int_0^1 [1 - (1-s)^{\alpha_1-\gamma_1-1}] s^{(\beta_1-1)(q_1-1)} (1-s)^{q_1-1} ds \\
 &\quad \times \left( \frac{1}{\Gamma(\beta_1)} \int_0^1 \tau(1-\tau)^{\beta_1-1} f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, a \tau^{\alpha_2-\gamma_2-1} \right) d\tau \right)^{q_1-1} \\
 &= k \lambda^{q_1-1} l_{v_1}^{\varepsilon(q_1-1)} t^{\alpha_1-\gamma_1-1} \left( \frac{1}{\Gamma(\beta_1)} \int_0^1 \tau(1-\tau)^{\beta_1-1} \right. \\
 &\quad \times f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, a \tau^{\alpha_2-\gamma_2-1} \right) d\tau \Big)^{q_1-1}, \tag{3.7}
 \end{aligned}$$

where

$$k = \int_0^1 [1 - (1-s)^{\alpha_1-\gamma_1-1}] s^{(\beta_1-1)(q_1-1)} (1-s)^{q_1-1} ds.$$

Choose

$$\begin{aligned}
 \tilde{l}_{v_1} &= \min \left\{ \frac{1}{2}, \left\{ \lambda^{q_1-1} l_{v_1}^{-\varepsilon(q_1-1)} d_1 \left( \frac{\beta_1-1}{\Gamma(\beta_1)} \int_0^1 f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \right. \right. \right. \\
 &\quad \left. \left. \left. \tau^{\alpha_1-\gamma_1-1}, b \tau^{\alpha_2-\gamma_2-1} \right) d\tau \right)^{q_1-1} \right\}^{-1}, \right. \\
 &\quad \left. k \lambda^{q_1-1} l_{v_1}^{\varepsilon(q_1-1)} \left( \frac{1}{\Gamma(\beta_1)} \int_0^1 \tau(1-\tau)^{\beta_1-1} f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \right. \right. \right. \\
 &\quad \left. \left. \left. \tau^{\alpha_1-\gamma_1-1}, a \tau^{\alpha_2-\gamma_2-1} \right) d\tau \right)^{q_1-1} \right\}. \tag{3.8}
 \end{aligned}$$

Then it follows from (3.4)-(3.8) that

$$\tilde{l}_{v_1} t^{\alpha_1-\gamma_1-1} \leq T_\lambda v_1(t) \leq \tilde{l}_{v_1}^{-1} t^{\alpha_1-\gamma_1-1}.$$

This implies that  $T_\lambda$  is well defined and  $T_\lambda(P) \subset P$ . Furthermore, comparing (3.3) and (2.2), the right hand side of (3.3) is exactly the same as the right hand of (2.2), if  $h_1(t)$  in (2.1) is taken as  $\lambda f_1(I^{\gamma_1} v_1(t), v_1(t), Av_1(t))$ . Hence as the left hand side of (2.2), i.e.  $v_1(t)$  satisfies equation (2.1) according to Lemma 2.4, the left hand side of (3.3), i.e.  $T_\lambda v_1(t)$  must also satisfy equation (2.1) with  $h_1(t)$  replace by  $\lambda f_1(I^{\gamma_1} v_1(t), v_1(t), Av_1(t))$ , namely

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}(T_\lambda v_1)))(t) = \lambda f_1(I^{\gamma_1} v_1(t), v_1(t), Av_1(t)), \\ D^{\alpha_1-\gamma_1}(T_\lambda v_1)(0) = D^{\alpha_1-\gamma_1}(T_\lambda v_1)(1) = 0, \\ (T_\lambda v_1)(0) = 0, \quad D^{\alpha_1-\gamma_1-1}(T_\lambda v_1)(1) = \xi_1 I^{\omega_1}(T_\lambda v_1)(\eta_1), \end{cases} \quad (3.9)$$

where

$$(Av_1)(t) = \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} v_1(\tau)) d\tau \right)^{q_2-1} ds.$$

Next, we shall find the upper and lower solutions of (1.1). First of all, let

$$e(t) = \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) f_1\left(\frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, A \tau^{\alpha_1-\gamma_1-1}\right) d\tau \right)^{q_2-1} ds,$$

where

$$At^{\alpha_1-\gamma_1-1} = \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2\left(\tau, \frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \right)^{q_2-1} ds.$$

