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# Positive periodic solution of $p$ -Laplacian Liénard type differential equation with singularity and deviating argument

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## Abstract

In this paper, we consider the following  $p$ -Laplacian Liénard type differential equation with singularity and deviating argument:

$$(\varphi_p(x'(t)))' + f(x(t))x'(t) + g(t, x(t - \sigma)) = e(t).$$

By applications of coincidence degree theory and some analysis techniques, sufficient conditions for the existence of positive periodic solutions are established.

**MSC:** 34C25; 34K13; 34K40

**Keywords:** positive solution;  $p$ -Laplacian; Liénard equation; singularity; deviating argument

## 1 Introduction

In this paper, we consider the following  $p$ -Laplacian Liénard type differential equation with singularity and deviating argument:

$$(\varphi_p(x'(t)))' + f(x(t))x'(t) + g(t, x(t - \sigma)) = e(t), \quad (1.1)$$

where  $\varphi_p : \mathbb{R} \rightarrow \mathbb{R}$  is given by  $\varphi_p(s) = |s|^{p-2}s$ , here  $p > 1$  is a constant,  $f$  is continuous function;  $g$  is a continuous function defined on  $\mathbb{R}^2$  and periodic in  $t$  with  $g(t, \cdot) = g(t + T, \cdot)$ ,  $g$  has a singularity at  $x = 0$ ;  $\sigma$  is a constant and  $0 \leq \sigma < T$ ;  $e : \mathbb{R} \rightarrow \mathbb{R}$  are continuous periodic functions with  $e(t + T) \equiv e(t)$  and  $\int_0^T e(t) dt = 0$ .

As is well known, the existence of periodic solutions for Liénard type differential equations was extensively studied (see [1–10] and the references therein). In recent years, there also appeared some results on a Liénard type differential equation with singularity; see [11, 12]. In 1996, using coincidence degree theory, Zhang considered the existence of  $T$ -periodic solutions for the scalar Liénard equation

$$x''(t) + f(x(t))x'(t) + g(t, x(t)) = 0,$$

when  $g$  becomes unbounded as  $x \rightarrow 0^+$ . The main emphasis was on the repulsive case, *i.e.* when  $g(t, x) \rightarrow +\infty$ , as  $x \rightarrow 0^+$ . Afterwards, Wang [12] studied the existence of periodic

solutions of the Liénard equation with a singularity and a deviating argument,

$$x''(t) + f(x(t))x'(t) + g(t, x(t - \sigma)) = 0,$$

where  $\sigma$  is a constant. When  $g$  has a strong singularity at  $x = 0$  and satisfies a new small force condition at  $x = \infty$ , the author proved that the given equation has at least one positive  $T$ -periodic solution.

However, the Liénard type differential equation (1.1), in which there is a  $p$ -Laplacian Liénard type differential equation, has not attracted much attention in the literature. There are not so many existence results for (1.1) even as regards the  $p$ -Laplacian Liénard type differential equation with singularity and deviating argument. In this paper, we try to fill this gap and establish the existence of a positive periodic solution of (1.1) using coincidence degree theory. Our new results generalize in several aspects some recent results contained in [11, 12].

## 2 Preparation

Let  $X$  and  $Y$  be real Banach spaces and  $L : D(L) \subset X \rightarrow Y$  be a Fredholm operator with index zero, here  $D(L)$  denotes the domain of  $L$ . This means that  $\text{Im} L$  is closed in  $Y$  and  $\dim \text{Ker} L = \dim(Y / \text{Im} L) < +\infty$ . Consider supplementary subspaces  $X_1, Y_1$  of  $X, Y$ , respectively, such that  $X = \text{Ker} L \oplus X_1, Y = \text{Im} L \oplus Y_1$ . Let  $P : X \rightarrow \text{Ker} L$  and  $Q : Y \rightarrow Y_1$  denote the natural projections. Clearly,  $\text{Ker} L \cap (D(L) \cap X_1) = \{0\}$  and so the restriction  $L_p := L|_{D(L) \cap X_1}$  is invertible. Let  $K$  denote the inverse of  $L_p$ .

