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Dynamics of stochastic Boissonade system on the time-varying domain

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Abstract

The current paper is devoted to studying the stochastic Boissonade system defined on time-varying domains. The existence and uniqueness of strong and weak solutions for the stochastic Boissonade system are established. Moreover, the existence of pullback attractor for the 'partial-random' system generated by the weak solution is also presented.

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1 Introduction

The well-posedness and dynamics of the partial differential equations defined on the time-varying domains are interesting questions to study, and they have attracted a lot of attentions recently. There are many papers on this topic, we refer the reader to [1–10] and the references therein. The stochastic dynamical systems defined on time-varying domains are more attractive. Crauel, Kloeden, and Real established the framework for deterministic PDE on time-varying domains, and later, they also developed a new approach to defined noise on time-varying domain, and established the existence and uniqueness of the solutions for stochastic partial differential equations with additive noise on time-varying domains in [11]. Recently, Crauel, Kloeden, and Yang developed the theory of 'partial-random' dynamical systems to obtain the existence of random attractors for stochastic reaction-diffusion equations on time-varying domains in [4].

Reaction-diffusion systems are usually used to describe the Turing pattern in a class of chemical or biological systems, and the Turing pattern was observed in the chlorite-iodine-malonic acid reaction in 1992. Dufiet and Boissonade in [12] were first to introduce the following reaction-diffusion systems (we called it a Boissonade system):

$$\begin{cases} \frac{\partial u}{\partial t} = d_1 \Delta u + u - \alpha v + \gamma uv - u^3, \\ \frac{\partial v}{\partial t} = d_2 \Delta v + u - \beta v, \end{cases} \quad (1.1)$$

to exhibit the Turing pattern of the model to describe the relation between the genuine homogeneous 2D systems and the 3D monolayers, where d_1 , d_2 , α , γ , and β are positive constants.

The Boissonade system (1.1) is quite different from the Fitzhugh-Nagumo system in [13] and [14], the square term u^2 in the Fitzhugh-Nagumo system is replaced by the cross term uv , leading to the nonlinearity of the second equation in the Boissonade system, and it induces more difficulties to obtain the uniqueness of the solution. Recently, Tu in [15] proved the existence of the global attractor for the Boissonade system (1.1). Due to the time-varying domain, the stochastic partial differential equation induces the *new partial* random dynamical systems, which is very interesting, we refer the reader to [11] for more details.

Motivated by the idea of Crauel, Kloeden, and Real in [3] and Crauel, Kloeden, and Yang in [11], we study the stochastic Boissonade system (SBS) on the time-varying domain by using some tricks derived from the Sobolev embedding theorem to obtain a unique solution for the SBS, and we establish the existence of a pullback attractor for the ‘partial-random’ dynamical system generated by the weak solution for the stochastic Boissonade system on the time-varying domain.

The rest of the paper is arranged as follows. In Section 2, some notations on time-varying domains are introduced. Sections 3 and 4 are devoted to proving the existence and uniqueness of solutions of random equations defined on fixed domains which are transformed from time-varying domains. The existence of the pullback attractor for the process generalized by the weak solution is presented in Section 5.

2 SBS defined on time-varying domains

In this section, we will introduce some notions and functional spaces on time-varying domains, following [11], and derive the Boissonade system with additive noise on the time-varying domain.

2.1 Assumption on the time-varying domain

Let \mathcal{O} be a nonempty bounded open subset of \mathbb{R}^N with C^2 boundary $\partial\mathcal{O}$, and $r = r(y, t)$ a vector function

$$r \in C^1(\bar{\mathcal{O}} \times \mathbb{R}; \mathbb{R}^N), \tag{2.1}$$

such that

$$r(\cdot, t) : \mathcal{O} \rightarrow \mathcal{O}_t \text{ is a } C^2\text{-diffeomorphism for all } t \in \mathbb{R}. \tag{2.2}$$

$\bar{r}(\cdot, t) = r^{-1}(\cdot, t)$ is the inverse of $r(\cdot, t)$ satisfying the property

$$\bar{r} \in C^{2,1}(\bar{Q}_{\tau,T}; \mathbb{R}^N) \text{ for all } \tau < T, \tag{2.3}$$

i.e., $\bar{r}, \frac{\partial \bar{r}}{\partial t}, \frac{\partial \bar{r}}{\partial x_i}$ and $\frac{\partial^2 \bar{r}}{\partial x_i \partial x_j}$ belong to $C(\bar{Q}_{\tau,T}; \mathbb{R}^N)$ for all $1 \leq i, j \leq N$ and for any $\tau < T$. Then $\{\mathcal{O}_t\}_{t \in [\tau, T]}$ is a family of nonempty bounded open subsets of \mathbb{R}^N ($N \leq 3$).

Define

$$Q_{\tau,T} := \bigcup_{t \in (\tau, T)} \mathcal{O}_t \times \{t\} \text{ for all } T > \tau, \tag{2.4}$$

$$Q_{\tau} := \bigcup_{t \in (\tau, \infty)} \mathcal{O}_t \times \{t\} \text{ for all } \tau \in \mathbb{R},$$

$$\Sigma_{\tau,T} := \bigcup_{t \in (\tau,T)} \partial \mathcal{O}_t \times \{t\} \quad \text{for all } T > \tau,$$

and

$$\Sigma_{\tau} := \bigcup_{t \in (\tau,\infty)} \partial \mathcal{O}_t \times \{t\} \quad \text{for all } \tau \in \mathbb{R}.$$

For any $T > \tau$, the set $Q_{\tau,T}$ is an open subset of \mathbb{R}^{N+1} with the boundary

$$\partial Q_{\tau,T} := \Sigma_{\tau,T} \cup (\partial \mathcal{O}_{\tau} \times \{\tau\}) \cup (\partial \mathcal{O}_T \times \{T\}).$$

2.2 Assumption on noise

Assume that $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space, a sequence $\{w_j(t) : t \in [0, \infty)\}_{j \geq 1}$ of mutually independent two-sided standard scalar Wiener processes adapted to a common filtration $\{\mathcal{F}_t : t \in [0, \infty)\}$ in \mathcal{F} . Let $\{\phi_j\}_{j \geq 1} \subset H_0^1(\mathcal{O}) \subset L^2(\mathcal{O})$ and $\{\varphi_j\}_{j \geq 1} \subset H_0^1(\mathcal{O}) \subset L^2(\mathcal{O})$ be two sequences of functions such that

$$\sum_{j=1}^{\infty} \|\phi_j\|_{H_0^1(\mathcal{O})} \leq \infty, \quad \sum_{j=1}^{\infty} \|\varphi_j\|_{H_0^1(\mathcal{O})} \leq \infty. \tag{2.5}$$

Define

$$\Phi_j := \phi_j(\bar{r}(x, t)), \quad \Psi_j := \varphi_j(\bar{r}(x, t)), \quad x \in \mathcal{O}_t, t \in [0, \infty), j = 1, 2, \dots$$

It follows from [7] that, for all $t \in \mathbb{R}$,

$$\sum_{j=1}^{\infty} \|\Phi_j\|_{H_0^1(\mathcal{O}_t)} \leq \infty, \quad \sum_{j=1}^{\infty} \|\Psi_j\|_{H_0^1(\mathcal{O}_t)} \leq \infty.$$

Consider the $L^2(\mathcal{O}_t)$ -valued \mathcal{F}_t -adapted stochastic processes. Define

$$M_1 := \sum_{j=1}^{\infty} \Phi_j(t)w_j(t), \quad M_2 := \sum_{j=1}^{\infty} \Psi_j(t)w_j(t), \quad t \geq 0. \tag{2.6}$$

Let \mathbb{E} be the expectation with respect the probability \mathbb{P} . Due to the pairwise independence of the $w_j(t)$, we have

$$E \left\| \sum_{j=n}^m \Phi_j(t)w_j(t) \right\|_{L^2(\mathcal{O}_t)}^2 = t \sum_{j=n}^m \|\Phi_j(t)\|_{L^2(\mathcal{O}_t)}^2$$

and

$$E \left\| \sum_{j=n}^m \Psi_j(t)w_j(t) \right\|_{L^2(\mathcal{O}_t)}^2 = t \sum_{j=n}^m \|\Psi_j(t)\|_{L^2(\mathcal{O}_t)}^2$$

for any $t \geq 0, m > n \geq 1$. Therefore, we get $M_1(t), M_2(t) \in L^2(\mathcal{O}_t \times \Omega)$ which are \mathcal{F}_t -measurable. Then $\{M_1(t) : t \geq 0\}$ and $\{M_2(t) : t \geq 0\}$ can be viewed as \mathcal{F}_t -adapted processes with values in $L^2(\mathcal{O}_t)$.

Direct computation implies that $\mathbb{E}M_1(t) = \mathbb{E}M_2(t) = 0$,

$$\mathbb{E} \|M_1(t)\|_{L^2(\mathcal{O}_t)}^2 = t \sum_{j=1}^{\infty} \|\Phi(t)\|_{L^2(\mathcal{O}_t)}^2 \leq t C_{r,t} \sum_{j=1}^{\infty} \|\phi(t)\|_{L^2(\mathcal{O})}^2$$

and

$$\mathbb{E} \|M_2(t)\|_{L^2(\mathcal{O}_t)}^2 = t \sum_{j=1}^{\infty} \|\Psi(t)\|_{L^2(\mathcal{O}_t)}^2 \leq t C_{r,t} \sum_{j=1}^{\infty} \|\varphi(t)\|_{L^2(\mathcal{O})}^2$$

for any $t \in [0, \infty)$, where $C_{r,t} = \max_{y \in \bar{\mathcal{O}}} \text{Jac}(r, y, t)$ and $\text{Jac}(r, y, t)$ denoted the absolute value of the determinant of the Jacobi matrix $(\frac{\partial r_i}{\partial y_j}(y, t))_{N \times N}$.

2.3 Stochastic Boissonade system on the time-varying domain

Following the arguments in [11], we can study the stochastic Boissonade system with additive noise and homogeneous Dirichlet boundary condition on the time-varying domain as follows:

$$\begin{cases} du = (d_1 \Delta u + u - \alpha v + \gamma uv - u^3) dt + dM_1, & \text{in } Q_0, \\ dv = (d_2 \Delta v + u - \beta v) dt + dM_2, & \text{in } Q_0, \\ u = 0, \quad v = 0, & \text{on } \Sigma_0, \\ u(0, x) = u_0(x), \quad v(0, x) = v_0(x), & x \in \mathcal{O}_0, \end{cases} \tag{2.7}$$

where dM_1 and dM_2 can be represented by

$$dM_1(t) = \sum_{j=1}^{\infty} \phi_j(\bar{r}(x, t)) dw_j(t) + \sum_{j=1}^{\infty} w_j(t) \nabla_y \phi_j(\bar{r}(x, t)) \cdot \frac{\partial \bar{r}}{\partial t}(x, t) dt \tag{2.8}$$

and

$$dM_2(t) = \sum_{j=1}^{\infty} \varphi_j(\bar{r}(x, t)) dw_j(t) + \sum_{j=1}^{\infty} w_j(t) \nabla_y \varphi_j(\bar{r}(x, t)) \cdot \frac{\partial \bar{r}}{\partial t}(x, t) dt. \tag{2.9}$$

Denote

$$U(y, t) = u(r(y, t), t), \quad V(y, t) = v(r(y, t), t) \quad \text{for } y \in \mathcal{O}, t \geq 0, \tag{2.10}$$

and

$$a_{jk}(y, t) = \sum_{i=1}^N \frac{\partial \bar{r}_k}{\partial x_i}(r(y, t), t) \frac{\partial \bar{r}_j}{\partial x_i}(r(y, t), t), \quad j, k = 1, \dots, N.$$

Define $b(y, t) = (b_1(y, t), \dots, b_N(y, t)) \in \mathbb{R}^N$ and $c(y, t) = (c_1(y, t), \dots, c_N(y, t)) \in \mathbb{R}^N$ by

$$\begin{aligned}
 b_k(y, t) &= d_1 \Delta_x \bar{r}_k(r(y, t), t) - \frac{\partial \bar{r}_k}{\partial t}(r(y, t), t) - d_1 \sum_{j=1}^N \frac{\partial a_{jk}}{\partial y_j}(y, t), \quad k = 1, \dots, N, \\
 c_k(y, t) &= d_2 \Delta_x \bar{r}_k(r(y, t), t) - \frac{\partial \bar{r}_k}{\partial t}(r(y, t), t) - d_2 \sum_{j=1}^N \frac{\partial a_{jk}}{\partial y_j}(y, t), \quad k = 1, \dots, N.
 \end{aligned}$$