Similar to (3.4) and (3.5), the following inequalities are also valid:

$$At^{\alpha_1-\gamma_1-1} \geq bt^{\alpha_2-\gamma_2-1}$$

and

$$At^{\alpha_1-\gamma_1-1} \leq at^{\alpha_2-\gamma_2-1}.$$

By Lemma 2.3, (H<sub>1</sub>), and (3.7), we also have

$$\begin{aligned} e(t) &\geq \int_0^1 H_1(t,s) \left( \int_0^1 G(\beta_1, s, \tau) f_1\left(\frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, a \tau^{\alpha_2-\gamma_2-1}\right) d\tau \right)^{q_2-1} ds \\ &\geq kt^{\alpha_1-\gamma_1-1} \left( \frac{1}{\Gamma(\beta_1)} \int_0^1 \tau(1-\tau)^{\beta_1-1} f_1\left(\frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \right. \right. \\ &\quad \left. \left. \tau^{\alpha_1-\gamma_1-1}, a \tau^{\alpha_2-\gamma_2-1}\right) d\tau \right)^{q_1-1}, \end{aligned}$$

and consequently there exists a constant  $\lambda_1 \geq 1$  such that

$$\lambda_1^{q_1-1} e(t) \geq t^{\alpha_1-\gamma_1-1}, \quad \forall t \in [0, 1]. \quad (3.10)$$

On the other hand by  $(H_1)$  and  $(H_2)$ , we know that  $A$  is increasing and  $T_\lambda$  is decreasing, and thus for  $\lambda > \lambda_1$ , from (3.6) we have

$$\begin{aligned} & \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} \lambda^{q_1-1} e(\tau), \lambda^{q_1-1} e(\tau), A \lambda^{q_1-1} e(\tau)) d\tau \right)^{q_1-1} ds \\ & \leq \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} \lambda_1^{q_1-1} e(\tau), \lambda_1^{q_1-1} e(\tau), A \lambda_1^{q_1-1} e(\tau)) d\tau \right)^{q_1-1} ds \\ & \leq \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} \tau^{\alpha_1-\gamma_1-1}, \tau^{\alpha_1-\gamma_1-1}, A \tau^{\alpha_1-\gamma_1-1}) d\tau \right)^{q_1-1} ds \\ & \leq \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, b \tau^{\alpha_2-\gamma_2-1} \right) d\tau \right)^{q_1-1} ds \\ & \leq d_1 \left( \frac{\beta_1 - 1}{\Gamma(\beta_1)} \int_0^1 f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}, \tau^{\alpha_1-\gamma_1-1}, b \tau^{\alpha_2-\gamma_2-1} \right) d\tau \right)^{q_1-1} ds \\ & < +\infty. \end{aligned} \quad (3.11)$$

Applying (3.2) and  $0 < \sigma < \frac{1}{q_2-1}$ , for any  $t \in [0, 1]$ , we have

$$\begin{aligned} A(\lambda^*)^{q_1-1} e(t) &= \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, (\lambda^*)^{q_1-1} I^{\gamma_1} e(\tau)) d\tau \right)^{q_2-1} ds \\ &\leq (\lambda^*)^{\sigma(q_1-1)(q_2-1)} \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} e(\tau)) d\tau \right)^{q_2-1} ds \\ &\leq (\lambda^*)^{(q_1-1)} \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} e(\tau)) d\tau \right)^{q_2-1} ds \\ &= (\lambda^*)^{(q_1-1)} A e(t). \end{aligned} \quad (3.12)$$

Let

$$C_1 = \max_{0 \leq t \leq 1} e(t), \quad C_2 = \max_{0 \leq t \leq 1} A e(t), \quad C = \max\{2, C_1, C_2\},$$

then we have

$$I^{\gamma_1} e(t) \leq \frac{C_1}{\Gamma(\gamma_1)} \leq C_1 \leq C, \quad A e(t) \leq C_2 \leq C, \quad e(t) \leq C_1 \leq C. \quad (3.13)$$

Now, take

$$\lambda^* > \left\{ \lambda_1, \left[ \frac{C^\varepsilon}{f_1^{q_1-1}(1, 1, 1) k \left[ \frac{1}{\Gamma(\beta_1)} \int_0^1 \tau(1-\tau)^{\beta_1-1} d\tau \right]^{q_1-1}} \right]^{\frac{1}{(q_1-1)[1-\varepsilon(q_1-1)]}} \right\}.$$

Then by (3.12), (3.13), and  $(H_1)$ , we have

$$\begin{aligned} & (\lambda^*)^{q_1-1} (f_1(I^{\gamma_1} (\lambda^*)^{q_1-1} e(\tau), (\lambda^*)^{q_1-1} e(\tau), A (\lambda^*)^{q_1-1} e(\tau)))^{q_1-1} \\ & \geq (\lambda^*)^{q_1-1} (f_1((\lambda^*)^{q_1-1} I^{\gamma_1} e(\tau), (\lambda^*)^{q_1-1} e(\tau), (\lambda^*)^{q_1-1} A e(\tau)))^{q_1-1} \\ & \geq (\lambda^*)^{q_1-1} (\lambda^*)^{-\varepsilon(q_1-1)^2} (f_1(I^{\gamma_1} e(\tau), e(\tau), A e(\tau)))^{q_1-1} \end{aligned}$$

$$\begin{aligned}
&\geq (\lambda^*)^{(q_1-1)[1-\varepsilon(q_1-1)]} (f_1(C, C, C))^{q_1-1} \\
&\geq (\lambda^*)^{(q_1-1)[1-\varepsilon(q_1-1)]} C^{-\varepsilon} f_1^{q_1-1}(1, 1, 1).
\end{aligned} \tag{3.14}$$

