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Asymptotical stability of Runge-Kutta for a class of impulsive differential equations

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Abstract

The aim of this paper is to study asymptotical stability of Runge-Kutta methods for a class of linear impulsive differential equations with piecewise continuous arguments. New results about the asymptotical stability region of Runge-Kutta methods for these equations are obtained by the theory of the Padé approximation. Finally, some numerical examples are given to illustrate the theoretical results.

Keywords: asymptotical stability; Runge-Kutta methods; impulsive differential equations; piecewise constant arguments; stability region

1 Introduction

In the past two decades, the theory of impulsive differential equations has been developed rapidly [1–3]. Such equations consist of differential equations with impulse effects and emerge in modeling of real-world problems observed in engineering, physics, biology, *etc.* In addition to these, the theory of numerical methods for impulsive differential equations has also been studied extensively [4–7].

In 1984, Cooke and Wiener studied differential equations without impulses and they noted that such equations were comprehensively related to impulsive and difference equations [8]. Later, the case of discontinuous solutions of differential equations with piecewise continuous arguments was proposed as an open problem by Wiener [9]. On the other hand, it is well known that many biological phenomena involving thresholds, bursting rhythm models in medicine and biology, and optimal control models in economics do exhibit impulsive effects [3]. Recently, the existence and uniqueness, and oscillation of the exactly solutions of impulsive delay differential equations with piecewise constant arguments have been widely studied [10–13]. But to the best of our knowledge, up to now, there are few articles referring to numerical methods for impulsive delay differential equations with piecewise constant arguments.

In this paper, we study the asymptotical stability of Runge-Kutta methods for the following scalar equation:

$$\begin{cases} x'(t) = px(t) + qx([t]), & t \geq 0, t \neq k, k = 1, 2, \dots, \\ \Delta x(k) = rx(k^-), & k = 1, 2, \dots, \\ x(0) = x_0, \end{cases} \quad (1.1)$$

where p, q, r , and x_0 are real constants and $[\cdot]$ denotes the greatest integer function. This paper can be seen not only as the extension of asymptotically stable theory of differential equations with piecewise arguments in [14], but also as the extension of asymptotically stable theory of impulsive ordinary differential equations in [4].

The paper is organized as follows. In Section 2, we obtain the existence, uniqueness, and asymptotical stability of the exact solutions of (1.1). In Section 3, we study the asymptotical stability of the Runge-Kutta methods for (1.1). In Section 4, two special cases of Section 3 are studied, respectively: impulsive differential equations without piecewise constant argument and differential equations with piecewise constant arguments. In Section 5, some numerical examples are given to confirm the theoretical results.

2 Asymptotical stability of the exact solutions

Definition 2.1 (See [10–12, 15]) If a function $x : \mathbb{R}^+ \rightarrow \mathbb{R}$ satisfies the following conditions, it is said to be a solution of (1.1):

- (1) $x(t)$ is continuous for $t \in [0, +\infty)$ with the possible exception of the points $[t] \in [0, \infty)$,
- (2) $x(t)$ is right continuous and has left-hand limit at the points $[t] \in [0, \infty)$,
- (3) $x(t)$ is differentiable and satisfies $x'(t) = px(t) + qx([t])$ for any $t \in \mathbb{R}^+$ with the possible exception of the points $[t] \in [0, \infty)$ where one-sided derivatives exist,
- (4) $x(n)$ satisfies $\Delta x(n) = rx(n^-)$ for $n \in \mathbb{Z}^+$.

Definition 2.2 The zero solution of (1.1) is said to be asymptotically stable, if

$$\lim_{t \rightarrow \infty} x(t) = 0, \tag{2.1}$$

where $x(t)$ is the solution of (1.1) for any initial data x_0 .

By [15], p.179, Theorem 3, and [15], p.183, Theorem 9, we immediately obtain the following theorem.

Theorem 2.3 When $p \neq 0$, on $t \in [0, \infty)$, (1.1) has a unique solution

$$x(t) = m_0(\{t\}) \cdot n_0^{[t]} \cdot x_0,$$

where $\{t\}$ is the fractional part of t and

$$m_0(t) = e^{pt} + \frac{q}{p}(e^{pt} - 1), \quad n_0 = (1+r)m_0(1) = (1+r)\left(e^p + \frac{q}{p}(e^p - 1)\right).$$

When $p = 0$, on $t \in [0, \infty)$, (1.1) also has a unique solution

$$x(t) = (1+r)^{[t]}(1+q)^{[t]}(q\{t\} + 1)x_0.$$

Consequently, when $p \neq 0$, the zero solution of (1.1) is asymptotically stable if and only if

$$\left| (1+r)\left(e^p + \frac{q}{p}(e^p - 1)\right) \right| < 1; \tag{2.2}$$

when $p = 0$, the zero solution of (1.1) is asymptotically stable if and only if

$$|(1+r)(1+q)| < 1. \tag{2.3}$$

We introduce the sets H_0 and H consisting of $(p, q, r) \in \mathbb{R}^3$ which satisfy the condition (2.2) and (2.3), respectively, *i.e.*

$$H_0 = \{(0, q, r) : |(1+r)(1+q)| < 1\},$$

$$H = \left\{ (p, q, r) : p \neq 0 \text{ and } \left| (1+r) \left(e^p + \frac{q}{p}(e^p - 1) \right) \right| < 1 \right\},$$

and we divide the region H into four parts as $p + q \neq 0$:

$$H_1 = \left\{ (p, q, r) : p < 0, e^p < \frac{q}{p+q} \text{ and } (p, q, r) \in H \right\},$$

$$H_2 = \left\{ (p, q, r) : p < 0, e^p > \frac{q}{p+q} \text{ and } (p, q, r) \in H \right\},$$

$$H_3 = \left\{ (p, q, r) : p > 0, e^p < \frac{q}{p+q} \text{ and } (p, q, r) \in H \right\},$$

$$H_4 = \left\{ (p, q, r) : p > 0, e^p > \frac{q}{p+q} \text{ and } (p, q, r) \in H \right\}.$$