Let  $\Omega$  be an open bounded subset of  $X$  with  $D(L) \cap \Omega \neq \emptyset$ . A map  $N : \overline{\Omega} \rightarrow Y$  is said to be  $L$ -compact in  $\overline{\Omega}$  if  $QN(\overline{\Omega})$  is bounded and the operator  $K(I - Q)N : \overline{\Omega} \rightarrow X$  is compact.

**Lemma 2.1** (Gaines and Mawhin [13]) *Suppose that  $X$  and  $Y$  are two Banach spaces, and  $L : D(L) \subset X \rightarrow Y$  is a Fredholm operator with index zero. Let  $\Omega \subset X$  be an open bounded set and  $N : \overline{\Omega} \rightarrow Y$  be  $L$ -compact on  $\overline{\Omega}$ . Assume that the following conditions hold:*

- (1)  $Lx \neq \lambda Nx, \forall x \in \partial\Omega \cap D(L), \lambda \in (0, 1)$ ;
- (2)  $Nx \notin \text{Im} L, \forall x \in \partial\Omega \cap \text{Ker} L$ ;
- (3)  $\deg\{JQN, \Omega \cap \text{Ker} L, 0\} \neq 0$ , where  $J : \text{Im} Q \rightarrow \text{Ker} L$  is an isomorphism.

*Then the equation  $Lx = Nx$  has a solution in  $\overline{\Omega} \cap D(L)$ .*

For the sake of convenience, throughout this paper we will adopt the following notation:

$$\begin{aligned} |u|_\infty &= \max_{t \in [0, T]} |u(t)|, & |u|_0 &= \min_{t \in [0, T]} |u(t)|, \\ |u|_p &= \left( \int_0^T |u|^p dt \right)^{\frac{1}{p}}, & \bar{h} &= \frac{1}{T} \int_0^T h(t) dt. \end{aligned}$$

**Lemma 2.2** ([14]) *If  $\omega \in C^1(\mathbb{R}, \mathbb{R})$  and  $\omega(0) = \omega(T) = 0$ , then*

$$\int_0^T |\omega(t)|^p dt \leq \left( \frac{T}{\pi_p} \right)^p \int_0^T |\omega'(t)|^p dt,$$

where  $1 \leq p < \infty, \pi_p = 2 \int_0^{(p-1)/p} \frac{ds}{(1-s^p)^{1/p}} = \frac{2\pi(p-1)^{1/p}}{p \sin(\pi/p)}$ .

**Lemma 2.3** *If  $x \in C^1(\mathbb{R}, \mathbb{R})$  with  $x(t + T) = x(t)$ , and  $t_0 \in [0, T]$  such that  $|x(t_0)| < d$ , then*

$$\left(\int_0^T |x(t)|^p dt\right)^{\frac{1}{p}} \leq \left(\frac{T}{\pi_p}\right) \left(\int_0^T |x'(t)|^p dt\right)^{\frac{1}{p}} + dT^{\frac{1}{p}}.$$

*Proof* Let  $\omega(t) = x(t + t_0) - x(t_0)$ , and then  $\omega(0) = \omega(T) = 0$ . By Lemma 2.2 and Minkowski’s inequality, we have

$$\begin{aligned} \left(\int_0^T |x(t)|^p dt\right)^{\frac{1}{p}} &= \left(\int_0^T |\omega(t) + x(t_0)|^p dt\right)^{\frac{1}{p}} \\ &\leq \left(\int_0^T |\omega(t)|^p dt\right)^{\frac{1}{p}} + \left(\int_0^T |x(t_0)|^p dt\right)^{\frac{1}{p}} \\ &\leq \left(\frac{T}{\pi_p}\right) \left(\int_0^T |\omega'(t)|^p dt\right)^{\frac{1}{p}} + dT^{\frac{1}{p}} \\ &= \left(\frac{T}{\pi_p}\right) \left(\int_0^T |x'(t)|^p dt\right)^{\frac{1}{p}} + dT^{\frac{1}{p}}. \end{aligned}$$