Then equations (2.7) on time-varying domains can be rewritten into the following equations on $\mathcal{O} \times [0, \infty)$:

$$\begin{cases}
 dU = [d_1 \sum_{j,k=1}^N \frac{\partial}{\partial y_j}(a_{jk} U_{y_k}) + b \cdot \nabla_y U \\
 \quad + U - \alpha V + \gamma UV - U^3 + R_1] dt + dW_1, & \text{in } \mathcal{O} \times [0, \infty), \\
 dV = [d_2 \sum_{j,k=1}^N \frac{\partial}{\partial y_j}(a_{jk} V_{y_k}) + c \cdot \nabla_y V \\
 \quad + U - \beta V + R_2] dt + dW_2, & \text{in } \mathcal{O} \times [0, \infty), \\
 U = 0, \quad V = 0, & \text{on } \partial \mathcal{O} \times [0, \infty), \\
 U(y, 0) = u(r(y, 0)), \quad V(y, 0) = v(r(y, 0)), & y \in \mathcal{O},
 \end{cases} \tag{2.11}$$

where

$$\begin{aligned}
 R_1(y, t) &= \sum_{j=1}^{\infty} w_j(t) \nabla_y \phi_j(y) \cdot \frac{\partial \bar{r}}{\partial t}(r(y, t), t), \\
 R_2(y, t) &= \sum_{j=1}^{\infty} w_j(t) \nabla_y \varphi_j(y) \cdot \frac{\partial \bar{r}}{\partial t}(r(y, t), t),
 \end{aligned}$$

and

$$W_1(y, t) = \sum_{j=1}^{\infty} \phi_j(y) w_j(t), \quad W_2(y, t) = \sum_{j=1}^{\infty} \varphi_j(y) w_j(t).$$

Due to the independence of the w_j and the assumption (2.5), the processes $W_1(t)$ and $W_2(t)$ are two $H_0^1(\mathcal{O})$ -valued Wiener processes, and

$$\mathbb{E} \|R_1(t)\|_{L^2(\mathcal{O})}^2 \leq t \max_{y \in \mathcal{O}} \left| \frac{\partial \bar{r}}{\partial t}(r(y, t), t) \right|_{\mathbb{R}^N}^2 \sum_{j=1}^{\infty} \|\phi_j\|_{H_0^1(\mathcal{O})}^2 \quad \forall t \geq 0$$

and

$$\mathbb{E} \|R_2(t)\|_{L^2(\mathcal{O})}^2 \leq t \max_{y \in \mathcal{O}} \left| \frac{\partial \bar{r}}{\partial t}(r(y, t), t) \right|_{\mathbb{R}^N}^2 \sum_{j=1}^{\infty} \|\varphi_j\|_{H_0^1(\mathcal{O})}^2 \quad \forall t \geq 0.$$

Therefore, $R_1(t)$ and $R_2(t)$ are two \mathcal{F}_t -adapted processes belonging to $L^\infty(0, T; L^2(\Omega \times \mathcal{O}))$ for all $T \geq 0$.

Denote

$$F(y, t) = U(y, t) - W_1(y, t), \quad G(y, t) = V(y, t) - W_2(y, t) \quad \text{for } y \in \mathcal{O}, t \geq 0. \tag{2.12}$$

Then equations (2.11) can be transformed into the following equations (2.12):

$$\begin{cases} dF = [d_1 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(F + W_1)_{y_k}) + b \cdot \nabla_y(F + W_1) + (F + W_1) - \alpha(G + W_2) \\ \quad + \gamma(F + W_1)(G + W_2) - (F + W_1)^3 + R_1] dt, & \text{in } \mathcal{O} \times [0, \infty), \\ dG = [d_2 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(G + W_2)_{y_k}) + c \cdot \nabla_y(G + W_2) + (F + W_1) \\ \quad - \beta(G + W_2) + R_2] dt, & \text{in } \mathcal{O} \times [0, \infty), \\ F = 0, \quad G = 0, & \text{on } \partial\mathcal{O} \times [0, \infty), \\ F(y, 0) = u(r(y, 0)) - W_1(y, 0), \quad V(y, 0) = v(r(y, 0)) - W_2(y, 0), & y \in \mathcal{O}. \end{cases} \tag{2.13}$$

In the following, in order to show the existence of strong solution, one is required to impose the conditions on ϕ_j and $\psi_j, j = 1, 2, \dots$ by

$$\sum_{j=1}^{\infty} \|\Delta\phi_j(y)\|_{L^4(\mathcal{O})}^4 < \infty, \quad \sum_{j=1}^{\infty} \|\Delta\psi_j(y)\|_{L^2(\mathcal{O})}^2 < \infty, \tag{2.14}$$

rather than the assumption in (2.5).

3 Existence of strong solutions of SBS (2.13)

In this section, we will establish the existence and uniqueness of the strong solution for equation (2.13).

For each $T > 0$, consider the auxiliary problem for equation (2.13),

$$\begin{cases} dF = [d_1 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(F + W_1)_{y_k}) + b \cdot \nabla_y(F + W_1) + (F + W_1) - \alpha(G + W_2) \\ \quad + \gamma(F + W_1)(G + W_2) - (F + W_1)^3 + R_1] dt, & \text{in } \mathcal{O} \times [0, T], \\ dG = [d_2 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(G + W_2)_{y_k}) + c \cdot \nabla_y(G + W_2) + (F + W_1) \\ \quad - \beta(G + W_2) + R_2] dt, & \text{in } \mathcal{O} \times [0, T], \\ F = 0, \quad G = 0, & \text{on } \partial\mathcal{O} \times [0, T], \\ F(y, 0) = u(r(y, 0)) - W_1(y, 0), \quad V(y, 0) = v(r(y, 0)) - W_2(y, 0), & y \in \mathcal{O}. \end{cases} \tag{3.1}$$

Definition 3.1 (Strong solution) A \mathcal{F}_t -adapted process $(F, G) = (F(\omega, y, t), G(\omega, y, t))$ defined in $\Omega \times \mathcal{O} \times [0, T]$ is said to be a strong solution for problem (3.1) if

$$\begin{aligned} F &\in L^2(\Omega, L^2(\tau, T; H^2(\mathcal{O}))) \cap L^2(\Omega, C([\tau, T]; H_0^1(\mathcal{O}))), \\ F' &\in L^2(\Omega, L^2(\tau, T; L^2(\mathcal{O}))), \\ G &\in L^2(\Omega, L^2(\tau, T; H^2(\mathcal{O}))) \cap L^2(\Omega, C([\tau, T]; H_0^1(\mathcal{O}))), \\ G' &\in L^2(\Omega, L^2(\tau, T; L^2(\mathcal{O}))), \end{aligned}$$

and the initial data conditions in (3.1) are satisfied almost everywhere in their corresponding domains.

Lemma 3.1 ([6]) *For any $-\infty < \tau \leq T < +\infty, a_{jk} \in C^1(\bar{\mathcal{O}} \times [\tau, T]), b_k, c_k \in C^0(\bar{\mathcal{O}} \times [\tau, T])$. In particular, $a_{jk}, \frac{\partial a_{jk}}{\partial y_j}, b_k, c_k \in L^\infty(\mathcal{O} \times (\tau, T)), j, k = 1, 2, \dots, N$. Moreover, there exists a*

$\delta = \delta(v, r, \tau, T) > 0$ such that, for any $(y, t) \in \mathcal{O} \times [\tau, T]$,

$$\sum_{j,k=1}^N a_{jk}(y, t) \xi_j \xi_k \geq \delta |\xi|^2 \quad \text{for any } \xi \in \mathbb{R}^N. \tag{3.2}$$

Lemma 3.2 ([6]) *For any $-\infty < \tau \leq T < +\infty$, there exist two positive constants δ_0 and c_0 which depend on r, τ, T such that for any $u \in H^2(\mathcal{O}) \cap H_0^1(\mathcal{O})$, the following estimate holds:*

$$\begin{aligned} \delta_0 \int_{\mathcal{O}} |\Delta u(y)|^2 dy &\leq \int_{\mathcal{O}} \sum_{k,j=1}^N a_{kj}(y, t) u_{y_k y_j} \Delta u dy \\ &\quad + c_0 \int_{\mathcal{O}} |u(y)|^2 dy \quad \text{for any } t \in [\tau, T]. \end{aligned} \tag{3.3}$$

Define the time-dependent bilinear form by

$$B[\alpha, \beta, t] = \int_{\mathcal{O}} -d_1 \sum_{j,k=1}^N (a_{jk}(y, t) \alpha_{y_k}(y, t)) \beta_{y_j}(y, t) + \sum_{k=1}^N b_k(y, t) \nabla_y \alpha(y, t) \beta(y, t) dy, \tag{3.4}$$

$$D[\alpha, \beta, t] = \int_{\mathcal{O}} -d_2 \sum_{j,k=1}^N (a_{jk}(y, t) \alpha_{y_k}(y, t)) \beta_{y_j}(y, t) + \sum_{k=1}^N c_k(y, t) \nabla_y \alpha(y, t) \beta(y, t) dy, \tag{3.5}$$

for $\alpha, \beta \in H_0^1(\mathcal{O})$ and $0 \leq t \leq T$.

We can apply the Galerkin argument (see [16–18]) to prove the existence of solution for SBS. Let $\varpi_k = \varpi_k(y) \in H^2(\mathcal{O}) \cap H_0^1(\mathcal{O})$ ($k = 1, 2, \dots$) be the eigenfunctions of $-\Delta$ on $H_0^1(\mathcal{O})$, $0 < \lambda_1 < \lambda_2 < \dots < \lambda_n \dots, \lambda_n \rightarrow \infty$ as $n \rightarrow \infty$ be the corresponding eigenvalues. Then $\{\varpi_k\}_{k=1}^\infty$ is an orthogonal basis of $H_0^1(\mathcal{O})$ and an orthogonal basis of $L^2(\mathcal{O})$.

For each fixed positive integer m , denote

$$F_m(t, \omega) := \sum_{k=1}^m \zeta_m^k(t, \omega) \varpi_k, \quad G_m(t, \omega) := \sum_{k=1}^m \eta_m^k(t, \omega) \varpi_k. \tag{3.6}$$

Then for $k = 1, \dots, m$ and $\tau \leq t \leq T$,

$$\begin{aligned} (A_m^1) \quad &(F'_m(t), \varpi_k) \\ &= B[F_m(t) + P_m W_1, \varpi_k; t] + (F_m(t) + P_m W_1 - \alpha(G_m(t) + P_m W_2), \varpi_k) \\ &\quad + (\gamma(F_m(t) + P_m W_1)(G_m(t) + P_m W_2) - (F_m(t) + P_m W_1)^3 + R_1, \omega_k), \\ (A_m^2) \quad &(G'_m(t), \varpi_k) \\ &= D[G_m(t) + P_m W_2, \varpi_k; t] + (F_m(t) + P_m W_1 - \beta(G_m(t) + P_m W_2) + R_2, \varpi_k), \\ &F_m(0) = P_m F_0, \quad G_m(0) = P_m G_0, \end{aligned}$$

where $F_0(y) := u_0(r(y, t)) - W_1$, $G_0(y) := v_0(r(y, t)) - W_2$. (\cdot, \cdot) is the inner product in $L^2(\mathcal{O})$ with associated norm $\|\cdot\|_{L^2(\mathcal{O})}$, P_m is the projector from $L^2(\mathcal{O})$ to $\text{span}\{\varpi_1, \varpi_2, \dots, \varpi_m\}$. It follows from [6] and the assumption (2.5) that $F_0 \in H_0^1(\mathcal{O})$, $G_0 \in H_0^1(\mathcal{O})$.