3 Runge-Kutta methods for (1.1)

Consider the Runge-Kutta methods for equation (1.1):

$$\begin{cases} x_{k,l+1} = x_{k,l} + h \sum_{i=1}^{\nu} b_i (pY_{k,l}^i + qx_{k,0}), & l = 0, \dots, m-1, k = 0, 1, \dots, \\ Y_{k,l}^i = x_{k,l} + h \sum_{j=1}^{\nu} a_{ij} (pY_{k,l}^j + qx_{k,0}), & l = 0, \dots, m-1, k = 0, 1, \dots, \\ x_{(k+1),0} = (1+r)x_{k,m}, & k = 0, 1, 2, \dots, \\ x_{0,0} = x_0, \end{cases} \tag{3.1}$$

where $h = \frac{\tau}{m}$, $m \geq 1$, m is an integer, h is the stepsize, ν is referred to as the number of stages. The weights are b_i , the abscissas are $c_i = \sum_{j=1}^{\nu} a_{ij}$ and the matrix $A = [a_{ij}]_{i,j=1}^{\nu}$ will be denoted by (A, b, c) .

Definition 3.1 Process (3.1) for equation (1.1) is called asymptotically stable at (p, q, r) if and only if for all $m \geq M$ and $h = \frac{1}{m}$

1. $I - zA$ is invertible where $z = hp$,
2. for any given $x_{k,l}$ ($0 \leq l \leq m$) by relationship (3.1), such that $\lim_{k \rightarrow \infty} X_k = 0$ where $X_k = (x_{k,0}, x_{k,1}, \dots, x_{k,m})$.

Definition 3.2 The set of all pairs (p, q, r) at the process (3.1) for equation (1.1) which is asymptotically stable is called stability region denoted by S .

Theorem 3.3 When $p \neq 0$, the method (3.1) is asymptotically stable if and only if

$$\left| (1+r) \left(R(z)^m + \frac{q}{p}(R(z)^m - 1) \right) \right| < 1,$$

where $R(z) = 1 + zb^T(I - zA)^{-1}e$, $e = (1, 1, \dots, 1)^T$ is a vector of v dimension. On the other hand, when $p = 0$, the consistent Runge-Kutta method (3.1) is asymptotically stable if and only if

$$|(1 + r)(1 + q)| < 1.$$

Proof The Runge-Kutta method (3.1) can be written as

$$\begin{cases} x_{k,l+1} = R(z)x_{k,l} + \frac{q}{p}(R(z) - 1)x_{k,0}, & l = 1, 2, \dots, m - 1, \\ x_{k+1,0} = (1 + r)x_{k,m}, & k = 0, 1, 2, \dots, \end{cases} \tag{3.2}$$

which implies that

$$\begin{cases} x_{k,l} = (R(z)^l + \frac{q}{p}(R(z)^l - 1))x_{k,0}, & l = 1, 2, \dots, m, \\ x_{k+1,0} = (1 + r)x_{k,m}, & k = 0, 1, 2, \dots, \end{cases} \tag{3.3}$$

which also implies that

$$x_{k,l} = \left((1 + r) \left(R(z)^m + \frac{q}{p}(R(z)^m - 1) \right) \right)^k \left(R(z)^l + \frac{q}{p}(R(z)^l - 1) \right) x_{0,0}.$$

Hence when $p \neq 0$, the method (3.1) is asymptotically stable if and only if $|(1 + r)(R(z)^m + \frac{q}{p}(R(z)^m - 1))| < 1$.

On the other hand, the Runge-Kutta method being consistent implies $\sum_{i=1}^v b_i = 1$, which also implies

$$x_{k,l} = ((1 + r)(1 + q))^k (1 + lhq)x_{0,0}, \quad l = 1, 2, \dots, m - 1, k = 0, 1, \dots \tag{3.4}$$

Consequently, when $p = 0$, the consistent Runge-Kutta method (3.1) is asymptotically stable if and only if

$$|(1 + r)(1 + q)| < 1. \tag{3.5} \quad \square$$

Lemma 3.4 *If the same Runge-Kutta method applied to the following test equation:*

$$\begin{cases} y'(t) = py(t), & t \geq 0, \\ y(0) = y_0, \end{cases} \tag{3.5}$$

is convergent (in the following, we always assume this condition holds), then we have $\lim_{m \rightarrow \infty, mh=1} R(z)^m = \lim_{m \rightarrow \infty, mh=1} R(hp)^m = e^p$, where $R(z) = 1 + zb^T(I - zA)^{-1}e$ is the stability function.

Proof Obviously, $y_1 = R(z)y_0$. Step by step, $y_m = R(z)^m y_0$ is an approximation of $y(1)$. Solving equation (3.5), we obtain $y(1) = e^p y_0$. Because the method is convergent, we have $\lim_{h \rightarrow 0, mh=1} y_m = y(1)$, which implies $\lim_{m \rightarrow \infty, mh=1} R(z)^m = e^p$. \square

Lemma 3.5 (See [16–19]) *The (j, k) -Padé approximation to e^z is given by*

$$R(z) = \frac{P_j(z)}{Q_k(z)}, \tag{3.6}$$

where

$$P_j(z) = 1 + \frac{j}{j+k} \cdot z + \frac{j(j-1)}{(j+k)(j+k-1)} \cdot \frac{z^2}{2!} + \dots + \frac{j!k!}{(j+k)!} \cdot \frac{z^j}{j!},$$

$$Q_k(z) = 1 - \frac{k}{j+k} \cdot z + \frac{k(k-1)}{(j+k)(j+k-1)} \cdot \frac{z^2}{2!} + \dots + (-1)^k \cdot \frac{k!j!}{(j+k)!} \cdot \frac{z^k}{k!},$$

with error

$$e^z - R(z) = (-1)^k \cdot \frac{j!k!}{(j+k)!(j+k+1)!} \cdot z^{j+k+1} + O(z^{j+k+2}).$$

It is the unique rational approximation to e^z of order $j+k$, such that the degrees of numerator and denominator are j and k , respectively.