Consequently, (3.7) and (3.14) yield

$$\begin{aligned}
&(\lambda^*)^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1}(\lambda^*)^{q_1-1} e(\tau), \right. \\
&\quad \left. (\lambda^*)^{q_1-1} e(\tau), A(\lambda^*)^{q_1-1} e(\tau) d\tau) \right)^{q_1-1} ds \\
&\geq (\lambda^*)^{(q_1-1)[1-\varepsilon(q_1-1)]} C^{-\varepsilon} f_1^{q_1-1}(1, 1, 1) \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) d\tau \right)^{q_1-1} ds \\
&\geq (\lambda^*)^{(q_1-1)[1-\varepsilon(q_1-1)]} C^{-\varepsilon} f_1^{q_1-1}(1, 1, 1) k t^{\alpha_1-\gamma_1-1} \left[ \frac{1}{\Gamma(\beta_1)} \int_0^1 \tau(1-\tau)^{\beta_1-1} d\tau \right]^{q_1-1} \\
&\geq t^{\alpha_1-\gamma_1-1}.
\end{aligned} \tag{3.15}$$

Let

$$\begin{aligned}
\Phi(t) &= (\lambda^*)^{q_1-1} e(t), \\
\Psi(t) &= (\lambda^*)^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1}(\lambda^*)^{q_1-1} e(\tau), \right. \\
&\quad \left. (\lambda^*)^{q_1-1} e(\tau), A(\lambda^*)^{q_1-1} e(\tau) d\tau) \right)^{q_1-1} ds,
\end{aligned}$$

then

$$\Phi(t) = T_{\lambda^*}(t^{\alpha_1-\gamma_1-1}), \quad \Psi(t) = T_{\lambda^*}(\Phi(t)). \tag{3.16}$$

It follows from the monotonicity of  $A, f_1$ , and (3.10), (3.15), that for any  $t \in [0, 1]$

$$\begin{aligned}
\Phi(t) &= (\lambda^*)^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1\left(\frac{\Gamma(\alpha_1-\gamma_1)}{\Gamma(\alpha_1)} t^{\alpha_1-1}, \right. \right. \\
&\quad \left. \left. \tau^{\alpha_1-\gamma_1-1}, A \tau^{\alpha_1-\gamma_1-1}\right) d\tau \right)^{q_1-1} ds \\
&\geq \lambda_1 e(t) \geq t^{\alpha_1-\gamma_1-1}, \\
\Psi(t) &= (\lambda^*)^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1}(\lambda^*)^{q_1-1} e(\tau), \right. \\
&\quad \left. (\lambda^*)^{q_1-1} e(\tau), A(\lambda^*)^{q_1-1} e(\tau) d\tau) \right)^{q_1-1} ds \\
&\geq t^{\alpha_1-\gamma_1-1}.
\end{aligned} \tag{3.17}$$

Moreover, by (3.9) and (3.16), we know

$$\begin{aligned}
D^{\alpha_1-\gamma_1} \Phi(0) &= D^{\alpha_1-\gamma_1} \Phi(1) = 0, & \Phi(0) &= 0, & D^{\alpha_1-\gamma_1-1} \Phi(1) &= \xi_1 I^{\omega_1} \Phi(\eta_1), \\
D^{\alpha_1-\gamma_1} \Psi(0) &= D^{\alpha_1-\gamma_1} \Psi(1) = 0, & \Psi(0) &= 0, & D^{\alpha_1-\gamma_1-1} \Psi(1) &= \xi_1 I^{\omega_1} \Psi(\eta_1).
\end{aligned} \tag{3.18}$$