The assumption (2.14) yields

$$\begin{aligned} P_m F_0 &\rightarrow F_0 \quad \text{in } H_0^1(\mathcal{O}) \text{ as } m \rightarrow \infty, \\ P_m G_0 &\rightarrow G_0 \quad \text{in } H_0^1(\mathcal{O}) \text{ as } m \rightarrow \infty. \end{aligned} \tag{3.7}$$

Noticing that for each integer $m = 1, 2, \dots$, there exists a unique local \mathcal{F}_t -adapted process $(F_m(\omega), G_m(\omega))$ of (2.7) satisfying (A_m) in an interval $[0, T_m]$ with $0 \leq T_m \leq T$.

Next, we will show some estimates on the sequences (F_m, G_m) , $m = 1, 2, \dots$

Lemma 3.3 *The following estimates hold.*

- (1) $\{F_m\}$ is bounded in $C^0([0, T]; L^2(\Omega, L^2(\mathcal{O}))) \cap L^2(0, T; L^2(\Omega, H_0^1(\mathcal{O}))) \cap L^4([0, T]; L^4(\mathcal{O} \times \Omega))$,
- (2) $\{G_m\}$ is bounded in $C^0([0, T]; L^2(\Omega, L^2(\mathcal{O}))) \cap L^2(0, T; L^2(\Omega, H_0^1(\mathcal{O})))$.

Proof Multiplying (A_m^1) by ζ_m^k and (A_m^2) by η_m^k , and taking the sum with respect to k from 1 to m , we obtain

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} (\|F_m\|_{L^2(\mathcal{O})}^2 + \|G_m\|_{L^2(\mathcal{O})}^2) \\ &= B[F_m, F_m; t] + B[P_m W_1, F_m; t] + D[G_m, G_m; t] + D[P_m W_2, G_m; t] + \|F_m(t)\|_{L^2(\mathcal{O})}^2 \\ &\quad + (P_m W_1, F_m) - \alpha(G_m(t) + P_m W_2, F_m(t)) + (\gamma(F_m + P_m W_1)(G_m + P_m W_2), F_m) \\ &\quad - ((F_m + P_m W_1)^3, F_m) + ((F_m + P_m W_1), G_m) - (\beta P_m W_2, G_m) - \beta \|G_m\|_{L^2(\mathcal{O})}^2 \\ &\quad + (R_1, F_m) + (R_2, G_m), \quad \forall t \in [0, T_m], \mathbb{P}\text{-a.s. } \omega \in \Omega. \end{aligned}$$

Combing Lemma 3.1 with (3.4) and (3.5) guarantees that there exists a positive constant δ , which depends only on T such that $\forall t \in [0, T_m], \mathbb{P}\text{-a.s. } \omega \in \Omega$,

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} (\|F_m\|_{L^2(\mathcal{O})}^2 + \|G_m\|_{L^2(\mathcal{O})}^2) + \delta (d_1 \|F_m(t)\|_{H_0^1(\mathcal{O})}^2 + d_2 \|G_m(t)\|_{H_0^1(\mathcal{O})}^2) \\ &\leq M_b \|F_m\|_{L^2(\mathcal{O})}^2 \|F_m(t)\|_{H_0^1(\mathcal{O})}^2 + d_1 M_a \|P_m W_1(t)\|_{H_0^1(\mathcal{O})}^2 \|F_m\|_{H_0^1(\mathcal{O})}^2 \\ &\quad + M_b \|P_m W_1(t)\|_{H_0^1(\mathcal{O})}^2 \|F_m\|_{L^2(\mathcal{O})}^2 + M_c \|G_m\|_{L^2(\mathcal{O})}^2 \|G_m(t)\|_{H_0^1(\mathcal{O})}^2 \\ &\quad + d_2 M_a \|P_m W_2(t)\|_{H_0^1(\mathcal{O})}^2 \|G_m\|_{H_0^1(\mathcal{O})}^2 + M_c \|P_m W_2(t)\|_{H_0^1(\mathcal{O})}^2 \|G_m\|_{L^2(\mathcal{O})}^2 \\ &\quad + \|F_m(t)\|_{L^2(\mathcal{O})}^2 + (P_m W_1, F_m) - \alpha(G_m(t) + P_m W_2, F_m(t)) \\ &\quad + (\gamma(F_m + P_m W_1)(G_m + P_m W_2), F_m) - ((F_m + P_m W_1)^3, F_m) \\ &\quad + ((F_m + P_m W_1), G_m) - (\beta P_m W_2, G_m) - \beta \|G_m\|_{L^2(\mathcal{O})}^2 + (R_1, F_m) + (R_2, G_m), \end{aligned}$$

where

$$M_a = N \max_{1 \leq j, k \leq N} \|a_{jk}\|_{L^\infty(\mathcal{O} \times [0, T])} \tag{3.8}$$

and

$$M_b = N^{1/2} \max_{1 \leq k \leq N} \|b_k\|_{L^\infty(\mathcal{O} \times [0, T])}, \quad M_c = N^{1/2} \max_{1 \leq k \leq N} \|c_k\|_{L^\infty(\mathcal{O} \times [0, T])}. \tag{3.9}$$

Here, we just consider the following term:

$$\begin{aligned} & (\gamma(F_m + P_m W_1)(G_m + P_m W_2), F_m) - ((F_m + P_m W_1)^3, F_m) \\ &= (\gamma(F_m + P_m W_1)(G_m + P_m W_2), F_m + P_m W_1) - \|F_m\|_{L^4(\mathcal{O})}^4 \\ & \quad - (\gamma(F_m + P_m W_1)(G_m + P_m W_2), P_m W_1) + ((F_m + P_m W_1)^3, P_m W_1) \\ & \leq -\frac{1}{8} \|F_m\|_{L^4(\mathcal{O})}^4 + \frac{1}{2} \|P_m W_1\|_{L^4(\mathcal{O})}^4 + 10\gamma^2 \|G_m\|_{L^2(\mathcal{O})}^2 + 10\gamma^2 \|P_m W_2\|_{L^2(\mathcal{O})}^2. \end{aligned}$$

Then it follows from Cauchy’s inequality that

$$\begin{aligned} & \frac{d}{dt} (\|F_m\|_{L^2(\mathcal{O})}^2 + \|G_m\|_{L^2(\mathcal{O})}^2) + \delta (d_1 \|F_m(t)\|_{H_0^1(\mathcal{O})}^2 + d_2 \|G_m(t)\|_{H_0^1(\mathcal{O})}^2) \\ & \quad + \frac{1}{4} \|F_m + P_m W_1\|_{L^4(\mathcal{O})}^4 \leq M_2 \|F_m(t)\|_{L^2(\mathcal{O})}^2 + M_3 \|G_m(t)\|_{L^2(\mathcal{O})}^2 + R_3(t), \end{aligned} \tag{3.10}$$

where

$$M_2 = \frac{2M_b^2}{d_1\delta} + M_b + 2\alpha + 5, \quad M_3 = \frac{2M_c^2}{d_1\delta} + M_c + \alpha + 20\gamma^2 - \beta + 5,$$

and

$$\begin{aligned} R_3(t) &= \left(\frac{2d_1M_a^2}{\delta} + M_b\right) \|P_m W_1\|_{H_0^1(\mathcal{O})}^2 + \left(\frac{2d_2M_a^2}{\delta} + M_c\right) \|P_m W_2\|_{H_0^1(\mathcal{O})}^2 \\ & \quad + 2\|P_m W_1\|_{L^2(\mathcal{O})}^2 + (\alpha + 20\gamma^2 + \beta) \|P_m W_2\|_{L^2(\mathcal{O})}^2 + \|P_m W_1\|_{L^4(\mathcal{O})}^4 \\ & \quad + \|R_1\|_{L^2(\mathcal{O})}^2 + \|R_2\|_{L^2(\mathcal{O})}^2. \end{aligned}$$

By the fact $\|P_m W_1\|_{H_0^1(\mathcal{O})} \leq \|W_1\|_{H_0^1(\mathcal{O})}$, $\|P_m W_2\|_{H_0^1(\mathcal{O})} \leq \|W_2\|_{H_0^1(\mathcal{O})}$, the assumption (2.5) and the BDG inequality, we can find that $\mathbb{E}R_3(t) < \infty, \forall t \in [0, T_m]$. Then combining (3.10) with the Gronwall inequality and the fact $\|P_m U_0\|_{L^2(\mathcal{O})}^2 \leq \|U_0\|_{L^2(\mathcal{O})}^2, \|P_m V_0\|_{L^2(\mathcal{O})}^2 \leq \|V_0\|_{L^2(\mathcal{O})}^2$, we can find a positive constant M_4 here such that

$$\begin{aligned} & \mathbb{E} \|F_m(t)\|_{L^2(\mathcal{O})}^2 + \mathbb{E} \|G_m(t)\|_{L^2(\mathcal{O})}^2 + \int_0^T \delta (d_1 \mathbb{E} \|F_m(s)\|_{H_0^1(\mathcal{O})}^2 + d_2 \mathbb{E} \|G_m(s)\|_{H_0^1(\mathcal{O})}^2) \\ & \quad + \frac{1}{4} \mathbb{E} \|F_m(s)\|_{L^4(\mathcal{O})}^4 ds \leq M_4, \end{aligned}$$

which implies that Lemma 3.3 holds. □

Lemma 3.4 *The following estimates hold:*

- (3) *the sequence $\{F_m\}$ is bounded in $C^0([0, T]; L^2(\Omega, H_0^1(\mathcal{O}))) \cap L^2(0, T; L^2(\Omega, H^2(\mathcal{O})))$,*
- (4) *the sequence $\{G_m\}$ is bounded in $C^0([0, T]; L^2(\Omega, H_0^1(\mathcal{O}))) \cap L^2(0, T; L^2(\Omega, H^2(\mathcal{O})))$.*

Proof Multiplying (A_m^2) by $\lambda_k \eta_m^k(t, \omega)$ and summing over $k = 1, 2, \dots$, and recalling the fact that $-\Delta_y G_m(t) = \sum_{k=1}^m \lambda_k \eta_m^k(t, \omega) \varpi_k$ equals 0 on $\partial\mathcal{O}$, we obtain from Lemma 3.2

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|G_m(t)\|_{H_0^1(\mathcal{O})}^2 + d_2 \delta_0 \|\Delta G_m(t)\|_{H_0^1(\mathcal{O})}^2 \\ & \leq M_{\varepsilon} \|G_m(t)\|_{H_0^1(\mathcal{O})} \|\Delta G_m(t)\|_{L^2(\mathcal{O})} + d_2 M_a \|\Delta P_m W_2(t)\|_{L^2(\mathcal{O})} \|\Delta G_m(t)\|_{L^2(\mathcal{O})} \end{aligned}$$

$$\begin{aligned}
 &+ M_{\bar{c}} \|P_m W_2(t)\|_{H_0^1(\mathcal{O})} \|\Delta G_m(t)\|_{L^2(\mathcal{O})} + d_2 C_0 |G_m(t)|^2 \\
 &- \int_{\mathcal{O}} (F_m + P_m W_1 - R_2) \Delta G_m + \beta ((\nabla G_m)^2 + \nabla G_m \nabla (P_m W_2)) \, dy,
 \end{aligned}$$

where $M_{\bar{c}} = N^{1/2} \max_{1 \leq k \leq N} |\bar{c}_k|_{L^\infty(\mathcal{O} \times (0, T))}$, and $\bar{c}_k(y, t) := c_k(y, t) + d_2 \sum_{j=1}^N \frac{\partial a_{jk}}{\partial y_j}(y, t)$, $k = 1, 2, \dots, N$.