It is easy to prove the following lemma. Therefore, the proof is omitted.

Lemma 3.6 *Assume $p \neq 0, p+q \neq 0$, and $f(x) = |x + \frac{q}{p}(x-1)|$. Then $f(x)$ is decreasing for $x < \frac{q}{p+q}$. On the other hand, $f(x)$ is increasing for $x > \frac{q}{p+q}$.*

The set S of all (p, q, r) at which the scheme (3.1) is asymptotically stable is called the asymptotical stability region,

$$S = \left\{ (p, q, r) : \left| (1+r) \left(R(z)^m + \frac{q}{p} (R(z)^m - 1) \right) \right| < 1 \right\}.$$

Theorem 3.7 *Assume $p \neq 0, p+q \neq 0$, and the stability function of the Runge-Kutta method $R(z)$ is the (j, k) -Padé approximation to $e^z, z = hp$. Then for $h = \frac{1}{m}, m$ being an integer,*

1. when $h \leq \min\{h_1, -\frac{\zeta}{p}\}, H_1 \subseteq S$ if and only if j is even,
2. when $h \leq h_2, H_2 \subseteq S$ if and only if j is odd,
3. when $h \leq \min\{h_1, \frac{\eta}{p}\}, H_3 \subseteq S$ if and only if k is odd,
4. when $h \leq h_2, H_4 \subseteq S$ if and only if k is even,

where $h_1 = \sup\{x : R(hp)^{\frac{1}{h}} < \frac{q}{p+q} \text{ for all } h \in (0, x)\}, h_2 = \sup\{x : R(hp)^{\frac{1}{h}} > \frac{q}{p+q} \text{ for all } h \in (0, x)\}, \eta$ is a real zero of $Q_k(z)$, and ζ is a real zero of $P_j(z)$. (See Table 1.)

Proof For brevity, we only prove case 1 of the theorem; the others, which can be proved similarly, are omitted. By Lemma 3.4, we see that $\lim_{m \rightarrow \infty, mh=1} R(z)^m = e^p$. $e^p \leq \frac{q}{p+q}$ implies $R(z)^m \leq \frac{q}{p+q}$ for $h \leq h_1$. Assume $h \leq \min\{h_1, -\frac{\zeta}{p}\}$.

\Leftarrow By Lemma 3.5 and j is even, we can obtain $e^z \leq R(z)$, which implies that $e^p \leq R(z)^m \leq \frac{q}{p+q}$ for $m \geq M$. Consequently, by Lemma 3.6, we have

$$\left| R(z)^m + \frac{q}{p} (R(z)^m - 1) \right| \leq \left| e^p + \frac{q}{p} (e^p - 1) \right|,$$

which implies $H_1 \subseteq S$.

Table 1 The high order Runge-Kutta methods for (1.1)

	Gauss-Legendre	Radau IA, IIA	Lobatto IIIA, IIIB	Lobatto IIIC
(j, k)	(v, v)	$(v - 1, v)$	$(v - 1, v - 1)$	$(v - 2, v)$
$H_1 \subseteq S$	v is even	v is odd	v is odd	v is even
$H_2 \subseteq S$	v is odd	v is even	v is even	v is odd
$H_3 \subseteq S$	v is odd	v is odd	v is even	v is odd
$H_4 \subseteq S$	v is even	v is even	v is odd	v is even

$\implies H_1 \subseteq S$ implies $|R(z)^m + \frac{q}{p}(R(z)^m - 1)| \leq |e^p + \frac{q}{p}(e^p - 1)|$. Because $e^p \leq \frac{q}{p+q}$, $R(z)^m \leq \frac{q}{p+q}$, by Lemma 3.6, we obtain $R(z)^m \leq e^p$, which implies $R(z) \geq e^z$. By Lemma 3.5, we see that j is even. □

4 Special cases

In this section, two special cases are studied: the first special case $q = 0$, where equation (1.1) is changed as linear impulsive ordinary differential equations; second special case $r = 0$, where equation (1.1) is changed as linear differential equations with piecewise continuous argument without impulsive perturbations.

4.1 Linear impulsive ordinary differential equations

In this subsection, the special case of (1.1) when $q = 0$ is studied. Equation (1.1) is changed as

$$\begin{cases} x'(t) = px(t), & t \geq 0, t \neq k, k = 1, 2, \dots, \\ \Delta x(k) = rx(k^-), & k = 1, 2, \dots, \\ x(0) = x_0, \end{cases} \tag{4.1}$$

where p, r , and x_0 .

Theorem 2.3 is changed to the following result.