Proceeding as in (3.6)-(3.8), we get that  $\Phi(t), \Psi(t) \in P$ . By (3.16) and (3.17), we have

$$t^{\alpha_1-\gamma_1-1} \leq \Psi(t) = (T_{\lambda^*}\Phi)(t), \quad t^{\alpha_1-\gamma_1-1} \leq \Phi(t), \quad \forall t \in [0, 1], \quad (3.19)$$

which implies

$$\begin{aligned} \Psi(t) &= (T_{\lambda^*}\Phi)(t) \\ &= (\lambda^*)^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1}(\lambda^*)^{q_1-1} e(\tau), \right. \\ &\quad \left. (\lambda^*)^{q_1-1} e(\tau), A(\lambda^*)^{q_1-1} e(\tau)) d\tau \right)^{q_1-1} ds \\ &\leq (\lambda^*)^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} \tau^{\alpha_1-\gamma_1-1}, \tau^{\alpha_1-\gamma_1-1}, A\tau^{\alpha_1-\gamma_1-1}) d\tau \right)^{q_1-1} ds \\ &= \Phi(t). \end{aligned} \quad (3.20)$$

Thus, by (3.9), (3.16), (3.17), and (3.20)

$$\begin{aligned} D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Psi))(t) + \lambda^* f_1(I^{\gamma_1}\Psi(t), \Psi(t), A\Psi(t)) \\ = D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}(T_{\lambda^*}\Phi)))(t) + \lambda^* f_1(I^{\gamma_1}\Psi(t), \Psi(t), A\Psi(t)) \\ \geq -\lambda^* f_1(I^{\gamma_1}\Phi(t), \Phi(t), A\Phi(t)) + \lambda^* f_1(I^{\gamma_1}\Phi(t), \Phi(t), A\Phi(t)) = 0, \end{aligned} \quad (3.21)$$

$$\begin{aligned} D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Phi))(t) + \lambda^* f_1(I^{\gamma_1}\Phi(t), \Phi(t), A\Phi(t)) \\ = D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}(T_{\lambda^*}(t^{\alpha_1-\gamma_1-1}))))(t) + \lambda^* f_1(I^{\gamma_1}\Phi(t), \Phi(t), A\Phi(t)) \\ \leq -\lambda^* f_1(I^{\gamma_1} t^{\alpha_1-\gamma_1-1}, t^{\alpha_1-\gamma_1-1}, A t^{\alpha_1-\gamma_1-1}) \\ + \lambda^* f_1(I^{\gamma_1} t^{\alpha_1-\gamma_1-1}, t^{\alpha_1-\gamma_1-1}, A t^{\alpha_1-\gamma_1-1}) = 0. \end{aligned} \quad (3.22)$$

It follows from (3.18) and (3.21)-(3.22) that  $\Psi(t), \Phi(t)$  are upper and lower solutions of BVP (2.6), and that  $\Psi(t), \Phi(t) \in P$ . Now let us define a function

$$F(v_1) = \begin{cases} f_1(I^{\gamma_1}\Psi(t), \Psi(t), A\Psi(t)), & v_1 < \Psi(t), \\ f_1(I^{\gamma_1}v_1(t), v_1(t), Av_1(t)), & \Psi(t) \leq v_1 \leq \Phi(t), \\ f_1(I^{\gamma_1}\Phi(t), \Phi(t), A\Phi(t)), & v_1 > \Phi(t). \end{cases}$$

Clearly,  $F: [0, +\infty] \rightarrow [0, +\infty]$  is continuous.

We now show that the fractional boundary value problem

$$\begin{cases} -D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}v_1))(t) = \lambda^* F(v_1), \\ D^{\alpha_1-\gamma_1}v_1(0) = D^{\alpha_1-\gamma_1}v_1(1) = 0, \\ v_1(0) = 0, \quad D^{\alpha_1-\gamma_1-1}v_1(1) = \xi_1 I^{\omega_1}v_1(\eta_1), \end{cases} \quad (3.23)$$

has a positive solution. Define the operator  $D_{\lambda^*}$  by

$$D_{\lambda^*}v_1(t) = (\lambda^*)^{q_1-1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) F(v_1(\tau)) d\tau \right)^{q_1-1} ds.$$

Then  $D_{\lambda^*} : C[0,1] \rightarrow C[0,1]$ , and a fixed point of the operator  $D_{\lambda^*}$  is a solution of the BVP (3.23). On the other hand, from the definition of  $F$  and the fact that the function  $f_1(x, y, z)$  is non-increasing in  $x, y, z$  respectively, and  $A$  is non-decreasing, we obtain  $f_1(I^{\gamma_1} \Phi(t), \Phi(t), A\Phi(t)) \leq F(v_1(t)) \leq f_1(I^{\gamma_1} \Psi(t), \Psi(t), A\Psi(t))$ , provided that  $\Psi(t) \leq v_1(t) \leq \Phi(t)$ ,  $F(v_1(t)) = f_1(I^{\gamma_1} \Psi(t), \Psi(t), A\Psi(t))$ , provided that  $v_1(t) < \Psi(t)$ , and  $F(v_1(t)) = f_1(I^{\gamma_1} \Phi(t), \Phi(t), A\Phi(t))$ , provided that  $v_1(t) > \Phi(t)$ . So we have

$$f_1(I^{\gamma_1} \Phi(t), \Phi(t), A\Phi(t)) \leq F(v_1(t)) \leq f_1(I^{\gamma_1} \Psi(t), \Psi(t), A\Psi(t)), \quad \forall v_1(t) \in E.$$