This completes the proof of Lemma 2.3. □

In order to apply the topological degree theorem to study the existence of a positive periodic solution for (1.1), we rewrite (1.1) in the form

$$\begin{cases} x_1'(t) = \varphi_q(x_2(t)), \\ x_2'(t) = -f(x_1(t))x_1'(t) - g(t, x_1(t - \sigma)) + e(t), \end{cases} \tag{2.1}$$

where  $\frac{1}{p} + \frac{1}{q} = 1$ . Clearly, if  $x(t) = (x_1(t), x_2(t))^T$  is an  $T$ -periodic solution to (2.1), then  $x_1(t)$  must be an  $T$ -periodic solution to (1.1). Thus, the problem of finding an  $T$ -periodic solution for (1.1) reduces to finding one for (2.1).

Now, set  $X = Y = \{x = (x_1(t), x_2(t)) \in C^1(\mathbb{R}, \mathbb{R}^2) : x(t + T) \equiv x(t)\}$  with the norm  $\|x\| = \max\{|x_1|_\infty, |x_2|_\infty\}$ . Clearly,  $X$  and  $Y$  are both Banach spaces. Meanwhile, define

$$L : D(L) = \{x \in C^1(\mathbb{R}, \mathbb{R}^2) : x(t + T) = x(t), t \in \mathbb{R}\} \subset X \rightarrow Y$$

by

$$(Lx)(t) = \begin{pmatrix} x_1'(t) \\ x_2'(t) \end{pmatrix}$$

and  $N : X \rightarrow Y$  by

$$(Nx)(t) = \begin{pmatrix} \varphi_q(x_2(t)) \\ -f(x_1(t))x_1'(t) - g(t, x_1(t - \sigma)) + e(t) \end{pmatrix}. \tag{2.2}$$

Then (2.1) can be converted to the abstract equation  $Lx = Nx$ . From the definition of  $L$ , one can easily see that

$$\text{Ker } L \cong \mathbb{R}^2, \quad \text{Im } L = \left\{ y \in Y : \int_0^T \begin{pmatrix} y_1(s) \\ y_2(s) \end{pmatrix} ds = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\}.$$

So  $L$  is a Fredholm operator with index zero. Let  $P : X \rightarrow \text{Ker } L$  and  $Q : Y \rightarrow \text{Im } Q \subset \mathbb{R}^2$  be defined by

$$Px = \begin{pmatrix} (Ax_1)(0) \\ x_2(0) \end{pmatrix}; \quad Qy = \frac{1}{T} \int_0^T \begin{pmatrix} y_1(s) \\ y_2(s) \end{pmatrix} ds,$$

then  $\text{Im } P = \text{Ker } L$ ,  $\text{Ker } Q = \text{Im } L$ . Let  $K$  denote the inverse of  $L|_{\text{Ker } P \cap D(L)}$ . It is easy to see that  $\text{Ker } L = \text{Im } Q = \mathbb{R}^2$  and

$$[Ky](t) = \int_0^T G(t, s)y(s) ds,$$

where

$$G(t, s) = \begin{cases} \frac{s}{T}, & 0 \leq s < t \leq T; \\ \frac{s-t}{T}, & 0 \leq t \leq s \leq T. \end{cases} \tag{2.3}$$

From (2.2) and (2.3), it is clear that  $QN$  and  $K(I - Q)N$  are continuous,  $QN(\overline{\Omega})$  is bounded and then  $K(I - Q)N(\overline{\Omega})$  is compact for any open bounded  $\Omega \subset X$ , which means  $N$  is  $L$ -compact on  $\overline{\Omega}$ .