Theorem 4.1 *On $t \in [0, \infty)$, (4.1) has a unique solution*

$$x(t) = m_1(\{t\}) \cdot n_1^{[t]} \cdot x_0,$$

where $\{t\}$ is the fractional part of t and

$$m_1(t) = e^{pt}, \quad n_1 = (1 + r)m_1(1) = (1 + r)e^p.$$

Consequently, the zero solution of (1.1) is asymptotically stable if and only if

$$|1 + r|e^p < 1. \tag{4.2}$$

The asymptotical stability sets H_0, H, H_2 , and H_4 are changed as follows, respectively:

$$\begin{aligned} H_5 &= \{(p, r) : p = 0 \text{ and } |1 + r| < 1\}, \\ H_6 &= \{(p, r) : |1 + r|e^p < 1\}, \\ H_7 &= \{(p, r) : p < 0 \text{ and } (p, r) \in H_6\}, \end{aligned}$$

Table 2 The high order Runge-Kutta methods for (4.1)

	Gauss-Legendre	Radau IA, IIA	Lobatto IIIA, IIIB	Lobatto IIIC
(j, k)	(v, v)	$(v - 1, v)$	$(v - 1, v - 1)$	$(v - 2, v)$
$H_7 \subseteq S_1$	v is odd	v is even	v is even	v is odd
$H_8 \subseteq S_1$	v is even	v is even	v is odd	v is even

$$H_8 = \{(p, r) : p > 0 \text{ and } (p, r) \in H_6\}.$$

Obviously, H_1 and H_3 are empty as $q = 0$, so it is not considered.

We also consider the Runge-Kutta methods for (4.1):

$$\begin{cases} x_{k,l+1} = x_{k,l} + hp \sum_{i=1}^v b_i Y_{k,l}^i, & l = 0, 1, \dots, m - 1, k = 0, 1, \dots, \\ Y_{k,l}^i = x_{k,l} + hp \sum_{j=1}^v a_{ij} Y_{k,l}^j, & l = 0, 1, \dots, m - 1, k = 0, 1, \dots, \\ x_{(k+1),0} = (1 + r)x_{k,m}, & k = 0, 1, 2, \dots, \\ x_{0,0} = x_0, \end{cases} \tag{4.3}$$

where $h = \frac{1}{m}$, $m \geq 1$, m is an integer, h is the stepsize. The set S_1 of all (p, r) at which the scheme (4.3) is asymptotically stable is called the asymptotical stability region,

$$S_1 = \{(p, r) : |1 + r| \cdot R(z)^m < 1\}.$$

From Theorem 3.7, we immediately obtain the following results.

Theorem 4.2 *Assume the stability function for the Runge-Kutta method is $R(z)$, the (j, k) -Padé approximation to e^z , $z = ph$. Then for $h = \frac{1}{m}$, m being an integer,*

1. $H_5 \subseteq S_1$ for an arbitrary consistent Runge-Kutta method,
2. when $h \leq h_3$, $H_7 \subseteq S_1$ if and only if j is odd,
3. when $h \leq h_3$, $H_8 \subseteq S_1$ if and only if k is even,

where $h_3 = \sup\{x : R(hx) > 0 \text{ for all } h \in (0, x)\}$. (See Table 2.)

The results obtained in this subsection are consistent with the results Ran *et al.* in [4].

4.2 Linear differential equations with piecewise continuous argument

In this subsection, the special case of (1.1) when $r = 0$ is studied. Equation (1.1) is changed as

$$\begin{cases} x'(t) = px(t) + qx([t]), & t \geq 0, \\ x(0) = x_0, \end{cases} \tag{4.4}$$

where we introduced p, q , and x_0 .

Theorem 2.3 is changed to the following result.

Theorem 4.3 *On $t \in [0, \infty)$, (4.4) has a unique solution*

$$x(t) = m_0(\{t\}) \cdot n_2^{[t]} \cdot x_0,$$

where $\{t\}$ is the fractional part of t and

$$m_0(t) = e^{pt} + \frac{q}{p}(e^{pt} - 1), \quad n_2 = m_0(1) = e^p + \frac{q}{p}(e^p - 1).$$

Consequently, when $p \neq 0$, the zero solution of (1.1) is asymptotically stable if and only if

$$\left| e^p + \frac{q}{p}(e^p - 1) \right| = e^p + \frac{|q|}{p}(e^p - 1) < 1. \tag{4.5}$$

Obviously, when $p = 0$, the zero solution of (1.1) is asymptotically stable if and only if $|1 + q| < 1$.

The asymptotical stability sets H, H_1 , and H_4 are changed as follows, respectively:

$$\begin{aligned} H_9 &= \{(p, q) : p = 0 \text{ and } |q| < 1\}, \\ H_{10} &= \left\{ (p, q) : \left| e^p + \frac{q}{p}(e^p - 1) \right| < 1 \right\} = \left\{ (p, q) : -\frac{p(e^p + 1)}{e^p - 1} < q < -p \right\}, \\ H_{11} &= \{(p, q) : p < 0 \text{ and } (p, q) \in H_{10}\}, \\ H_{12} &= \{(p, q) : p > 0 \text{ and } (p, q) \in H_{10}\}. \end{aligned}$$

Obviously, the sets H_2 and H_3 are empty when $r = 0$, so it is not considered.

We also consider the Runge-Kutta methods for (4.4):

$$\begin{cases} x_{k,l+1} = x_{k,l} + h \sum_{i=1}^v b_i(pY_{k,l}^i + qx_{k,0}), & l = 0, 1, \dots, m-1, k = 0, 1, \dots, \\ Y_{k,l}^i = x_{k,l} + h \sum_{j=1}^v a_{ij}(pY_{k,l}^j + qx_{k,0}), & l = 0, 1, \dots, m-1, k = 0, 1, \dots, \\ x_{(k+1),0} = x_{k,m}, & k = 0, 1, 2, \dots, \\ x_{0,0} = x_0, \end{cases} \tag{4.6}$$

where $h = \frac{1}{m}$, $m \geq 1$, m is an integer, h is the stepsize, v is referred to as the number of stages. The following set S_2 of all (p, q) at which the scheme (3.1) is asymptotically stable is called the asymptotical stability region,

$$S_2 = \left\{ (p, q) : \left| R(z)^m + \frac{q}{p}(R(z)^m - 1) \right| < 1 \right\}.$$

From Theorem 3.7, we immediately obtain the following results.