Furthermore, since  $\Psi(t) \geq t^{\alpha_1 - \gamma_1 - 1}$ , we have

$$\begin{aligned} f_1(I^{\gamma_1} \Phi(t), \Phi(t), A\Phi(t)) &\leq F(v_1(t)) \\ &\leq f_1(I^{\gamma_1} t^{\alpha_1 - \gamma_1 - 1}, t^{\alpha_1 - \gamma_1 - 1}, A t^{\alpha_1 - \gamma_1 - 1}), \quad \forall v_1(t) \in E. \end{aligned} \quad (3.24)$$

It follows from (3.11), for any  $v_1(t) \in E$

$$\begin{aligned} D_{\lambda^*} v_1(t) &= (\lambda^*)^{q_1 - 1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) F(v_1(\tau)) d\tau \right)^{q_1 - 1} ds \\ &\leq (\lambda^*)^{q_1 - 1} \int_0^1 H_1(t, s) \left( \int_0^1 G(\beta_1, s, \tau) f_1(I^{\gamma_1} \tau^{\alpha_1 - \gamma_1 - 1}, \right. \\ &\quad \left. \tau^{\alpha_1 - \gamma_1 - 1}, A \tau^{\alpha_1 - \gamma_1 - 1}) d\tau \right)^{q_1 - 1} ds \\ &\leq (\lambda^*)^{q_1 - 1} d_1 \left( \frac{\beta_1 - 1}{\Gamma(\beta_1)} \int_0^1 f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1 - 1}, \tau^{\alpha_1 - \gamma_1 - 1}, b \tau^{\alpha_2 - \gamma_2 - 1} \right) d\tau \right)^{q_1 - 1} ds \\ &< +\infty, \end{aligned} \quad (3.25)$$

namely, the operator  $D_{\lambda^*}$  is uniformly bounded.

On the other hand, let  $\Omega \subset E$  be bounded. As the function  $H_1(t, s)$ ,  $G(\beta_1, t, s)$  is uniformly continuous on  $[0, 1] \times [0, 1]$ ,  $D_{\lambda^*}(\Omega)$  is equicontinuous. By the Arzela-Ascoli theorem, we have  $D_{\lambda^*} : E \rightarrow E$  is completely continuous. Thus by using the Schauder fixed point theorem,  $D_{\lambda^*}$  has at least one fixed point  $x$  such the  $x = D_{\lambda^*} x$ .

Now we prove

$$\Psi(t) \leq x(t) \leq \Phi(t), \quad t \in [0, 1].$$

Since  $x$  is a fixed point of  $D_{\lambda^*}$ , by (3.18) and (3.23), we have

$$\begin{aligned} D^{\alpha_1 - \gamma_1} x(0) &= D^{\alpha_1 - \gamma_1} x(1) = 0, & x(0) &= 0, & D^{\alpha_1 - \gamma_1 - 1} x(1) &= \xi_1 I^{\omega_1}(x(\eta_1)), \\ D^{\alpha_1 - \gamma_1} \Phi(0) &= D^{\alpha_1 - \gamma_1} \Phi(1) = 0, & \Phi(0) &= 0, & D^{\alpha_1 - \gamma_1 - 1} \Phi(1) &= \xi_1 I^{\omega_1}(\Phi(\eta_1)). \end{aligned} \quad (3.26)$$

From (3.9), (3.16), (3.24), and noting that  $x$  is a fixed point of  $D_{\lambda^*}$ , we also have

$$\begin{aligned} D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1 - \gamma_1} \Phi))(t) &- D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1 - \gamma_1} x))(t) \\ &= -\lambda^* f_1(I^{\gamma_1} t^{\alpha_1 - \gamma_1 - 1}, t^{\alpha_1 - \gamma_1 - 1}, A t^{\alpha_1 - \gamma_1 - 1}) + \lambda^* F(x(t)) \leq 0. \end{aligned}$$

Let  $z(t) = \varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Phi)(t) - \varphi_{p_1}(-D^{\alpha_1-\gamma_1}x)(t)$ , then

$$D^{\beta_1}z(t) = D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Phi(t))) - D^{\beta_1}(\varphi_{p_1}(-D^{\alpha_1-\gamma_1}x(t))) \leq 0,$$

$$z(0) = \varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Phi(0)) - \varphi_{p_1}(-D^{\alpha_1-\gamma_1}x(0)) = 0,$$

$$z(1) = \varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Phi(1)) - \varphi_{p_1}(-D^{\alpha_1-\gamma_1}x(1)) = 0.$$