By Cauchy’s inequality, one derives that

$$\begin{aligned}
 &\frac{d}{dt} \|G_m(t)\|_{H_0^1(\mathcal{O})}^2 + d_2 \delta_0 \|\Delta G_m(t)\|_{L^2(\mathcal{O})}^2 \\
 &\leq \left(\frac{4M_{\bar{c}}^2}{d_2 \delta_0} - \beta \right) \|G_m(t)\|_{H_0^1(\mathcal{O})}^2 + 2d_2 c_0 \|G_m(t)\|_{L^2(\mathcal{O})}^2 \\
 &\quad + \frac{4d_2 M_a^2}{\delta_0} \|\Delta P_m W_2\|_{L^2(\mathcal{O})}^2 \\
 &\quad + \left(\frac{4M_{\bar{c}}^2}{d_2 \delta_0} + \beta \right) \|P_m W_2(t)\|_{H_0^1(\mathcal{O})}^2 \\
 &\quad + \frac{3}{d_2 \delta_0} (\|F_m\|_{L^2(\mathcal{O})}^2 + \|P_m W_1\|_{L^2(\mathcal{O})}^2 + \|R_2\|_{L^2(\mathcal{O})}^2). \tag{3.11}
 \end{aligned}$$

Since $P_m G_0$ is bounded in $H_0^1(\mathcal{O})$, then (2.14), (3.11), Lemma 3.3 and the Gronwall inequality imply that there exists a positive constant M_5 that satisfies

$$\mathbb{E} \|G_m(t)\|_{H_0^1(\mathcal{O})}^2 + d_2 \delta_0 \int_0^T \mathbb{E} \|\Delta G_m(s)\|_{L^2(\mathcal{O})}^2 \, ds \leq M_5.$$

Next, we show the second result in Lemma 3.4. Multiplying (A_m^1) by $\lambda_k \zeta_m^k$, summing over $k = 1, 2, \dots, m$, we get

$$\begin{aligned}
 &\frac{1}{2} \frac{d}{dt} \|F_m(t)\|_{H_0^1(\mathcal{O})}^2 + d_1 \delta_0 \|\Delta F_m(t)\|_{L^2(\mathcal{O})}^2 \\
 &\leq M_{\bar{b}} \|F_m(t)\|_{H_0^1(\mathcal{O})} \|\Delta F_m(t)\|_{L^2(\mathcal{O})} + d_1 M_a \|\Delta P_m W_1(t)\|_{L^2(\mathcal{O})} \|\Delta F_m(t)\|_{L^2(\mathcal{O})} \\
 &\quad + M_{\bar{b}} \|P_m W_1(t)\|_{H_0^1(\mathcal{O})} \|\Delta F_m(t)\|_{L^2(\mathcal{O})} + d_1 C_0 |F_m(t)|^2 + \|F_m(t)\|_{H_0^1(\mathcal{O})}^2 \\
 &\quad - (P_m W_1, \Delta F_m) + \alpha (G_m(t) + P_m W_2, \Delta F_m) \\
 &\quad - (\gamma (F_m + P_m W_1)(G_m + P_m W_2), \Delta F_m) \\
 &\quad - (R_1, \Delta F_m) + ((F_m + P_m W_1)^3, \Delta F_m), \tag{3.12}
 \end{aligned}$$

where $M_{\bar{b}} = N^{1/2} \max_{1 \leq k \leq N} |\bar{b}_k|_{L^\infty(\mathcal{O} \times (\tau, T))}$, and $\bar{b}_k(y, t) := b_k(y, t) + d_1 \sum_{j=1}^N \frac{\partial a_{jk}}{\partial y_j}(y, t)$, $k = 1, 2, \dots, N$. Here, we just consider the last term in (3.12),

$$\begin{aligned}
 &((F_m + P_m W_1)^3, \Delta F_m) \\
 &= ((F_m + P_m W_1)^3, \Delta(F_m + P_m W_1)) - ((F_m + P_m W_1)^3, \Delta(P_m W_1)) \\
 &= -3 \int_{\mathcal{O}} (F_m + P_m W_1)^2 (\nabla(F_m + P_m W_1))^2 \, dy - ((F_m + P_m W_1)^3, \Delta(P_m W_1))
 \end{aligned}$$

$$\begin{aligned} &\leq -((F_m + P_m W_1)^3, \Delta(P_m W_1)) \\ &\leq \frac{3}{4} \|F_m + P_m W_1\|_{L^4(\mathcal{O})}^4 + \frac{1}{4} \|\Delta(P_m W_1)\|_{L^4(\mathcal{O})}^4. \end{aligned}$$

The Cauchy inequality implies that

$$\begin{aligned} &\frac{d}{dt} \|F_m\|_{H^1(\mathcal{O})}^2 + d_1 \delta_0 \|\Delta F_m\|_{L^2(\mathcal{O})}^2 \\ &\leq \left(\frac{4M_b^2}{d_1 \delta_0} + \alpha + 3 \right) \|F_m\|_{H_0^1(\mathcal{O})}^2 + 2d_1 C_0 \|F_m\|_{L^2(\mathcal{O})}^2 + \frac{4d_1 M_a^2}{\delta_0} \|\Delta P_m W_1\|_{L^2(\mathcal{O})}^2 \\ &\quad + \left(\frac{4M_b^2}{d_1 \delta_0} + 1 \right) \|P_m W_1\|_{H_0^1(\mathcal{O})}^2 + \alpha \|G_m + P_m W_2\|_{H_0^1(\mathcal{O})}^2 \\ &\quad + \left(\frac{2\gamma^2}{d_1 \delta_0} + \frac{3}{2} \right) \|F_m + P_m W_1\|_{L^4(\mathcal{O})}^4 \\ &\quad + \frac{2\gamma^2}{d_1 \delta_0} \|G_m + P_m W_2\|_{L^4(\mathcal{O})}^4 + \frac{1}{2} \|\Delta P_m W_1\|_{L^4(\mathcal{O})}^4. \end{aligned}$$

Then for $N \leq 3$, the assumptions (2.5) and (2.14) imply that the second result of Lemma 3.4 holds. □

Lemma 3.5 *The sequences $\{F'_m\}$, $\{G'_m\}$ are bounded in $L^2(0, T; L^2(\Omega, L^2(\mathcal{O})))$.*

Proof Multiplying (A_m^1) by $\zeta_m^{k'}$, summing over $k = 1, 2, \dots, m$, and combining with $a_{k,j} = a_{j,k}$, we have

$$\begin{aligned} &\|F'_m(t)\|_{L^2(\mathcal{O})}^2 + \frac{d_1}{2} \frac{d}{dt} \int_{\mathcal{O}} \sum_{k,j=1}^N a_{k,j}(y, t) \frac{\partial F_m}{\partial y_j}(y, t) \frac{\partial F_m}{\partial y_k}(y, t) dy \\ &\quad - \frac{d_1}{2} \frac{d}{dt} \int_{\mathcal{O}} \sum_{k,j=1}^N \frac{\partial a_{k,j}(y, t)}{\partial t} \frac{\partial F_m}{\partial y_j}(y, t) \frac{\partial F_m}{\partial y_k}(y, t) dy \\ &\leq \frac{7}{8} \|F'_m\|_{L^2(\mathcal{O})}^2 + 2M_a^2 d_1^2 \|P_m W_1\|_{H_0^1(\mathcal{O})}^2 + 2M_b^2 \|F_m + P_m W_1\|_{H_0^1(\mathcal{O})}^2 \\ &\quad + 2 \|F_m + P_m W_1\|_{L^2(\mathcal{O})}^2 + 2\alpha^2 \|G_m + P_m W_2\|_{L^2(\mathcal{O})}^2 \\ &\quad + \gamma^2 (\|F_m + P_m W_1\|_{L^4(\mathcal{O})}^4 + \|G_m + P_m W_2\|_{L^4(\mathcal{O})}^4) \\ &\quad + 2 \|F_m + P_m W_1\|_{L^6(\mathcal{O})}^6 + 2 \|R_1\|_{L^2(\mathcal{O})}^2. \end{aligned}$$

Similarly,

$$\begin{aligned} &\|G'_m(t)\|_{L^2(\mathcal{O})}^2 + \frac{d_2}{2} \frac{d}{dt} \int_{\mathcal{O}} \sum_{k,j=1}^N a_{k,j}(y, t) \frac{\partial G_m}{\partial y_j}(y, t) \frac{\partial G_m}{\partial y_k}(y, t) dy \\ &\quad - \frac{d_2}{2} \frac{d}{dt} \int_{\mathcal{O}} \sum_{k,j=1}^N \frac{\partial a_{k,j}(y, t)}{\partial t} \frac{\partial G_m}{\partial y_j}(y, t) \frac{\partial G_m}{\partial y_k}(y, t) dy \\ &\leq \frac{5}{8} \|G'_m\|_{L^2(\mathcal{O})}^2 + 2M_a^2 d_2^2 \|P_m W_2\|_{H_0^1(\mathcal{O})}^2 + 2M_c^2 \|G_m + P_m W_2\|_{H_0^1(\mathcal{O})}^2 \\ &\quad + 2 \|F_m + P_m W_1\|_{L^2(\mathcal{O})}^2 + 2\beta^2 \|G_m + P_m W_2\|_{L^2(\mathcal{O})}^2 + 2 \|R_2\|_{L^2(\mathcal{O})}^2. \end{aligned}$$

Noticing the fact that $a_{k,j} \in C^1(\bar{\mathcal{O}} \times [\tau, T])$ ($k = 1, 2, \dots, N$), $P_m F_0, P_m G_0$ are bounded in $H_0^1(\mathcal{O})$, $N \leq 3$, we deduce that Lemma 3.5 holds. \square

Theorem 3.1 *Assume that r and \bar{r} satisfy the assumptions (2.1), (2.2), (2.3), and*

$$\partial\mathcal{O} \text{ is } C^m \quad \text{where } m \geq 2. \tag{3.13}$$

Then for any $(u_0, v_0) \in H_0^1(\mathcal{O}_0) \times H_0^1(\mathcal{O}_0)$, $\{\phi_j(y)\}_{j=1,2,\dots}$, $\{\psi_j(y)\}_{j=1,2,\dots}$ satisfy the assumption (2.14), and for any $0 \leq T < +\infty$, there exists a unique strong solution (F, G) of (3.1). Moreover, (F, G) satisfies the equality of energy, for \mathbb{P} -a.s. $\omega \in \Omega$,

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|F\|_{L^2(\mathcal{O})}^2 + \int_0^T \int_{\mathcal{O}} d_1 \sum_{j,k=1}^N (a_{jk}(F + W_1)_{y_k}) F_{y_j} + (F + W_1)b \cdot \nabla_y F \, dy \, dt \\ &= \int_0^T \int_{\mathcal{O}} [(F + W_1) - \alpha(G + W_2) + \gamma(F + W_1)(G + W_2) \\ & \quad - (F + W_1)^3 + R_1] F \, dy \, dt, \end{aligned} \tag{3.14}$$

and

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|G\|_{L^2(\mathcal{O})}^2 + \int_0^T \int_{\mathcal{O}} d_2 \sum_{j,k=1}^N (a_{jk}(G + W_2)_{y_k}) G_{y_j} + (G + W_2)c \cdot \nabla_y G \, dy \, dt \\ &= \int_0^T \int_{\mathcal{O}} [(F + W_1) - \beta(G + W_2) + R_2] G \, dy \, dt, \quad \forall t \in [0, T]; \end{aligned} \tag{3.15}$$

and the following estimates, for \mathbb{P} -a.s. $\omega \in \Omega$:

$$\|F(t)\|_{L^2(\mathcal{O})}^2 + \|G(t)\|_{L^2(\mathcal{O})}^2 \leq e^{Mt} (\|F_0\|_{L^2(\mathcal{O})}^2 + \|G_0\|_{L^2(\mathcal{O})}^2) + \int_0^t e^{Ms} R \, ds, \tag{3.16}$$

$$\begin{aligned} & \delta \int_0^t (d_1 \|F\|_{H_0^1(\mathcal{O})}^2 + d_2 \|G\|_{H_0^1(\mathcal{O})}^2) \, ds \\ & \leq e^{Mt} (\|F_0\|_{L^2(\mathcal{O})}^2 + \|G_0\|_{L^2(\mathcal{O})}^2) + \int_0^t e^{Ms} R \, ds, \end{aligned} \tag{3.17}$$

where M is a constant and R is a fixed random function which satisfies, for \mathbb{P} -a.s. $\omega \in \Omega$, $R(t) \in L^1(0, T)$.