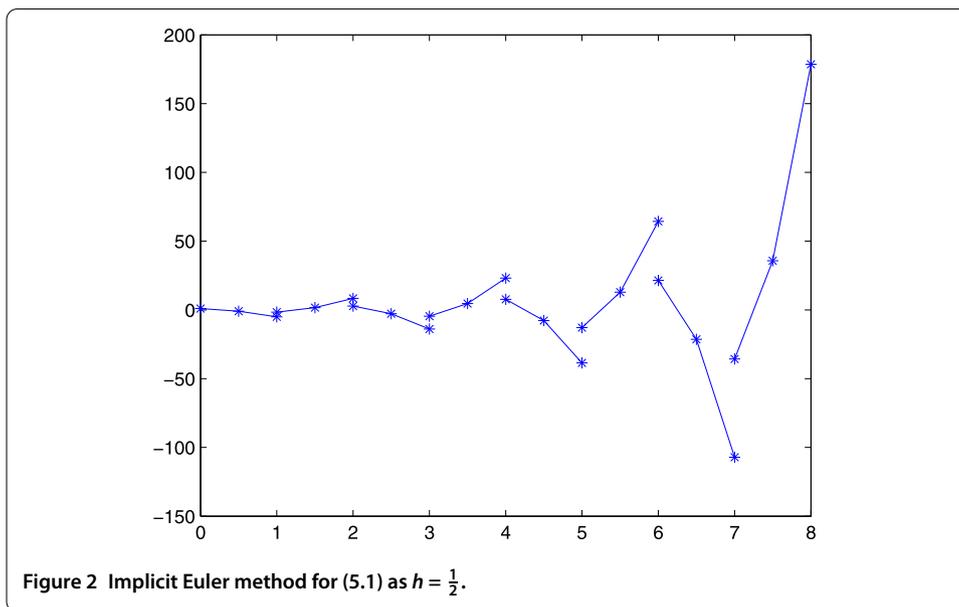
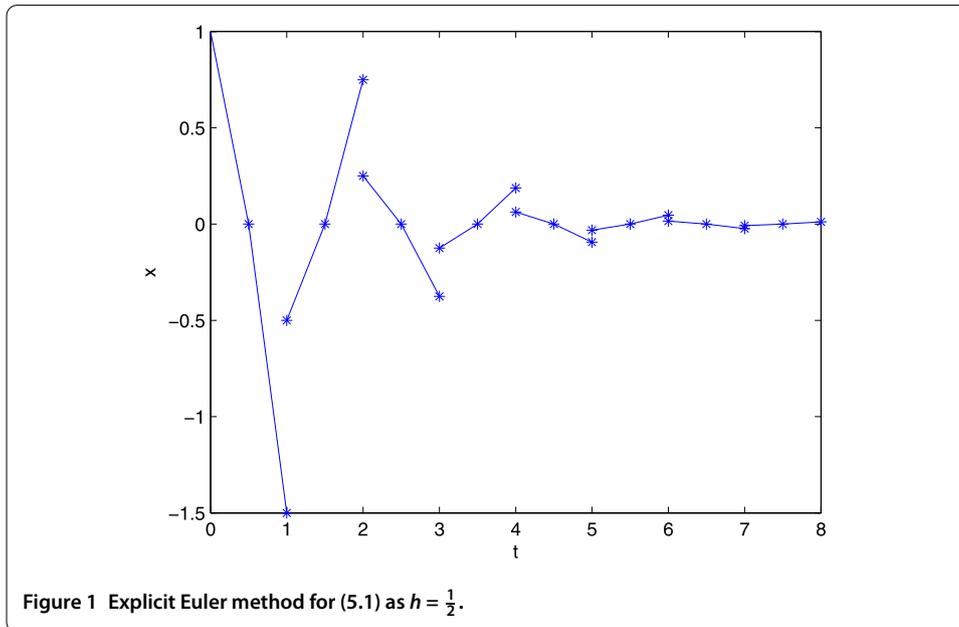
Theorem 4.4 *Assume the stability function Runge-Kutta method is $R(z)$, the (j, k) -Padé approximation to e^z , $z = ph$. Then for $h = \frac{1}{m}$, m being an integer,*