In view of Lemmas 2.1 and 2.3, we obtain

$$z(t) \geq 0,$$

i.e.

$$\varphi_{p_1}(-D^{\alpha_1-\gamma_1}\Phi(t)) - \varphi_{p_1}(-D^{\alpha_1-\gamma_1}x(t)) \geq 0,$$

Noticing that  $\varphi_{p_1}$  is monotone increasing, we have

$$-D^{\alpha_1-\gamma_1}\Phi(t) \geq -D^{\alpha_1-\gamma_1}x(t),$$

i.e.

$$-D^{\alpha_1-\gamma_1}(\Phi(t) - x(t)) \geq 0.$$

It follows from Lemma 2.6 and (3.26)

$$\Phi(t) - x(t) \geq 0.$$

Then we have  $x(t) \leq \Phi(t)$  on  $[0, 1]$ . In the same way we also have  $x(t) \geq \Psi(t)$  on  $[0, 1]$ . So

$$\Psi(t) \leq x(t) \leq \Phi(t). \quad (3.27)$$

Consequently,  $F(x(t)) = f_1(I^{\gamma_1}x(t), x(t), Ax(t))$ ,  $t \in [0, 1]$ . Hence  $x(t)$  is a positive solution of the problem (2.6). Finally, by (3.27) and  $\Phi, \Psi \in P$ , we have

$$l_{\Psi}t^{\alpha_1-\gamma_1-1} \leq \Psi(t) \leq x(t) \leq \Phi(t) \leq l_{\Phi}^{-1}t^{\alpha_1-\gamma_1-1}.$$

Then by Lemmas 2.5

$$\begin{cases} u_1(t) = I^{\gamma_1}x(t), \\ u_2(t) = I^{\gamma_1}v_2(t), \end{cases}$$

where  $v_2(t) = \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1}x(\tau)) d\tau \right)^{q_2-1} ds$  is the unique positive solution of system (1.1).

Since the process is similar to (3.4) and (3.5) we obtain

$$\begin{aligned} v_2(t) &= \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1}x(\tau)) d\tau \right)^{q_2-1} ds \\ &\leq \int_0^1 H_2(t, s) \left( \int_0^1 G(\beta_2, s, \tau) f_2\left(\tau, l_{\Phi}^{-1} \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1}\right) d\tau \right)^{q_2-1} ds \\ &\leq al_{\Phi}^{-\sigma(q_2-1)} t^{\alpha_2-\gamma_2-1} \end{aligned}$$



and

$$\begin{aligned} v_2(t) &= \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2(\tau, I^{\gamma_1} x(\tau)) d\tau \right)^{q_2-1} ds \\ &\geq \int_0^1 H_2(t,s) \left( \int_0^1 G(\beta_2, s, \tau) f_2 \left( \tau, l_{\Psi} \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1-1} \right) d\tau \right)^{q_2-1} ds \\ &\geq b l_{\Psi}^{\sigma(q_2-1)} t^{\alpha_2 - \gamma_2 - 1}, \end{aligned}$$

i.e.

$$b l_{\Psi}^{\sigma(q_2-1)} \frac{\Gamma(\alpha_2 - \gamma_2)}{\Gamma(\alpha_2)} t^{\alpha_2-1} \leq u_2(t) = I^{\gamma_1} v_2(t) \leq a l_{\Phi}^{-\sigma(q_2-1)} \frac{\Gamma(\alpha_2 - \gamma_2)}{\Gamma(\alpha_2)} t^{\alpha_2-1}. \quad (3.28)$$

□

**Example** Consider the following boundary value problem:

$$\begin{cases} -D^{\frac{5}{2}}(\varphi_3(-D^{\frac{4}{3}}u_1))(t) = \lambda(u_1^{-\frac{2}{9}}(t) + [D^{\frac{1}{6}}u_1(t)]^{-\frac{1}{2}} + [D^{\frac{1}{4}}u_2(t)]^{-\frac{1}{8}}), \\ -D^{\frac{11}{4}}(\varphi_4(-D^{\frac{3}{2}}u_2))(t) = (t^2 + 1)u_1^{\frac{1}{7}}(t), \\ D^{\frac{4}{3}}u_1(0) = D^{\frac{4}{3}}u_1(1) = 0, D^{\frac{1}{6}}u_1(0) = 0, D^{\frac{1}{3}}u_1(1) = 2I^{\frac{5}{6}}(D^{\frac{1}{6}}u_1(\frac{1}{3})), \\ D^{\frac{3}{2}}u_2(0) = D^{\frac{3}{2}}u_2(1) = 0, D^{\frac{1}{4}}u_2(0) = 0, D^{\frac{1}{2}}u_2(1) = 5I^{\frac{7}{4}}(D^{\frac{1}{4}}u_2(\frac{1}{2})). \end{cases} \quad (3.29)$$

Let  $\alpha_1 = \frac{4}{3}, \alpha_2 = \frac{3}{2}, \beta_1 = \frac{5}{2}, \beta_2 = \frac{11}{4}, \gamma_1 = \frac{1}{6}, \gamma_2 = \frac{1}{4}, p_1 = 3, p_2 = 4, \omega_1 = \frac{5}{6}, \omega_2 = \frac{7}{4}, \xi_1 = 2, \xi_2 = 5, \eta_1 = \frac{1}{3}, \eta_2 = \frac{1}{2}$ .