### 3 Main results

Assume that

$$\psi(t) = \lim_{x \rightarrow +\infty} \sup \frac{g(t, x)}{x^{p-1}} \tag{3.1}$$

exists uniformly a.e.  $t \in [0, T]$ , i.e., for any  $\varepsilon > 0$  there is  $g_\varepsilon \in L^2(0, T)$  such that

$$g(t, x) \leq (\psi(t) + \varepsilon)x + g_\varepsilon(t), \tag{3.2}$$

for all  $x > 0$  and a.e.  $t \in [0, T]$ . Moreover,  $\psi \in C(\mathbb{R}, \mathbb{R})$  and  $\psi(t + T) = \psi(t)$ .

For the sake of convenience, we list the following assumptions which will be used repeatedly in the sequel:

(H<sub>1</sub>) (Balance condition) There exist constants  $0 < D_1 < D_2$  such that if  $x$  is a positive continuous  $T$ -periodic function satisfying

$$\int_0^T g(t, x(t)) dt = 0,$$

then

$$D_1 \leq x(\tau) \leq D_2,$$

for some  $\tau \in [0, T]$ .

(H<sub>2</sub>) (Degree condition)  $\bar{g}(x) < 0$  for all  $x \in (0, D_1)$ , and  $\bar{g}(x) > 0$  for all  $x > D_2$ .

(H<sub>3</sub>) (Decomposition condition)  $g(t, x) = g_0(x) + g_1(t, x)$ , where  $g_0 \in C((0, \infty); \mathbb{R})$  and  $g_1 : [0, T] \times [0, \infty) \rightarrow \mathbb{R}$  is an  $L^2$ -Carathéodory function, i.e. it is measurable in the first variable and continuous in the second variable, and for any  $b > 0$  there is  $h_b \in L^2(0, T; \mathbb{R}_+)$  such that

$$|g_1(t, x)| \leq h_b(t), \quad \text{a.e. } t \in [0, T], \forall 0 \leq x \leq b.$$

(H<sub>4</sub>) (Strong force condition at  $x = 0$ )  $\int_0^1 g_0(x) dx = -\infty$ .

**Theorem 3.1** *Assume that conditions (H<sub>1</sub>)-(H<sub>4</sub>) hold. Suppose the following condition is satisfied:*

(H<sub>5</sub>)  $(\frac{T}{\pi p})^p |\psi|_\infty < 1$ .

*Then (1.1) has at least one positive  $T$ -periodic solution.*

*Proof* Consider the equation

$$Lx = \lambda Nx, \quad \lambda \in (0, 1).$$

Set  $\Omega_1 = \{x : Lx = \lambda Nx, \lambda \in (0, 1)\}$ . If  $x(t) = (x_1(t), x_2(t))^T \in \Omega_1$ , then

$$\begin{cases} x_1'(t) = \lambda \varphi_q(x_2(t)), \\ x_2'(t) = -\lambda f(x_1(t))x_1'(t) - \lambda g(t, x_1(t - \sigma)) + \lambda e(t). \end{cases} \tag{3.3}$$

Substituting  $x_2(t) = \frac{1}{\lambda^{p-1}} \varphi_p(x_1'(t))$  into the second equation of (3.3)

$$(\varphi_p(x_1'(t)))' + \lambda^p f(x_1(t))x_1'(t) + \lambda^p g(t, x_1(t - \sigma)) = \lambda^p e(t). \tag{3.4}$$

Integrating both sides of (3.4) over  $[0, T]$ , we have

$$\int_0^T g(t, x_1(t - \sigma)) dt = 0. \tag{3.5}$$

From (H<sub>1</sub>), there exist positive constants  $D_1, D_2$ , and  $\xi \in [0, T]$  such that

$$D_1 \leq x_1(\xi) \leq D_2. \tag{3.6}$$

Then we have

$$|x_1(t)| = \left| x_1(\xi) + \int_\xi^t x_1'(s) ds \right| \leq D_2 + \int_\xi^t |x_1'(s)| ds, \quad t \in [\xi, \xi + T],$$

and

$$|x_1(t)| = |x_1(t - T)| = \left| x_1(\xi) - \int_{t-T}^\xi x_1'(s) ds \right| \leq D_2 + \int_{t-T}^\xi |x_1'(s)| ds, \quad t \in [\xi, \xi + T].$$