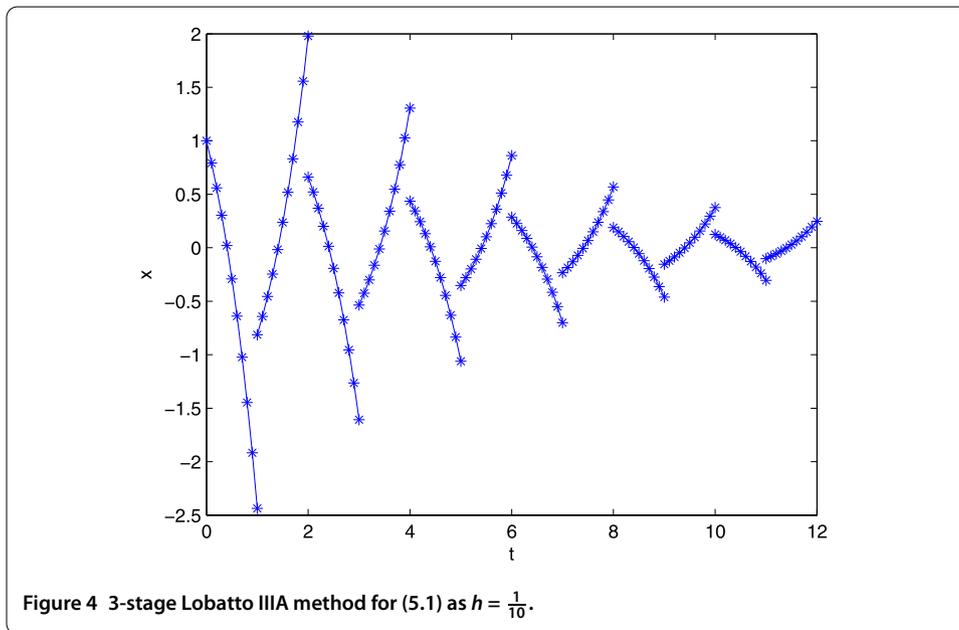
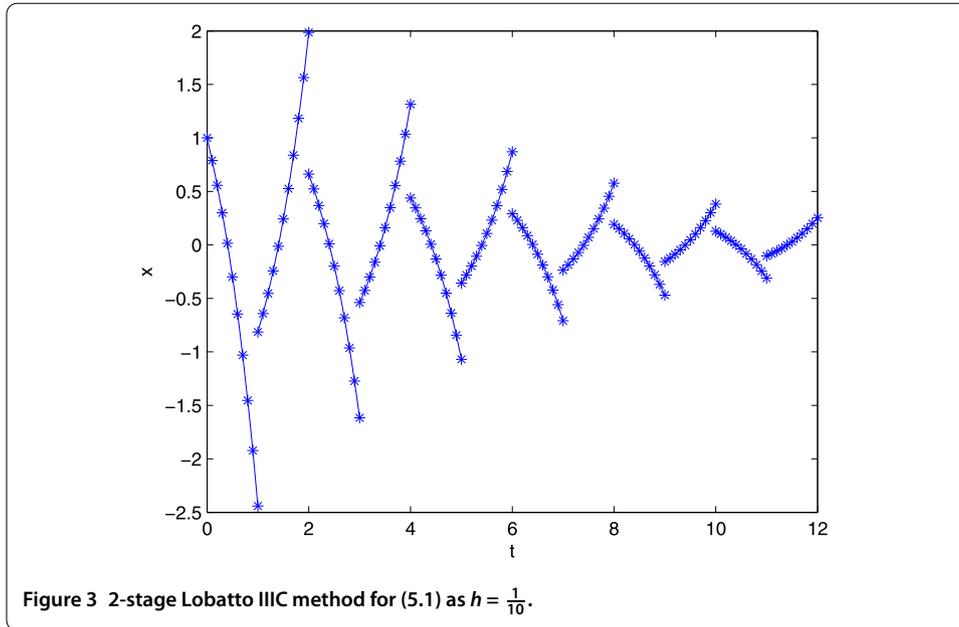
1. $H_9 \subseteq S_2$ for arbitrary consistent Runge-Kutta method,
2. when $h \leq \min\{h_1, -\frac{c}{p}\}$, $H_{11} \subseteq S_2$ if and only if j is even,
3. when $h \leq h_2$, $H_{12} \subseteq S_2$ if and only if k is even. (See Table 3.)

The results obtained in this subsection are consistent with the results of Liu *et al.* in [14].

Table 3 The high order Runge-Kutta methods for (4.4)

	Gauss-Legendre	Radau IA, IIA	Lobatto IIIA, IIIB	Lobatto IIIC
(j, k)	(v, v)	$(v - 1, v)$	$(v - 1, v - 1)$	$(v - 2, v)$
$H_{11} \subseteq S_2$	v is even	v is odd	v is odd	v is even
$H_{12} \subseteq S_2$	v is even	v is even	v is odd	v is even



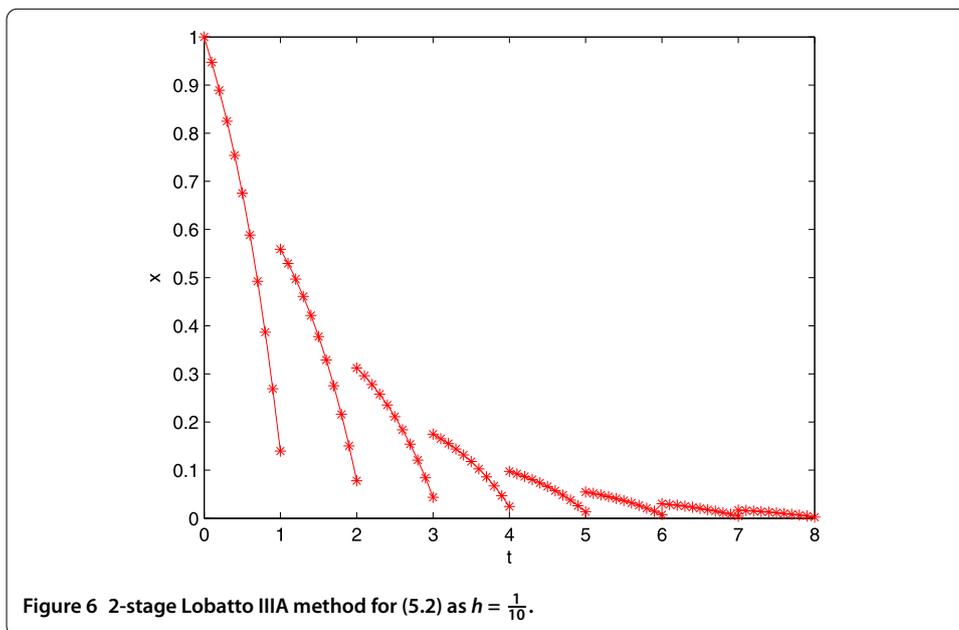
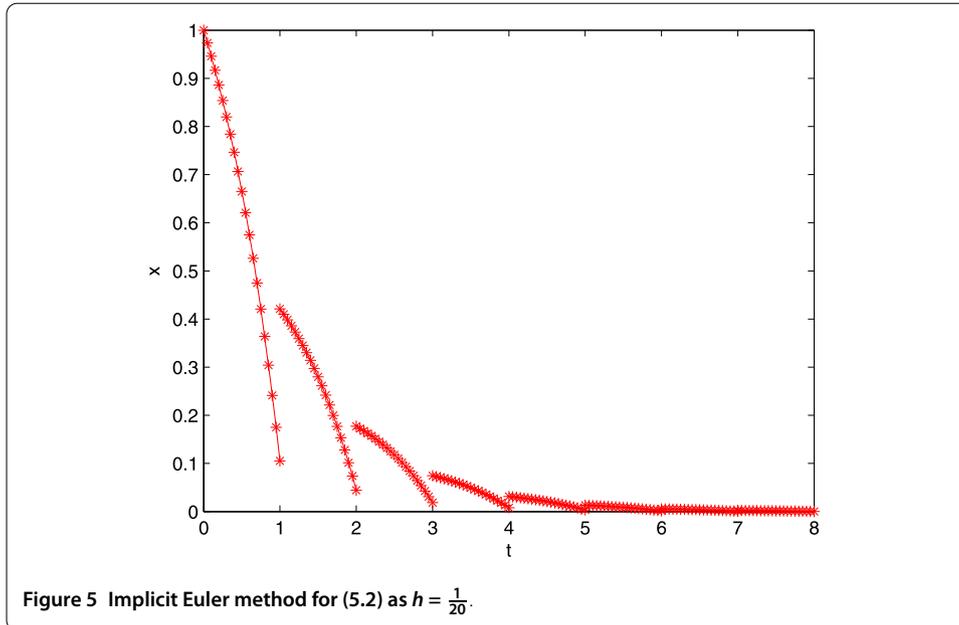