First, we have

$$\begin{aligned} \Gamma(\alpha_1 - \gamma_1 + \omega_1) &= \Gamma(2) = 1 > \xi_1 \eta_1^{\alpha_1 - \gamma_1 + \omega_1 - 1} = 2 \left( \frac{1}{3} \right), \\ \Gamma(\alpha_2 - \gamma_2 + \omega_2) &= \Gamma(3) = 2 > \xi_2 \eta_2^{\alpha_2 - \gamma_2 + \omega_2 - 1} = 5 \left( \frac{1}{2} \right)^2, \end{aligned}$$

and  $q_1 = \frac{3}{2}, q_2 = \frac{4}{3}$ , then  $(s_0), (s_1)$ , and  $(s_2)$  hold.

Second, let

$$f_1(x, y, z) = x^{-\frac{2}{9}} + y^{-\frac{1}{2}} + z^{-\frac{1}{8}}, \quad f_2(t, x) = (t^2 + 1)x^{\frac{1}{7}}, \quad \sigma = \frac{1}{3} < \frac{1}{q_2 - 1} = 3,$$

and for all  $r \in (0, 1), (x, y, z) \in (0, +\infty)^3, (t, x) \in (0, 1) \times (0, +\infty)$ ,

$$\begin{aligned} f_1(rx, ry, rz) &= r^{-\frac{2}{9}}x^{-\frac{2}{9}} + r^{-\frac{1}{2}}y^{-\frac{1}{2}} + r^{-\frac{1}{8}}z^{-\frac{1}{8}} \leq r^{-\frac{1}{2}}f_1(x, y, z), \\ f_2(t, rx) &= (t^2 + 1)r^{\frac{1}{7}}x^{\frac{1}{7}} \geq r^{\frac{1}{3}}f_2(t, x), \end{aligned}$$

which implies that  $(H_1), (H_2)$  hold. On the other hand, by direct calculation, we have  $f_1(1, 1, 1) = 3 \neq 0$ , and then

$$\begin{aligned} b &= e_2 \int_0^1 [1 - (1-s)^{\alpha_2 - \gamma_2 - 1}] s^{(\beta_2 - 1)(q_2 - 1)} (1-s)^{q_2 - 1} ds \\ &\quad \times \left( \frac{1}{\Gamma(\beta_2)} \int_0^1 \tau (1-\tau)^{\beta_2 - 1} f_2 \left( \tau, \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} \tau^{\alpha_1 - 1} \right) d\tau \right)^{q_2 - 1} \end{aligned}$$

$$\begin{aligned}
 &= \Gamma\left(\frac{5}{4}\right) \int_0^1 [1 - (1-s)^{\frac{1}{4}}] s^{\frac{7}{4} \cdot \frac{1}{3}} (1-s)^{\frac{1}{3}} ds \\
 &\quad \times \left( \frac{1}{\Gamma(\frac{11}{4})} \int_0^1 \tau(1-\tau)^{\frac{7}{4}} (\tau^2 + 1) \left[ \frac{\Gamma(\frac{7}{6})}{\Gamma(\frac{4}{3})} \right]^{\frac{1}{7}} \tau^{\frac{1}{21}} d\tau \right)^{\frac{1}{3}} > 0.
 \end{aligned}$$

Thus

$$\begin{aligned}
 &\int_0^1 f_1 \left( \frac{\Gamma(\alpha_1 - \gamma_1)}{\Gamma(\alpha_1)} t^{\alpha_1-1}, t^{\alpha_1-\gamma_1-1}, b t^{\alpha_2-\gamma_2-1} \right) dt \\
 &= \int_0^1 \left\{ \left[ \frac{\Gamma(\frac{7}{6})}{\Gamma(\frac{4}{3})} t^{\frac{1}{3}} \right]^{-\frac{2}{9}} + [t^{\frac{1}{6}}]^{-\frac{1}{2}} + [b t^{\frac{1}{4}}]^{-\frac{1}{8}} \right\} dt \\
 &= \int_0^1 \left\{ \left[ \frac{\Gamma(\frac{7}{6})}{\Gamma(\frac{4}{3})} \right]^{-\frac{2}{9}} t^{-\frac{2}{27}} + t^{-\frac{1}{12}} + b^{-\frac{1}{8}} t^{-\frac{1}{32}} \right\} dt < +\infty.
 \end{aligned}$$

Hence,  $(H_3)$  holds. Then by Theorem 3.1 there exists a constant  $\lambda^* > 0$  such that for any  $\lambda \in (\lambda^*, +\infty)$ , the BVP (1.1) has at least one positive solution  $(u_1(t), u_2(t))$ .