Combining the above two inequalities, we obtain

$$\begin{aligned}
 |x_1|_\infty &= \max_{t \in [0, T]} |x_1(t)| = \max_{t \in [\xi, \xi + T]} |x_1(t)| \\
 &\leq \max_{t \in [\xi, \xi + T]} \left\{ D_2 + \frac{1}{2} \left( \int_\xi^t |x'_1(s)| ds + \int_{t-T}^\xi |x'_1(s)| ds \right) \right\} \\
 &\leq D_2 + \frac{1}{2} \int_0^T |x'_1(s)| ds.
 \end{aligned} \tag{3.7}$$

Multiplying both sides of (3.4) by  $x_1(t)$  and integrating over the interval  $[0, T]$ , we get

$$\begin{aligned}
 &\int_0^T (\varphi_p(x'_1(t)))' x_1(t) dt + \lambda^p \int_0^T f(x_1(t)) x'_1(t) x_1(t) dt + \lambda^p \int_0^T g(t, x_1(t - \sigma)) x_1(t) dt \\
 &= \lambda^p \int_0^T e(t) x_1(t) dt.
 \end{aligned} \tag{3.8}$$

Substituting  $\int_0^T (\varphi_p(x'_1(t)))' x_1(t) dt = -\int_0^T |x'_1(t)|^p dt$ ,  $\int_0^T f(x_1(t)) x'_1(t) x_1(t) dt = 0$  into (3.8), we have

$$\int_0^T |x'_1(t)|^p dt = \lambda^p \int_0^T g(t, x_1(t - \sigma)) x_1(t) dt - \lambda^p \int_0^T e(t) x_1(t) dt. \tag{3.9}$$

For any  $\varepsilon > 0$ , there exists a function  $g_\varepsilon \in L^2(0, T)$  such that (3.2) holds. Since  $x_1(t) > 0$ ,  $t \in [0, T]$ , it follows from (3.4) that

$$g(t, x_1(t - \sigma)) x_1(t) \leq (\psi(t) + \varepsilon) x_1^{p-1}(t - \sigma) x_1(t) + g_\varepsilon(t) x_1(t). \tag{3.10}$$

We infer from (3.9) and (3.10)

$$\begin{aligned}
 &\int_0^T |x'_1(t)|^p dt \\
 &\leq \lambda^p \int_0^T (\psi(t) + \varepsilon) x_1^{p-1}(t - \sigma) x_1(t) dt + \lambda^p \int_0^T (g_\varepsilon(t) + e(t)) x_1(t) dt \\
 &\leq \int_0^T (|\psi(t)| + \varepsilon) |x_1^{p-1}(t - \sigma)| |x_1(t)| dt + \int_0^T (|g_\varepsilon(t)| + |e(t)|) |x_1(t)| dt \\
 &\leq (|\psi|_\infty + \varepsilon) \left( \int_0^T |x_1(t - \sigma)|^p dt \right)^{\frac{p-1}{p}} \left( \int_0^T |x_1(t)|^p dt \right)^{\frac{1}{p}} \\
 &\quad + |x_1|_\infty \left( \int_0^T |g_\varepsilon(t)| dt + \int_0^T |e(t)| dt \right) \\
 &\leq (|\psi|_\infty + \varepsilon) \left( \int_0^T |x_1(t)|^p dt \right) + |x_1|_\infty \left( \int_0^T |g_\varepsilon(t)| dt + \int_0^T |e(t)| dt \right).
 \end{aligned} \tag{3.11}$$

From Lemma 2.3 and (3.7), we have

$$\left( \int_0^T |x_1(t)|^p dt \right)^{\frac{1}{p}} \leq \left( \frac{T}{\pi_p} \right) \left( \int_0^T |x'_1(t)|^p dt \right)^{\frac{1}{p}} + D_2 T^{\frac{1}{p}}. \tag{3.12}$$