5 Numerical experiments

First of all, we consider the following equation:

$$\begin{cases} x'(t) = x(t) - 3x([t]), & t \geq 0, t \neq k, k = 1, 2, \dots, \\ \Delta x(k) = -\frac{2}{3}x(k^-), & k = 1, 2, \dots, \\ x(0) = 1. \end{cases} \tag{5.1}$$

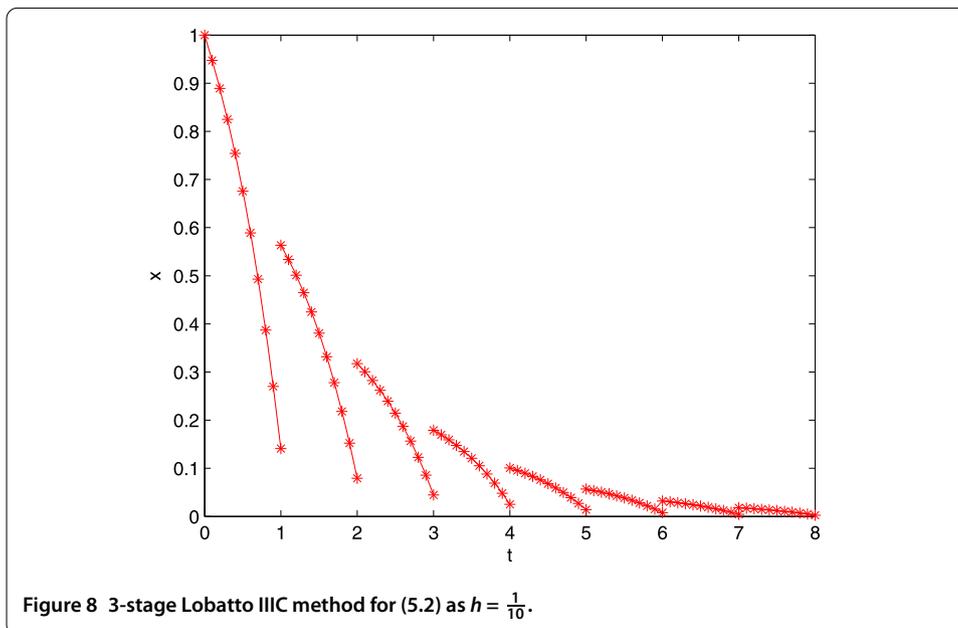
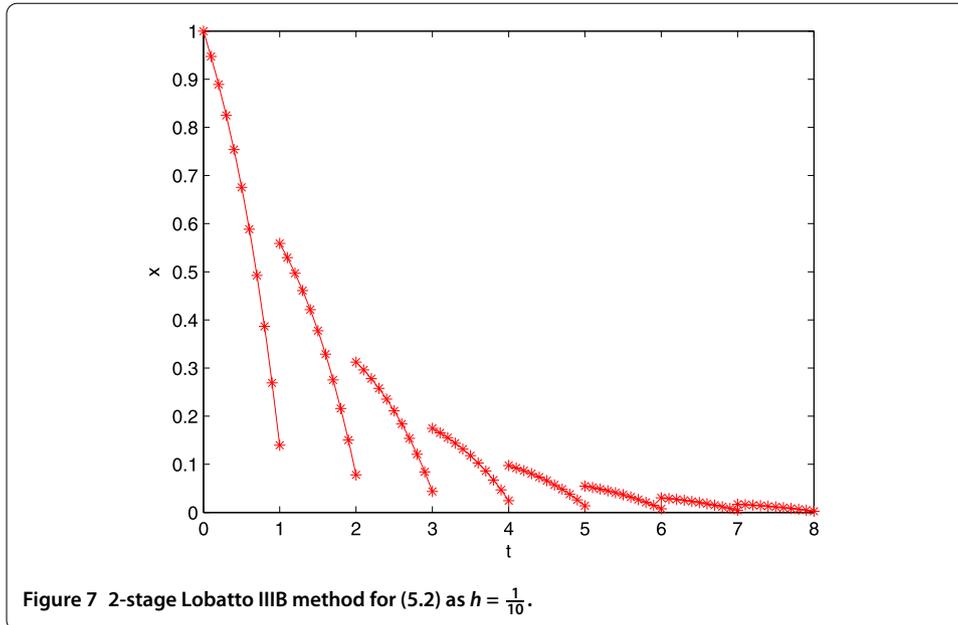
Obviously, we have $|(1+r)(e^p + \frac{q}{p}(e^p - 1))| < 1$. Hence the exact solution of (5.1) is asymptotically stable.