#### Competing interests

The author declares to have no competing interests.

#### Author's contributions

The whole work was carried out by the author.

#### Acknowledgements

The author sincerely thanks the editor and reviewers for their valuable suggestions and useful comments to improve the manuscript.

Received: 15 May 2016 Accepted: 28 July 2016 Published online: 17 August 2016

#### References

- Wang, Y, Liu, L, Wu, Y: Positive solutions for a nonlocal fractional differential equation. *Nonlinear Anal., Theory Methods Appl.* **74**, 3599-3605 (2011)
- Zhang, X, Liu, L, Wu, Y: The uniqueness of positive solution for a singular fractional differential system involving derivatives. *Commun. Nonlinear Sci. Numer. Simul.* **18**, 1400-1409 (2013)
- Zhang, X, Liu, L, Benchawan, W, Wu, Y: The eigenvalue for a class of singular p-Laplacian fractional differential equations involving the Riemann-Stieltjes integral boundary condition. *Appl. Math. Comput.* **235**, 412-422 (2014)
- Zhang, X, Liu, L, Wu, Y: Existence results for multiple positive solutions of nonlinear higher order perturbed fractional differential equations with derivatives. *Appl. Math. Comput.* **219**, 1420-1433 (2012)
- Zhang, X, Wu, Y, Caccetta, L: Nonlocal fractional order differential equations with changing-sign singular perturbation. *Appl. Math. Model.* **39**, 6543-6552 (2015)
- Zhang, X, Liu, L, Wu, Y, Wiwatanapatapee, B: The spectral analysis for a singular fractional differential equation with a signed measure. *Appl. Math. Comput.* **257**, 252-263 (2015)
- Cui, Y, Liu, L, Zhang, X, Wu, Y: Uniqueness and existence of positive solutions for singular differential systems with coupled integral boundary value problems. *Abstr. Appl. Anal.* **2013**, Article ID 340487 (2013)
- Wang, Y, Liu, L, Zhang, X, Wu, Y: Positive solutions for  $(n-1, 1)$ -type singular fractional differential system with coupled integral boundary conditions. *Abstr. Appl. Anal.* **2014**, Article ID 142391 (2014)
- Ahmas, B, Niteo, JJ: Existence results for a coupled system of nonlinear fractional differential equations with three-point boundary conditions. *Appl. Math. Comput.* **58**(9), 1838-1843 (2009)
- Su, X: Boundary value problem for a coupled system of nonlinear fractional differential equations. *Appl. Math. Lett.* **22**(1), 64-69 (2009)
- Zhang, Y, Bai, Z, Feng, T: Existence results for a coupled system of nonlinear fractional three-point boundary value problems at resonance. *Appl. Math. Comput.* **61**(4), 1032-1047 (2011)
- Goodrich, CS: Existence of a positive solution to systems of differential equations of fractional order. *Appl. Math. Comput.* **62**(3), 1251-1268 (2011)
- Wei, Z, Li, Q, Che, J: Initial value problems for fractional differential equations involving Riemann-Liouville sequential fractional derivative. *J. Math. Anal. Appl.* **367**(1), 260-272 (2010)
- Li, F, Sun, J, Jia, M: Monotone iterative method for second-order three-point boundary value problem with upper and lower solutions in the reversed order. *Appl. Math. Comput.* **217**, 4840-4847 (2011)
- Henderson, J: Existence of multiple solutions for second order boundary value problems. *J. Differ. Equ.* **166**, 443-454 (2000)
- Bai, Z, Lv, H: Positive solutions for boundary value problem of nonlinear fractional differential equation. *J. Math. Anal. Appl.* **311**, 495-505 (2005)

17. Wang, G: Explicit iteration and unbounded solutions for fractional integral boundary value problem on an infinite interval. *Appl. Math. Lett.* **17**, 1-7 (2015)
18. Zhang, X, Liu, L, Wu, Y: The uniqueness of positive solution for a fractional order model of turbulent flow in a porous medium. *Appl. Math. Lett.* **37**, 26-33 (2014)

**Submit your manuscript to a SpringerOpen<sup>®</sup> journal and benefit from:**

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

---

Submit your next manuscript at ► [springeropen.com](http://springeropen.com)