Substituting (3.7), (3.12) into (3.11), we get

$$\begin{aligned}
 & \int_0^T |x_1'(t)|^p dt \\
 & \leq (|\psi|_\infty + \varepsilon) \left( \left( \frac{T}{\pi_p} \right) \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{1}{p}} + D_2 T^{\frac{1}{p}} \right)^p \\
 & \quad + \left( D_2 + \frac{1}{2} \int_0^T |x_1'(t)| dt \right) \left( \int_0^T |g_\varepsilon(t)| dt + \int_0^T |e(t)| dt \right) \\
 & \leq (|\psi|_\infty + \varepsilon) \left( \left( \frac{T}{\pi_p} \right)^p \int_0^T |x_1'(t)|^p dt \right. \\
 & \quad \left. + p \left( \frac{T}{\pi_p} \right)^{p-1} \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{p-1}{p}} D_2 T^{\frac{1}{p}} + \dots + D_2^p T \right) \\
 & \quad + \left( D_2 + \frac{1}{2} T^{\frac{1}{q}} \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{1}{p}} \right) (T^{\frac{1}{2}} (|g_\varepsilon|_2 + |e|_2)) \\
 & = (|\psi|_\infty + \varepsilon) \left( \frac{T}{\pi_p} \right)^p \int_0^T |x_1'(t)|^p dt \\
 & \quad + (|\psi|_\infty + \varepsilon) p \left( \frac{T}{\pi_p} \right)^{p-1} \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{p-1}{p}} D_2 T^{\frac{1}{p}} + \dots \\
 & \quad + \frac{1}{2} T^{\frac{1}{q} + \frac{1}{2}} \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{1}{p}} (|g_\varepsilon|_2 + |e|_2) \\
 & \quad + (|\psi|_\infty + \varepsilon) D_2^p T + T^{\frac{1}{2}} D_2 (|g_\varepsilon|_2 + |e|_2), \tag{3.13}
 \end{aligned}$$

where  $|g_\varepsilon|_2 = \left( \int_0^T |g_\varepsilon(t)|^2 dt \right)^{\frac{1}{2}}$ . Since  $\varepsilon$  is sufficiently small, from (H<sub>5</sub>) we know that  $\left( \frac{T}{\pi_p} \right)^p |\psi|_\infty < 1$ . So, it is easy to see that there exists a positive constant  $M'_1$  such that

$$\int_0^T |x_1'(t)|^p dt \leq M'_1.$$

From (3.7), we have

$$\begin{aligned}
 |x_1|_\infty & \leq D_2 + \frac{1}{2} \int_0^T |x_1'(t)| dt \\
 & \leq D_2 + \frac{T^{\frac{1}{q}}}{2} \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{1}{p}} \\
 & \leq D_2 + \frac{T^{\frac{1}{q}}}{2} (M'_1)^{\frac{1}{p}} := M_1. \tag{3.14}
 \end{aligned}$$

Write

$$I_+ = \{t \in [0, T] : g(t, x_1(t - \sigma)) \geq 0\}; \quad I_- = \{t \in [0, T] : g(t, x_1(t - \sigma)) \leq 0\}.$$

Then we get from (3.2) and (3.6)

$$\begin{aligned}
 \int_0^T |g(t, x_1(t - \sigma))| dt &= \int_{I_+} g(t, x_1(t - \sigma)) dt - \int_{I_-} g(t, x_1(t - \sigma)) dt \\
 &= 2 \int_{I_+} g(t, x_1(t - \sigma)) dt \\
 &\leq 2 \int_{I_+} ((\psi(t) + \varepsilon)x_1^{p-1}(t - \sigma) + g_\varepsilon(t)) dt \\
 &\leq 2(|\psi|_\infty + \varepsilon) \int_0^T |x_1(t)|^{p-1} dt + 2 \int_0^T |g_\varepsilon(t)| dt \\
 &\leq 2(|\psi|_\infty + \varepsilon) TM_1^{p-1} + 2\sqrt{T}|g_\varepsilon|_2. \tag{3.15}
 \end{aligned}$$