Proof We first prove the uniqueness of the solution. Let $(u_{i0}, v_{i0}) \in H_0^1(\mathcal{O}_0) \times H_0^1(\mathcal{O}_0)$ and $(F_i(t), G_i(t))$, $i = 1, 2$ be the corresponding strong solutions, then we derive

$$\begin{aligned} \frac{\partial(U_1 - U_2)}{\partial t} &= d_1 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(U_1 - U_2)_{y_k}) + b \cdot \nabla_y (U_1 - U_2) + (U_1 - U_2) \\ & \quad - \alpha(V_1 - V_2) + \gamma(U_1 - U_2)(V_1 - V_2) - ((U_1)^3 - (U_2)^3), \end{aligned} \tag{3.18}$$

$$\begin{aligned} \frac{\partial(V_1 - V_2)}{\partial t} &= d_2 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(V_1 - V_2)_{y_k}) + c \cdot \nabla_y (V_1 - V_2) + (U_1 - U_2) \\ & \quad - \beta(V_1 - V_2). \end{aligned} \tag{3.19}$$

Taking the inner product of (3.18) with $(U_1 - U_2)$ and (3.19) with $\alpha(V_1 - V_2)$ in $L^2(\mathcal{O}_t)$, we obtain, \mathbb{P} -a.s. $\omega \in \Omega$,

$$\begin{aligned} & \frac{d}{dt} \left(\|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \alpha \|V_1 - V_2\|_{L^2(\mathcal{O})}^2 \right) \\ & \quad + d_1 \delta \|\nabla_y(U_1 - U_2)\|_{L^2(\mathcal{O})}^2 + \alpha d_2 \delta \|\nabla_y(V_1 - V_2)\|_{L^2(\mathcal{O})}^2 \\ & \leq \left(2 + \frac{M_b^2}{d_1 \delta} \right) \|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \alpha \left(\frac{M_c^2}{d_2 \delta} - 2\beta \right) \|V_1 - V_2\|_{L^2(\mathcal{O})}^2 \\ & \quad + 2 \int_{\mathcal{O}} \gamma (U_1(V_1 - V_2) + V_2(U_1 - U_2)) \, dy, \end{aligned} \tag{3.20}$$

where M_b, M_c are defined by (3.9).

Thanks to the Hölder inequality

$$\begin{aligned} & \int_{\mathcal{O}} (U_1(V_1 - V_2) + V_2(U_1 - U_2)) \, dy \\ & \leq \|U_1\|_{L^4(\mathcal{O})} \|V_1 - V_2\|_{L^4(\mathcal{O})} \|U_1 - U_2\|_{L^2(\mathcal{O})} \\ & \quad + \|V_2\|_{L^4(\mathcal{O})} \|U_1 - U_2\|_{L^4(\mathcal{O})} \|V_1 - V_2\|_{L^2(\mathcal{O})}. \end{aligned} \tag{3.21}$$

Since (F_1, G_1) and (F_2, G_2) are strong solutions of (3.1), $U_1, V_2 \in H_0^1(\mathcal{O}), \forall t \in [\tau, T]$, and there exists a constant M such that $\|U_1\|_{H_0^1(\mathcal{O})} \leq M$ and $\|V_2\|_{H_0^1(\mathcal{O})} \leq M$. Applying the Sobolev embedding theorem, Cauchy’s inequality, and (3.21), we have

$$\begin{aligned} & \int_{\mathcal{O}} \gamma (U_1(V_1 - V_2) + V_2(U_1 - U_2)) \, dy \\ & \leq \frac{d_1 \delta}{4} \|U_1 - U_2\|_{H_0^1(\mathcal{O})}^2 + \frac{\alpha d_2 \delta}{4} \|V_1 - V_2\|_{H_0^1(\mathcal{O})}^2 \\ & \quad + \tilde{M} (\|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \|V_1 - V_2\|_{L^2(\mathcal{O})}^2), \end{aligned} \tag{3.22}$$

where \tilde{M} is a constant dependent on $d_1, d_2, M, \alpha, \gamma, \delta$, and the Sobolev embedding constant.

Combining (3.22) with (3.20) yields

$$\begin{aligned} & \frac{d}{dt} \left(\|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \alpha \|V_1 - V_2\|_{L^2(\mathcal{O})}^2 \right) + \frac{d_1 \delta}{2} \|U_1 - U_2\|_{H_0^1(\mathcal{O})}^2 \\ & \quad + \frac{\alpha d_2 \delta}{2} \|V_1 - V_2\|_{H_0^1(\mathcal{O})}^2 \\ & \leq M_1 (\|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \|V_1 - V_2\|_{L^2(\mathcal{O})}^2), \end{aligned} \tag{3.23}$$

where $M_1 = \max\{1, \frac{1}{\alpha}\} * \max\{2\tilde{M} + (2 + \frac{M_b^2}{d_1 \delta}), 2\tilde{M} + \alpha(\frac{M_c^2}{d_2 \delta} - 2\beta)\}$.

Due to the Gronwall lemma and the fact $u_{10}(x) - u_{20}(x) = v_{10}(x) - v_{20}(x) = 0, F_1 - F_2 = U_1 - U_2, G_1 - G_2 = V_1 - V_2$, we obtain the uniqueness of the strong solution for (3.1) immediately. Taking the inner product of (3.1) with (U, V) , we can obtain the energy equality (3.14) and (3.15) immediately.

Based on the estimates in Lemma 3.3, Lemma 3.4, and Lemma 3.5 on F_m and G_m , there exist a subsequence of $\{F_m(\omega)\}$ and a subsequence of $\{G_m(\omega)\}$ converging weakly in

$L^2((0, T] \times; H^2(\mathcal{O}))$, weakly star in $L^\infty(0, T; H_0^1(\mathcal{O}))$, and strongly in $L^2((0, T]; H_0^1(\mathcal{O}))$, for \mathbb{P} -a.s. $\omega \in \Omega$. Moreover, the extremities $F(\omega), G(\omega)$ are \mathcal{F} -adapted processes and satisfy

$$F \in L^2(\Omega, L^2(\tau, T; H^2(\mathcal{O}))) \cap L^2(\Omega, C([\tau, T]; H_0^1(\mathcal{O}))),$$

$$F' \in L^2(\Omega, L^2(\tau, T; L^2(\mathcal{O}))),$$

and

$$G \in L^2(\Omega, L^2(\tau, T; H^2(\mathcal{O}))) \cap L^2(\Omega, C([\tau, T]; H_0^1(\mathcal{O}))),$$

$$G' \in L^2(\Omega, L^2(\tau, T; L^2(\mathcal{O}))).$$

Thus, $\{(F_m, G_m)\}$ converges to (F, G) in the sense of mean-square.

Therefore, it follows that, for \mathbb{P} -a.s. $\omega \in \Omega$,

$$\begin{aligned} & \frac{d}{dt} (\|F\|_{L^2(\mathcal{O})}^2 + \|G\|_{L^2(\mathcal{O})}^2) + \delta(d_1 \|F(t)\|_{H_0^1(\mathcal{O})}^2 + d_2 \|G(t)\|_{H_0^1(\mathcal{O})}^2) + \frac{7}{8} \|F\|_{L^4(\mathcal{O})}^4 \\ & \leq M_2 \|F(t)\|_{L^2(\mathcal{O})}^2 + M_3 \|G(t)\|_{L^2(\mathcal{O})}^2 + R(t), \end{aligned}$$

where

$$\begin{aligned} R(t) = & (2d_1 M_a^2 + M_b) \|W_1\|_{H_0^1(\mathcal{O})}^2 + (2d_2 M_a^2 + M_c) \|W_2\|_{H_0^1(\mathcal{O})}^2 + 2 \|W_1\|_{L^2(\mathcal{O})}^2 \\ & + (\alpha + 4\gamma^2 + \beta) \|W_2\|_{L^2(\mathcal{O})}^2 + \left(\frac{\gamma}{2} + 2\gamma^4 + 348\right) \|W_1\|_{L^4(\mathcal{O})}^4 \\ & + \frac{\gamma}{2} \|W_2\|_{L^4(\mathcal{O})}^4 + \|R_1\|_{L^2(\mathcal{O})}^2 + \|R_2\|_{L^2(\mathcal{O})}^2. \end{aligned}$$

Denote $M = \max\{M_2, M_3\}$; the Gronwall inequality implies Theorem 3.1 holds. □

4 Existence of the weak solution

In this section, we will show the existence of the weak solution for SBS.

Denote

$$\begin{aligned} \mathcal{U}_{\tau, T} := & \{ \vartheta \in L^2(0, T; H_0^1(\mathcal{O})) \cap L^4(0, T; L^4(\mathcal{O})) : \vartheta' \in L^2(0, T; L^2(\mathcal{O})), \\ & \vartheta(0) = \vartheta(T) = 0 \}. \end{aligned}$$

Definition 4.1 For any given initial data $(u_0, v_0) \in (L^2(\mathcal{O}_0))^2$, $0 \leq T < +\infty$, a function (F, G) is called a weak solution of (3.1) if the following conditions hold. \mathbb{P} -a.s. $\omega \in \Omega$,

- (1) $F \in C([0, T]; L^2(\mathcal{O})) \cap L^2([0, T]; H_0^1(\mathcal{O})) \cap L^4(0, T; L^4(\mathcal{O}))$,
 $G \in C([0, T]; L^2(\mathcal{O})) \cap L^2([0, T]; H_0^1(\mathcal{O}))$ with
 $(F(0), G(0)) = (u_0(r(y, 0)) + W_1(0), v_0(r(y, 0)) + W_2(0))$.
- (2) There exists a sequence of regular data $(F_{0,m}, G_{0,m}) \in H_0^1(\mathcal{O}) \times H_0^1(\mathcal{O})$, $m = 1, 2, \dots$,
such that $(F_{0,m}, G_{0,m}) \rightarrow (F_0, G_0)$ in $L^2(\mathcal{O}) \times L^2(\mathcal{O})$ and $(F_m, G_m) \rightarrow (F, G)$ in
 $C([0, T]; L^2(\mathcal{O} \times \Omega)) \times C([0, T]; L^2(\mathcal{O} \times \Omega))$.

(3) It follows that, for all $\vartheta \in \mathcal{U}_{0,T}$,

$$\begin{aligned} & \int_0^T \int_{\mathcal{O}} -F\vartheta' + d_1 \sum_{j,k=1}^N (a_{jk}(F + W_1)_{,jk}) \vartheta_{,yj} + (F + W_1)b \cdot \nabla_y \vartheta \, dy \, dt \\ &= \int_0^T \int_{\mathcal{O}} [(F + W_1) - \alpha(G + W_2) + \gamma(F + W_1)(G + W_2) \\ &\quad - (F + W_1)^3 + R_1] \vartheta \, dy \, dt \end{aligned} \tag{4.1}$$

and

$$\begin{aligned} & \int_0^T \int_{\mathcal{O}} -G\vartheta' + d_2 \sum_{j,k=1}^N (a_{jk}(G + W_2)_{,jk}) \vartheta_{,yj} + (G + W_2)c \cdot \nabla_y \vartheta \, dy \, dt \\ &= \int_0^T \int_{\mathcal{O}} [(F + W_1) - \beta(G + W_2) + R_2] \vartheta \, dy \, dt. \end{aligned} \tag{4.2}$$

It is easy to find that every strong solution is a weak solution of (3.1) from the definition.

Theorem 4.1 *Let the function r and \bar{r} satisfy assumptions (2.1)-(2.3). Assume that $\partial\mathcal{O}$ is C^m $m \geq 2$. Then for any $(F_0, G_0) \in L^2(\mathcal{O}) \times L^2(\mathcal{O})$ and $0 \leq T < +\infty$, there exists a unique weak solution (F, G) of (3.1). Moreover, (F, G) satisfies the equality of energy, for \mathbb{P} -a.s. $\omega \in \Omega$,*

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|F\|_{L^2(\mathcal{O})}^2 + \int_0^T \int_{\mathcal{O}} d_1 \sum_{j,k=1}^N (a_{jk}(F + W_1)_{,jk}) F_{,yj} + (F + W_1)b \cdot \nabla_y F \, dy \, dt \\ &= \int_0^T \int_{\mathcal{O}} [(F + W_1) - \alpha(G + W_2) + \gamma(F + W_1)(G + W_2) \\ &\quad - (F + W_1)^3 + R_1] F \, dy \, dt, \quad \forall t \in [0, T]; \\ & \frac{1}{2} \frac{d}{dt} \|G\|_{L^2(\mathcal{O})}^2 + \int_0^T \int_{\mathcal{O}} d_2 \sum_{j,k=1}^N (a_{jk}(G + W_2)_{,jk}) G_{,yj} + (G + W_2)c \cdot \nabla_y G \, dy \, dt \\ &= \int_0^T \int_{\mathcal{O}} [(F + W_1) - \beta(G + W_2) + R_2] G \, dy \, dt, \quad \forall t \in [0, T], \end{aligned}$$

and the following estimates, for \mathbb{P} -a.s. $\omega \in \Omega$:

$$\|F(t)\|_{L^2(\mathcal{O})}^2 + \|G(t)\|_{L^2(\mathcal{O})}^2 \leq e^{Mt} (\|F_0\|_{L^2(\mathcal{O})}^2 + \|G_0\|_{L^2(\mathcal{O})}^2) + \int_0^t e^{Ms} R \, ds, \tag{4.3}$$

$$\delta \int_0^t (d_1 \|F\|_{H_0^1(\mathcal{O})}^2 + d_2 \|G\|_{H_0^1(\mathcal{O})}^2) \, ds \leq e^{Mt} (\|F_0\|_{L^2(\mathcal{O})}^2 + \|G_0\|_{L^2(\mathcal{O})}^2) + \int_0^t e^{Ms} R \, ds, \tag{4.4}$$

where M and R are defined in the proof of Theorem 3.1.