By Theorem 3.7 (case 4 of the theorem), we can see that explicit Euler method for (5.1) (see Figure 1) is asymptotically stable for arbitrary $h = \frac{1}{m}$, m is an integer. (Obviously, $R(hp)^{\frac{1}{h}} = (1 + hp)^{\frac{1}{h}} = (1 + \frac{1}{m})^m \geq 2 > \frac{3}{2} = \frac{q}{p+q}$, which implies $h \leq h_2$ holds for arbitrary $h = \frac{1}{m}$, m being an integer.)

We all know that the implicit Euler method for the test equation $y'(t) = \lambda y(t)$, $\Re(\lambda) < 0$, is asymptotically stable for arbitrary step size $h > 0$. But this does not hold for arbitrary step size $h > 0$ when the implicit Euler method is adopted for (5.1) (see Figure 2).

By Theorem 3.7 and Table 1, we can also see that the 2-stage Lobatto IIIC method and the 3-stage Lobatto IIIA method are all asymptotically stable (see Figures 3 and 4) for h small enough.



Consider the following equation:

$$\begin{cases} x'(t) = x(t) - \frac{3}{2}x([t]), & t \geq 0, t \neq k, k = 1, 2, \dots, \\ \Delta x(k) = 3x(k^-), & k = 1, 2, \dots, \\ x(0) = 1. \end{cases} \tag{5.2}$$

Obviously, we have $|(1+r)(e^p + \frac{q}{p}(e^p - 1))| = 2(3-e) < 1$. Hence the exact solution of (5.2) is asymptotically stable.

By Theorem 3.7 (case 3 of the theorem), we can also see that the implicit Euler method for (5.1) (see Figure 5) is asymptotically stable for $h = \frac{1}{m}$, m being an integer and $m \geq 6$.

Table 4 The errors of the Runge-Kutta methods for (5.1)

<i>m</i>	The implicit Euler		2-Lobatto IIIA		2-Lobatto IIIC	
	AE	RE	AE	RE	AE	RE
10	0.2731	2.1864	0.0023	0.0188	0.0049	0.0393
20	0.0956	0.7651	5.8209	0.0047	0.0012	0.0096
40	0.0406	0.3251	1.4524e-004	0.0012	2.9546e-004	0.0024
80	0.0188	0.1504	3.6293e-005	2.9057e-004	7.3237e-005	5.8636e-004
160	0.0090	0.0724	9.0721e-006	7.2634e-005	1.8227e-005	1.4594e-004
320	0.0044	0.0355	2.2680e-006	1.8158e-005	4.5464e-006	3.6400e-005
Ratio	2.2977	2.2977	4.0083	4.0083	4.0435	4.0435

Table 5 The errors of the Runge-Kutta methods for (5.2)

<i>m</i>	The implicit Euler		2-Lobatto IIIA		2-Lobatto IIIC	
	AE	RE	AE	RE	AE	RE
100	0.0013	0.3930	2.5918e-006	8.0380e-004	5.2281e-006	0.0016
200	7.0145e-004	0.2175	6.4811e-007	2.0100e-004	1.3014e-006	4.0362e-004
400	3.6926e-004	0.1145	1.6204e-007	5.0254e-005	3.2470e-007	1.0070e-004
800	1.8947e-004	0.0588	4.0510e-008	1.2564e-005	8.1098e-008	2.5151e-005
1,600	9.5971e-005	0.0298	1.0128e-008	3.1409e-006	2.0265e-008	6.2848e-006
3,200	4.8298e-005	0.0150	2.5319e-009	7.8522e-007	5.0649e-009	1.5708e-006
Ratio	1.9326	1.9227	3.9997	3.9997	4.0064	4.0064

(Obviously, $\frac{\eta}{p} = 1$ and $R(hp)^{\frac{1}{h}} = (\frac{1}{1-hp})^{\frac{1}{h}} = (1 - \frac{1}{m})^{-m} < 3 = \frac{q}{p+q}$, which implies $h \leq \min\{h_1, \frac{\eta}{p}\}$ holds for $h = \frac{1}{m}$, m being an integer and $m \geq 6$.)

Similarly, we can also see that the 2-stage Lobatto IIIA method for (5.1) (see Figure 6) is asymptotically stable for $h = \frac{1}{m}$, m being an integer and $m \geq 2$. (Obviously, $\frac{\eta}{p} = 2$ and $R(hp)^{\frac{1}{h}} = (\frac{1+\frac{hp}{2}}{1-\frac{hp}{2}})^{\frac{1}{h}} = (1 + \frac{2}{2m-1})^m < 3 = \frac{q}{p+q}$, which implies $h \leq \min\{h_1, \frac{\eta}{p}\}$ holds for $h = \frac{1}{m}$, m being an integer and $m \geq 2$.)

By Theorem 3.7 and Table 1, we also see that the 2-stage Lobatto IIIB and the 3-stage Lobatto IIIC (see Figures 7 and 8) are all asymptotically stable for h small enough.

We can see that the methods conserve their orders of convergence from Table 4 and Table 5.

Competing interests

The author declares that they have no competing interests.

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