Proof We first of all show the uniqueness of weak solutions for (3.1). Let (F_1, G_1) and (F_2, G_2) be weak solutions for (3.1) with the initial value $(u_{0,1}, v_{0,1})$ and $(u_{0,2}, v_{0,2})$, respec-

tively, then

$$\begin{aligned}
 (B_1) \quad \frac{\partial(U_1 - U_2)}{\partial t} &= d_1 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(U_1 - U_2)_{y_k}) + b \cdot \nabla_y(U_1 - U_2) + (U_1 - U_2) \\
 &\quad - \alpha(V_1 - V_2) + \gamma(U_1 - U_2)(V_1 - V_2) - ((U_1)^3 - (U_2)^3), \\
 (B_2) \quad \frac{\partial(V_1 - V_2)}{\partial t} &= d_2 \sum_{j,k=1}^N \frac{\partial}{\partial y_j} (a_{jk}(V_1 - V_2)_{y_k}) + c \cdot \nabla_y(V_1 - V_2) + (U_1 - U_2) \\
 &\quad - \beta(V_1 - V_2).
 \end{aligned}$$

Taking the inner product of (B_2) with $V_1 - V_2$ in $L^2(\mathcal{O})$ and using Lemma 3.1 and Cauchy’s inequality, we obtain

$$\begin{aligned}
 &\frac{d}{dt} \|V_1 - V_2\|_{L^2(\mathcal{O})}^2 + d_2 \delta \| (V_1 - V_2) \|_{H_0^1(\mathcal{O})}^2 \\
 &\leq \left(\frac{M_c^2}{d_2 \delta} - 2\beta + 1 \right) \|V_1 - V_2\|_{L^2(\mathcal{O})}^2 + \|U_1 - U_2\|_{L^2(\mathcal{O})}^2,
 \end{aligned} \tag{4.5}$$

where M_c is defined in the proof of Theorem 3.1.

Taking the inner product of (B_1) with $U_1 - U_2$ in $L^2(\mathcal{O})$ and using Lemma 3.1 and Cauchy’s inequality again, we can get

$$\begin{aligned}
 &\frac{d}{dt} \|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + d_1 \delta \| (U_1 - U_2) \|_{H_0^1(\mathcal{O})}^2 \\
 &\leq \left(\frac{M_b^2}{d_1 \delta} + 2 \right) \|U_1 - U_2\|_{L^2(\mathcal{O})}^2 \\
 &\quad + 2 \int_{\mathcal{O}} (-\alpha(V_1 - V_2) + \gamma(U_1 V_1 - U_2 V_2) - (U_1^3 - U_2^3))(U_1 - U_2) \, dy \\
 &\leq \left(\frac{M_b^2}{d_1 \delta} + \alpha + 2 \right) \|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \alpha \|V_1 - V_2\|_{L^2(\mathcal{O})}^2 \\
 &\quad + 2 \int_{\mathcal{O}} \gamma(U_1 V_1 - U_2 V_2)(U_1 - U_2) \, dy.
 \end{aligned} \tag{4.6}$$

Notice that $U_1, U_2 \in C(0, T; L^2(\mathcal{O}))$, then there exists a constant M_u such that $|U_1|_t^2 + |U_2|_t^2 \leq M_u, \forall t \in (0, T)$, and

$$\begin{aligned}
 &\int_{\mathcal{O}} (\gamma(U_1 V_1 - U_2 V_2))(U_1 - U_2) \, dy \\
 &= \int_{\mathcal{O}} \gamma U_1 (V_1 - V_2)(U_1 - U_2) + V_2 (U_1 - U_2)^2 \, dy \\
 &\leq \gamma M_u \|V_1 - V_2\|_{L^4(\mathcal{O})} \|U_1 - U_2\|_{L^4(\mathcal{O})} + \gamma \|V_2\|_{L^4(\mathcal{O})} \|U_1 - U_2\|_{L^2(\mathcal{O})}^2 \|U_1 - U_2\|_{L^4(\mathcal{O})}.
 \end{aligned}$$

Hence, there exists a constant C_N such that

$$\begin{aligned}
 &\int_{\mathcal{O}} (\gamma(U_1 V_1 - U_2 V_2))(U_1 - U_2) \, dy \\
 &\leq \gamma M_u C_N^2 \|V_1 - V_2\|_{H_0^1(\mathcal{O})} \|U_1 - U_2\|_{H_0^1(\mathcal{O})}
 \end{aligned}$$

$$\begin{aligned} & + \gamma C_N^2 \|V_2\|_{H_0^1(\mathcal{O})} \|U_1 - U_2\|_{L^2(\mathcal{O})} \|U_1 - U_2\|_{H_0^1(\mathcal{O})} \\ \leq & \frac{d_1 \delta}{4} \|U_1 - U_2\|_{H_0^1(\mathcal{O})}^2 + \frac{2M_u^2 C_N^4}{d_1 \delta} \|V_1 - V_2\|_{H_0^1(\mathcal{O})}^2 \\ & + \frac{2\gamma^2 C_N^4 \|V_2\|_{H_0^1(\mathcal{O})}^2}{d_1 \delta} \|U_1 - U_2\|_{L^2(\mathcal{O})}^2. \end{aligned}$$

Combining the above inequality with (4.5) and (4.6), we obtain

$$\frac{d}{dt} \left(\|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \frac{8M_u^2 C_N^4}{d_1 d_2 \delta^2} \|V_1 - V_2\|_{L^2(\mathcal{O})}^2 \right) \leq \bar{M} (\|U_1 - U_2\|_{L^2(\mathcal{O})}^2 + \|V_1 - V_2\|_{L^2(\mathcal{O})}^2),$$

where

$$\bar{M}(t) = \frac{4\gamma^2 C_N^4 \|V_2(t)\|_{H_0^1(\mathcal{O})}^2}{d_1 \delta} + \frac{M_b^2}{d_1 \delta} + \alpha + 2 + \left(\frac{M_c^2}{d_2 \delta} + 1 \right) * \frac{8M_u^2 C_N^4}{d_1 d_2 \delta^2}.$$

Recalling that $V_1, V_2 \in L^2(0, T; H_0^1(\mathcal{O}))$, so $\int_0^T \bar{M}(s) dt < \infty$. Thus we can obtain uniqueness immediately from the above inequality, the Gronwall inequality, and the fact $F_1 - F_2 = U_1 - U_2, G_1 - G_2 = V_1 - V_2, u_{10} = u_{20}, v_{10} = v_{20}$.

Next, we will show the existence of a weak solution. Let $F_{0,m}, G_{0,m} \in H_0^1(\mathcal{O}), m = 1, 2, \dots$, such that

$$F_{0,m} \rightarrow F_0 \quad \text{in } L^2(\mathcal{O}), \text{ as } m \rightarrow \infty, \tag{4.7}$$

$$G_{0,m} \rightarrow G_0 \quad \text{in } L^2(\mathcal{O}), \text{ as } m \rightarrow \infty. \tag{4.8}$$

Then for each $F_{0,m}, G_{0,m}, m = 1, 2, \dots$, there exists a unique strong solution (F_m, G_m) for (3.1). We deduce from (3.16) and (3.17) that, for \mathbb{P} -a.s. $\omega \in \Omega$,

$$\{F_m\} \text{ is bounded in } C([0, T]; L^2(\mathcal{O})) \cap L^2(0, T, H_0^1(\mathcal{O})) \cap L^4(0, T; L^4(\mathcal{O})) \tag{4.9}$$

and

$$\{G_m\} \text{ is bounded in } C([0, T]; L^2(\mathcal{O})) \cap L^2(0, T, H_0^1(\mathcal{O})), \tag{4.10}$$

which implies that

$$\text{the sequence } \{\gamma F_m G_m - F_m^3\} \text{ is bounded in } L^{4/3}(0, T; L^{4/3}(\mathcal{O})). \tag{4.11}$$

Therefore, we can extract a subsequence (denoted also by $\{(F_m, G_m)\}$) such that \mathbb{P} -a.s. $\omega \in \Omega$

$$F_m \rightharpoonup F \quad \text{weakly in } L^2(0, T; H_0^1(\mathcal{O})), \tag{4.12}$$

$$G_m \rightharpoonup G \quad \text{weakly in } L^2(0, T; H_0^1(\mathcal{O})), \tag{4.13}$$

$$\gamma F_m G_m - F_m^3 \rightharpoonup \Phi \quad \text{weakly in } L^{4/3}(0, T; L^{4/3}(\mathcal{O})). \tag{4.14}$$

Combining the arguments of the uniqueness and the fact (4.7), (4.8), which implies that $\{F_m\}$ and $\{G_m\}$ are Cauchy sequences in $C([0, T]; L^2(\mathcal{O} \times \Omega))$, the uniqueness of the limit and (4.12)-(4.13) yield, for \mathbb{P} -a.s. $\omega \in \Omega$,

$$\begin{aligned} F_m &\rightarrow F \quad \text{in } C([0, T]; L^2(\mathcal{O})) \quad \text{and} \\ G_m &\rightarrow G \quad \text{in } C([0, T]; L^2(\mathcal{O})), \quad \text{as } m \rightarrow \infty. \end{aligned} \tag{4.15}$$

Therefore, extracting a subsequence if necessary, we can assume that $\gamma F_m G_m - F_m^3 \rightarrow \gamma FG - F^3$, a.e. in $\mathcal{O} \times [0, T]$ as $m \rightarrow \infty$. Then (4.14) implies that $\Phi = \gamma FG - F^3$. Meanwhile, for any test function $\vartheta \in \mathcal{U}_{0,T}$, (F_m, G_m) satisfies (4.1) and (4.2). By using (4.12), (4.13), (4.14), and (4.15), and passing to the limit, we see that (F, G) also satisfies (4.1) and (4.2). The estimates (4.3) and (4.4) can be obtained from (3.16), (3.17), (4.7), (4.8), and (4.15) directly. Thus, we can see (F, G) is a weak solution of (3.1) with initial (u_0, v_0) by all arguments above. Then the proof of Theorem 4.1 is completed. \square

Remark 4.1 Since $(F, G) \in (L^2(0, T; H_0^1(\mathcal{O})))^2$, for any $t \in (\tau, T)$, \mathbb{P} -a.s. $\omega \in \Omega$, it follows that there exists an earlier time $t_0 \in (0, t)$ satisfying that $(F, G) \in (H_0^1(\mathcal{O}))^2$, which implies that the weak solutions of (3.1) turn into the strong solutions after a null measure set (τ, t_0) . Hence, we obtain $(F', G') \in L^2(0, T; L^2(\mathcal{O})) \times L^2(0, T; L^2(\mathcal{O}))$ and $(F, G) \in C(0, T; L^2(\mathcal{O})) \times C(0, T; L^2(\mathcal{O}))$.

Definition 4.2 A function $(F, G) : \bigcup_{t \in [0, \infty)} \mathcal{O} \times t \rightarrow \mathbb{R}^2$ is called a weak solution of (2.13) if for any $T \geq 0$, the restriction of (F, G) on $\bigcup_{t \in [0, T)} \mathcal{O} \times t$ is a weak solution of (3.1).

Repeating arguments similar to Theorem 4.1, we obtain the following result.

Theorem 4.2 Under the same assumptions of Theorem 3.1, for any $(u_0, v_0) \in L^2(\mathcal{O}_0) \times L^2(\mathcal{O}_0)$, (2.13) has a unique weak solution.

5 The non-autonomous pullback \mathcal{D}_σ -attractor for SBS

In this section, we will establish some priori estimates for the solutions of (2.13), and introduce the ‘partial-random’ dynamical system generated by weak solution. By following the argument in [8], we prove the existence of the non-autonomous pullback \mathcal{D}_σ -attractor for the system.

Assume that (F, G) is a weak solution of (2.13) with initial value (F_0, G_0) . Let

$$\bar{M}_a = N \max_{1 \leq j, k \leq N} \|a_{jk}\|_{L^\infty(\mathcal{O} \times \mathbb{R})}, \tag{5.1}$$

$$\bar{M}_b = N^{1/2} \max_{1 \leq k \leq N} \|b_k\|_{L^\infty(\mathcal{O} \times \mathbb{R})}, \quad \bar{M}_c = N^{1/2} \max_{1 \leq k \leq N} \|c_k\|_{L^\infty(\mathcal{O} \times \mathbb{R})}, \tag{5.2}$$

and

$$\bar{M}_{\bar{b}} = N^{1/2} \max_{1 \leq k \leq N} \|\bar{b}_k\|_{L^\infty(\mathcal{O} \times \mathbb{R})}, \quad \bar{M}_{\bar{c}} = N^{1/2} \max_{1 \leq k \leq N} \|\bar{c}_k\|_{L^\infty(\mathcal{O} \times \mathbb{R})}, \tag{5.3}$$

where \bar{b}, \bar{c} are defined in the proof of Theorem 3.1. We will also assume that $\bar{M}_a < \infty$, $\bar{M}_b < \infty$, $\bar{M}_c < \infty$, $\bar{M}_{\bar{b}} < \infty$, and $\bar{M}_{\bar{c}} < \infty$.

Lemma 5.1 *There exist two positive constants M, C , and a random process R_4 such that for \mathbb{P} -a.s. $\omega \in \Omega, t \geq \tau$*

$$\begin{aligned} & \|F(t)\|_{L^2(\mathcal{O})}^2 + \|G(t)\|_{L^2(\mathcal{O})}^2 \\ & \leq Me^{-C(t-\tau)} (\|F(\tau)\|_{L^2(\mathcal{O})}^2 + \|G(\tau)\|_{L^2(\mathcal{O})}^2) + \int_{\tau}^t e^{-C(t-s)} R_4(s, \omega) ds. \end{aligned} \tag{5.4}$$

Proof Taking the inner product of the first formula of (2.13) with F and the second formula with G in $L^2(\mathcal{O})$, then using Cauchy’s inequality, Hölder’s inequality, and Lemma 3.1, we can obtain

$$\begin{aligned} & \frac{d}{dt} \|F(t)\|_{L^2(\mathcal{O})}^2 + d_1 \delta \|F(t)\|_{H_0^1(\mathcal{O})}^2 + \|F(t)\|_{L^4(\mathcal{O})}^4 \\ & \leq M_1 \|F(t)\|_{L^2(\mathcal{O})}^2 + M_2 \|G(t)\|_{L^2(\mathcal{O})}^2 + R_5(t, \omega), \end{aligned} \tag{5.5}$$

where $M_1 = \frac{2\bar{M}_b^2}{d_1\delta} + \bar{M}_b + 2\alpha + \gamma + 4, M_2 = \alpha + 5\gamma^2$, and

$$\begin{aligned} R_5(t, \omega) = & \left(\frac{2d_1\bar{M}_a^2}{\delta} + \bar{M}_b \right) \|W_1\|_{H_0^1(\mathcal{O})}^2 + \|W_1\|_{L^2(\mathcal{O})}^2 + (\alpha + 4\gamma^2) \|W_2\|_{L^2(\mathcal{O})}^2 \\ & + \left(\frac{\gamma}{2} + 709 \right) \|W_1\|_{L^4(\mathcal{O})}^4 + \frac{\gamma}{2} \|W_2\|_{L^4(\mathcal{O})}^4 + \|R_1\|_{L^2(\mathcal{O})}^2. \end{aligned}$$

Similarly, we have

$$\frac{d}{dt} \|G(t)\|_{L^2(\mathcal{O})}^2 + d_2 \delta \|G(t)\|_{H_0^1(\mathcal{O})}^2 \leq \|F(t)\|_{L^2(\mathcal{O})}^2 + M_3 \|G(t)\|_{L^2(\mathcal{O})}^2 + R_6(t, \omega), \tag{5.6}$$

where $M_3 = \frac{2\bar{M}_c^2}{d_2\delta} + \bar{M}_c + 4 - \beta$, and

$$R_6(t, \omega) = \left(\frac{2d_2\bar{M}_a^2}{\delta} + \bar{M}_c \right) \|W_1\|_{H_0^1(\mathcal{O})}^2 + \|W_1\|_{L^2(\mathcal{O})}^2 + \beta \|W_2\|_{L^2(\mathcal{O})}^2 + \|R_2\|_{L^2(\mathcal{O})}^2.$$

Choosing $\beta > \max_{\delta} \{ \frac{2\bar{M}_c^2}{d_2\delta} + \bar{M}_c + 4 \}$ such that $M_3 < 0$, and denoting $\tilde{M}_3 = -M_3$. We can derive from (5.5) and (5.6) that

$$\begin{aligned} & \frac{d}{dt} (\|F(t)\|_{L^2(\mathcal{O})}^2 + \bar{C} \|G(t)\|_{L^2(\mathcal{O})}^2) + d_1 \delta \|F(t)\|_{H_0^1(\mathcal{O})}^2 + \bar{C} d_2 \delta \|G(t)\|_{H_0^1(\mathcal{O})}^2 + \|F(t)\|_{L^4(\mathcal{O})}^4 \\ & \leq (M_1 + \bar{C}) \|F(t)\|_{L^2(\mathcal{O})}^2 + (M_2 - \bar{C}\tilde{M}_3) \|G(t)\|_{L^2(\mathcal{O})}^2 + R_5(t, \omega) + \bar{C}R_6(t, \omega). \end{aligned} \tag{5.7}$$

Let $\bar{C} = \frac{2M_2}{\tilde{M}_3}$, then

$$\begin{aligned} & \frac{d}{dt} (\|F(t)\|_{L^2(\mathcal{O})}^2 + \bar{C} \|G(t)\|_{L^2(\mathcal{O})}^2) + d_1 \delta \|F(t)\|_{H_0^1(\mathcal{O})}^2 + \bar{C} d_2 \delta \|G(t)\|_{H_0^1(\mathcal{O})}^2 \\ & \quad + \frac{M_2}{\bar{C}} \|F(t)\|_{L^2(\mathcal{O})}^2 + M_2 \|G(t)\|_{L^2(\mathcal{O})}^2 + \frac{1}{4} \|F(t)\|_{L^4(\mathcal{O})}^4 \\ & \leq \frac{d}{dt} (\|F(t)\|_{L^2(\mathcal{O})}^2 + \bar{C} \|G(t)\|_{L^2(\mathcal{O})}^2) + d_1 \delta \|F(t)\|_{H_0^1(\mathcal{O})}^2 + \bar{C} d_2 \delta \|G(t)\|_{H_0^1(\mathcal{O})}^2 \end{aligned}$$

$$\begin{aligned}
 & + \frac{1}{2} \|F(t)\|_{L^4(\mathcal{O})}^4 + M_2 \|G(t)\|_{L^2(\mathcal{O})}^2 + \frac{M_2^2}{\bar{C}^2} |\mathcal{O}| \\
 & \leq \left(\frac{(M_1 + \bar{C})^2}{2} + \frac{M_2^2}{\bar{C}^2} \right) |\mathcal{O}| + R_5(t, \omega) + \bar{C} R_6(t, \omega).
 \end{aligned} \tag{5.8}$$

Denote

$$R_7(t, \omega) = \left(\frac{(M_1 + \bar{C})^2}{2} + \frac{M_2^2}{\bar{C}^2} \right) |\mathcal{O}| + R_5(t, \omega) + \bar{C} R_6(t, \omega),$$

the inequality (5.8) implies that

$$\begin{aligned}
 & \frac{d}{dt} (\|F(t)\|_{L^2(\mathcal{O})}^2 + \bar{C} \|G(t)\|_{L^2(\mathcal{O})}^2) + \frac{M_2}{\bar{C}} (\|F(t)\|_{L^2(\mathcal{O})}^2 + \bar{C} \|G(t)\|_{L^2(\mathcal{O})}^2) \\
 & + d_1 \delta \|F(t)\|_{H_0^1(\mathcal{O})}^2 + \bar{C} d_2 \delta \|G(t)\|_{H_0^1(\mathcal{O})}^2 + \frac{1}{4} \|F(t)\|_{L^4(\mathcal{O})}^4 \leq R_7(t, \omega).
 \end{aligned} \tag{5.9}$$

From the Gronwall inequality, we see that for \mathbb{P} -a.s. $\omega \in \Omega$

$$\begin{aligned}
 & \|F(t)\|_{L^2(\mathcal{O})}^2 + \bar{C} \|G(t)\|_{L^2(\mathcal{O})}^2 \\
 & \leq e^{-\frac{M_2}{\bar{C}}(t-\tau)} (\|F(\tau)\|_{L^2(\mathcal{O})}^2 + \bar{C} \|G(\tau)\|_{L^2(\mathcal{O})}^2) + \int_{\tau}^t e^{-\frac{M_2}{\bar{C}}(s-\tau)} R_7(s, \omega) ds.
 \end{aligned} \tag{5.10}$$

Denoting $M = \frac{\max\{1, \bar{C}\}}{\min\{1, \bar{C}\}}$, $C = \frac{M_2}{\bar{C}}$ and $R_4(t, \omega) = \frac{1}{\min\{1, \bar{C}\}} R_7(t, \omega)$, the proof is completed. \square

Lemma 5.2 *For any nonrandom bounded set $B \in L^2(\mathcal{O}) \times L^2(\mathcal{O})$, there exists a random time $T_B(\omega) \geq 0$ such that*

$$\|F(t)\|_{L^2(\mathcal{O})}^2 + \|G(t)\|_{L^2(\mathcal{O})}^2 \leq 2 \int_{-\infty}^t e^{-C(t-s)} R_4(s, \omega) ds, \tag{5.11}$$

for \mathbb{P} -a.s. $\omega \in \Omega$, for all $t - \tau \geq T_b(\omega)$, for any $(F(\tau), G(\tau)) \in B$.

Proof It follows from Lemma 5.1 that

$$\begin{aligned}
 & \|F(t)\|_{L^2(\mathcal{O})}^2 + \|G(t)\|_{L^2(\mathcal{O})}^2 \\
 & \leq M e^{-C(t-\tau)} (\|F(\tau)\|_{L^2(\mathcal{O})}^2 + \|G(\tau)\|_{L^2(\mathcal{O})}^2) + \int_{\tau}^t e^{-C(t-s)} R_4(s, \omega) ds.
 \end{aligned}$$

We can obtain from the above inequality that

$$e^{-C(t-\tau)} (\|F(\tau)\|_{L^2(\mathcal{O})}^2 + \|G(\tau)\|_{L^2(\mathcal{O})}^2) \rightarrow 0 \quad \text{as } t - \tau \rightarrow \infty.$$

Then there exists a random time $T_B(\omega)$ such that for $t - \tau \geq T_B(\omega)$

$$e^{-C(t-\tau)} (\|F(\tau)\|_{L^2(\mathcal{O})}^2 + \|G(\tau)\|_{L^2(\mathcal{O})}^2) \leq \int_{-\infty}^t e^{-C(t-s)} R_4(s, \omega) ds.$$

Thus, the proof is completed. \square

Corollary 5.1 *For any nonrandom bounded $B \in L^2(\mathcal{O}) \times L^2(\mathcal{O})$, there exist a random time $T_B(\omega) \geq 0$ such that*

$$\int_t^{t+1} \|F(s)\|_{H_0^1(\mathcal{O})}^2 + \|G(s)\|_{H_0^1(\mathcal{O})}^2 + \|F(t)\|_{L^4(\mathcal{O})}^4 ds \leq \hat{M}, \tag{5.12}$$

for \mathbb{P} -a.s. $\omega \in \Omega$, for all $t - \tau \geq T_B(\omega)$, for any $(F(\tau), G(\tau)) \in B$.

Lemma 5.3 *For any nonrandom bounded $B \in L^2(\mathcal{O}) \times L^2(\mathcal{O})$, there exists a random time $\bar{T}_B(\omega) \geq 0$ and a random constant \tilde{M} , such that*

$$\|F(s)\|_{H_0^1(\mathcal{O})}^2 + \|G(s)\|_{H_0^1(\mathcal{O})}^2 \leq \tilde{M}, \tag{5.13}$$

for \mathbb{P} -a.s. $\omega \in \Omega$, for all $t - \tau \geq T_B(\omega)$, for any $(F(\tau), G(\tau)) \in B$.

Proof Taking the inner product of the second formula in (2.13) with $-\Delta G$ in $L^2(\mathcal{O})$, and using Cauchy’s inequality, Hölder’s inequality, and Lemma 3.2, we obtain

$$\begin{aligned} & \frac{d}{dt} \|G(t)\|_{H_0^1(\mathcal{O})}^2 + d_2 \delta_0 \|\Delta G(t)\|_{L^2(\mathcal{O})}^2 \\ & \leq \left(\frac{4\bar{M}_c^2}{d_2 \delta_0} - \beta \right) \|G(t)\|_{H_0^1(\mathcal{O})}^2 + 2d_2 c_0 \|G(t)\|_{L^2(\mathcal{O})}^2 + \frac{4d_2 \bar{M}_a^2}{\delta_0} \|\Delta W_2\|_{L^2(\mathcal{O})}^2 \\ & \quad + \left(\frac{4\bar{M}_c^2}{d_2 \delta_0} + \beta \right) \|W_2(t)\|_{H_0^1(\mathcal{O})}^2 + \frac{3}{d_2 \delta_0} (\|F\|_{L^2(\mathcal{O})}^2 + \|W_1\|_{L^2(\mathcal{O})}^2 + \|R_2\|_{L^2(\mathcal{O})}^2). \end{aligned} \tag{5.14}$$

Combining the assumptions (2.5), (2.14) with Lemmas 5.1-5.2, we have

$$\begin{aligned} & \int_t^{t+1} 2d_2 c_0 \|G(s)\|_{L^2(\mathcal{O})}^2 + \frac{4d_2 \bar{M}_a^2}{\delta_0} \|\Delta W_2\|_{L^2(\mathcal{O})}^2 + \left(\frac{4\bar{M}_c^2}{d_2 \delta_0} + \beta \right) \|W_2(s)\|_{H_0^1(\mathcal{O})}^2 \\ & \quad + \frac{3}{d_2 \delta_0} (\|F(s)\|_{L^2(\mathcal{O})}^2 + \|W_1\|_{L^2(\mathcal{O})}^2 + \|R_2\|_{L^2(\mathcal{O})}^2) ds < \infty, \end{aligned}$$

for \mathbb{P} -a.s. $\omega \in \Omega$ and for all $t - \tau > T_B(\omega)$. Therefore there exists a constant \tilde{M} such that

$$\|G\|_{H_0^1(\mathcal{O})}^2 \leq \tilde{M}, \tag{5.15}$$

for \mathbb{P} -a.s. $\omega \in \Omega$ and for all $t - \tau > T_B(\omega) + 1$.

Similarly,

$$\begin{aligned} & \frac{d}{dt} \|F\|_{H^1(\mathcal{O})}^2 + d_1 \delta_0 \|\Delta F\|_{L^2(\mathcal{O})}^2 \\ & \leq \left(\frac{4\bar{M}_b^2}{d_1 \delta_0} + \alpha + 3 \right) \|F\|_{H_0^1(\mathcal{O})}^2 + 2d_1 C_0 \|F\|_{L^2(\mathcal{O})}^2 + \frac{4d_1 \bar{M}_a^2}{\delta_0} \|\Delta W_1\|_{L^2(\mathcal{O})}^2 \\ & \quad + \left(\frac{4\bar{M}_b^2}{d_1 \delta_0} + 1 \right) \|W_1\|_{H_0^1(\mathcal{O})}^2 + \alpha \|G + W_2\|_{H_0^1(\mathcal{O})}^2 + \left(\frac{2\gamma^2}{d_1 \delta_0} + \frac{3}{2} \right) \|F + W_1\|_{L^4(\mathcal{O})}^4 \\ & \quad + \frac{2\gamma^2}{d_1 \delta_0} \|G + W_2\|_{L^4(\mathcal{O})}^4 + \frac{1}{2} \|\Delta W_1\|_{L^4(\mathcal{O})}^4. \end{aligned} \tag{5.16}$$

Due to (2.5), (2.14), we have

$$\begin{aligned} & \int_t^{t+1} 2d_1 C_0 \|F\|_{L^2(\mathcal{O})}^2 + \frac{4d_1 \bar{M}_a^2}{\delta_0} \|\Delta W_1\|_{L^2(\mathcal{O})}^2 \\ & + \left(\frac{4\bar{M}_b^2}{d_1 \delta_0} + 1 \right) \|W_1\|_{H_0^1(\mathcal{O})}^2 + \alpha \|G + W_2\|_{H_0^1(\mathcal{O})}^2 \\ & + \left(\frac{2\gamma^2}{d_1 \delta_0} + \frac{3}{2} \right) \|F + W_1\|_{L^4(\mathcal{O})}^4 + \frac{2\gamma^2}{d_1 \delta_0} \|G + W_2\|_{L^4(\mathcal{O})}^4 \\ & + \frac{1}{2} \|\Delta W_1\|_{L^4(\mathcal{O})}^4 ds < \infty, \end{aligned}$$

for \mathbb{P} -a.s. $\omega \in \Omega$ and for all $t - \tau > T_B(\omega) + 1$. Thus, applying the uniform Gronwall lemma to (5.16), we see that there exists a constant \tilde{M} such that

$$\|F\|_{H_0^1(\mathcal{O})}^2 \leq \tilde{M}, \tag{5.17}$$

for \mathbb{P} -a.s. $\omega \in \Omega$ and for all $t - \tau > T_B(\omega) + 2$. Denoting $\tilde{T}_B(\omega) = T_B(\omega) + 2$, we complete the proof. \square

6 Attractors for partial-random dynamical system

In this section, we introduce the partial-random dynamical system generated by a SPDE defined on time-varying domains developed by Crauel *et al.* in [4], and prove the existence of the non-autonomous attractor for partial-random dynamical system.

Assume that the probability space $(\Omega, \mathcal{F}, \mathbb{P})$ with incremental shifts $(\kappa_t)_{t \in \mathbb{R}}$ is a metric dynamical system, \mathfrak{R} is a subset of the topology of space $C_b^1(\mathbb{R}; C_b^2(\bar{\mathcal{O}}; \mathbb{R}^N))$ generated by the domain varying diffeomorphisms r . The transformations $\pi_t : \mathfrak{R} \rightarrow \mathfrak{R}$ defined by $\pi_t r(\cdot + s, \cdot) = r(\cdot + s + t, \cdot)$ for $t \in \mathbb{R}$, form a one-parameter group $(\pi_t)_{t \in \mathbb{R}}$ with

$$\pi_{t+s} = \pi_t \circ \pi_s$$

for all $s, t \in \mathbb{R}$. The product flow, given by

$$(\kappa \times \pi)_t = \kappa_t \times \pi_t : \omega \times \mathfrak{R} \rightarrow \omega \times \mathfrak{R}$$

for $t \in \mathbb{R}$, will be denoted by $(\bar{\kappa}_t)_{t \in \mathbb{R}}$.

For each $(F_0, G_0) \in (L^2(\mathcal{O}))^2$, Theorem 4.2 implies that equations (2.13) have a unique global solution (F, G) . Define the operators

$$\Upsilon(t, (\omega, r)) : L^2(\mathcal{O}) \times L^2(\mathcal{O}) \rightarrow L^2(\mathcal{O}) \times L^2(\mathcal{O}) \tag{6.1}$$

by

$$\Upsilon(t, (\omega, r))(F_0, G_0) = (F(t; (\omega, r), F_0, G_0), G(t; (\omega, r), F_0, G_0)) = (F(t), G(t)). \tag{6.2}$$

Here $(F(t; (\omega, r), F_0, G_0), G(t; (\omega, r), F_0, G_0))$ is defined by unique solution process of (5.9) with initial value (F_0, G_0) and the transform for domains r . From Theorem 4.2, we know

that the definition makes sense. Then the family of operators $\{\Upsilon(t) : 0 \leq t < +\infty\}$ generates a non-autonomous dynamic system, *i.e.*

$$\Upsilon(0, (\omega, r)) = \text{Id}(\text{identity on } L^2(\mathcal{O})) \quad \forall (\omega, r) \in \Omega \times \mathfrak{R}, \tag{6.3}$$

$$\begin{aligned} &\Upsilon(t+s, (\omega, r)) \\ &= \Upsilon(t, \bar{\kappa}_s p(\omega, r)) \circ \Upsilon(s, (\omega, r)) \quad \text{for all } s, t \in [0, \infty) \text{ and } (\omega, r) \in \Omega \times \mathfrak{R}. \end{aligned} \tag{6.4}$$

Now, we can define the attractor of the non-autonomous dynamic system Υ .

Definition 6.1 ([4]) Suppose that \mathcal{D} is a set of maps from $\Omega \times \mathfrak{R}$ to the power set of $L^2(\mathcal{O}) \times L^2(\mathcal{O})$ such that $D(\omega, r)$ is nonempty for every $(\omega, r) \in \Omega \times \mathfrak{R}$ and $D \in \mathcal{D}$. A map A from $\Omega \times \mathfrak{R}$ to the power set of $L^2(\mathcal{O}) \times L^2(\mathcal{O})$ is said to be a \mathcal{D} -attractor if:

- (1) $A(\omega, r)$ is compact for all $(\omega, r) \in \Omega \times \mathfrak{R}$,
- (2) A is invariant in the sense that

$$\Upsilon(t, (\omega, r))A(\omega, r) = \bar{\kappa}_t A(\omega, r)$$

for all $t \in [0, \infty)$ and $(\omega, r) \in \Omega \times \mathfrak{R}$,

- (3) A attracts every $D \in \mathcal{D}$ in the sense that

$$\lim_{t \rightarrow \infty} \text{dist}(\Upsilon(t, \bar{\kappa}_{-t}(\omega, r))D(\bar{\kappa}_{-t}(\omega, r)), A(\omega, r)) = 0$$

for every $D \in \mathcal{D}$.

Here $\text{dist}(A, D)$ is for the Hausdorff semi-distance.

Definition 6.2 ([4]) Suppose that \mathcal{D} is a set of maps from $\Omega \times \mathfrak{R}$ to the power set of $L^2(\mathcal{O}) \times L^2(\mathcal{O})$ such that $D(\omega, r)$ is nonempty for every $(\omega, r) \in \Omega \times \mathfrak{R}$ and $D \in \mathcal{D}$. A map K from $\Omega \times \mathfrak{R}$ to the power set of $L^2(\mathcal{O}) \times L^2(\mathcal{O})$ is said to be a \mathcal{D} -attracting if

$$\lim_{t \rightarrow \infty} \text{dist}(\Upsilon(t, \bar{\kappa}_{-t}(\omega, r))D(\bar{\kappa}_{-t}(\omega, r)), K(\omega, r)) = 0$$

for every $D \in \mathcal{D}$.

Theorem 6.1 ([4]) *The existence of a compact \mathcal{D} -attracting K is equivalent to the existence of a \mathcal{D} -attractor.*

Remark 6.1 From Lemmas 5.2 and 5.3, we can find that there exists a compact \mathcal{D} -attracting K for the non-autonomous dynamic system Υ defined above, attracting bounded subsets of $L^2(\mathcal{O}) \times L^2(\mathcal{O})$. Thus, using Theorem 6.1, we can obtain a unique non-autonomous pullback attractor in $L^2(\mathcal{O}) \times L^2(\mathcal{O})$.

Theorem 6.2 *The partial-random system generated by the random-PDE (2.13) on domain \mathcal{O} has a unique non-autonomous pullback attractor in $L^2(\mathcal{O}) \times L^2(\mathcal{O})$, attracting bounded subsets of $L^2(\mathcal{O}) \times L^2(\mathcal{O})$.*

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors read and approved the final manuscript.

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