By the second equations of (3.3) and (3.15), we obtain

$$\begin{aligned}
 &\int_0^T |x_2'(t)| dt \\
 &\leq \lambda \int_0^T |f(x_1(t))||x_1'(t)| dt + \lambda \int_0^T |g(t, x_1(t - \sigma))| dt + \lambda \int_0^T |e(t)| dt \\
 &\leq \lambda |f|_{M_1} T^{\frac{1}{q}} \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{1}{p}} + \lambda (2(|\psi|_\infty + \varepsilon) TM_1^{p-1} + 2\sqrt{T}|g_\varepsilon|_2) + \lambda \sqrt{T}|e|_2 \\
 &\leq \lambda |f|_{M_1} T^{\frac{1}{q}} (M_1')^{\frac{1}{p}} + \lambda (2(|\psi|_\infty + \varepsilon) TM_1^{p-1} + 2\sqrt{T}|g_\varepsilon|_2) + \lambda \sqrt{T}|e|_2 \\
 &:= \lambda M_2', \tag{3.16}
 \end{aligned}$$

where  $|f|_{M_1} = \max_{0 < x_1 \leq M_1} |f(x_1(t))|$ . By the first equation of (3.3), we have

$$\int_0^T |x_2(s)|^{q-2} x_2(s) ds = 0,$$

which implies that there is a constant  $t_2 \in [0, T]$  such that  $x_2(t_2) = 0$ , so

$$|x_2|_\infty \leq \frac{1}{2} \int_0^{t_2} |x_2'(s)| ds \leq \frac{1}{2} \int_0^T |x_2'(s)| ds \leq \frac{\lambda}{2} M_2' := \lambda M_2. \tag{3.17}$$

On the other hand, it follows from (3.4) that

$$(\varphi_p(x_1'(t + \sigma)))' + \lambda^p (f(x_1(t + \sigma))x_1'(t + \sigma) + g(t + \sigma, x_1(t))) = \lambda^p e(t + \sigma). \tag{3.18}$$

Namely,

$$\begin{aligned}
 &(\varphi_p(x_1'(t + \sigma)))' + \lambda^p f(x_1(t + \sigma))x_1'(t + \sigma) \\
 &\quad + \lambda^p g_0(x_1(t)) + g_1(t + \sigma, x_1(t)) = \lambda^p e(t + \sigma). \tag{3.19}
 \end{aligned}$$

Multiplying both sides of (3.19) by  $x_1'(t)$ , we get

$$\begin{aligned}
 &(\varphi_p(x_1'(t + \sigma)))' x_1'(t) + \lambda^p f(x_1(t + \sigma))x_1'(t + \sigma)x_1'(t) \\
 &\quad + \lambda^p g_0(x_1(t))x_1'(t) + \lambda^p g_1(t + \sigma, x_1(t))x_1'(t) = \lambda^p e(t + \sigma)x_1'(t). \tag{3.20}
 \end{aligned}$$

Let  $\tau \in [0, T]$ , for any  $\tau \leq t \leq T$ , we integrate (3.20) on  $[\tau, t]$  and get

$$\begin{aligned} \lambda^p \int_{x_1(\tau)}^{x_1(t)} g_0(u) du &= \lambda^p \int_{\tau}^t g_0(x_1(s))x_1'(s) ds \\ &= - \int_{\tau}^t (\varphi_p(x_1'(s + \sigma)))' x_1'(s) ds - \lambda^p \int_{\tau}^t f(x_1(s + \sigma))x_1'(s + \sigma)x_1'(s) ds \\ &\quad - \lambda^p \int_{\tau}^t g_1(s + \sigma, x_1(s))x_1'(s) ds + \lambda^p \int_{\tau}^t e(s + \sigma)x_1'(s) ds. \end{aligned} \tag{3.21}$$

By (3.14), (3.15), (3.16), (3.17), and (3.18), we have

$$\begin{aligned} &\left| \int_{\tau}^t (\varphi_p(x_1'(t + \sigma)))' x_1'(s) ds \right| \\ &\leq \int_{\tau}^t |(\varphi_p(x_1'(t + \sigma)))'| |x_1'(s)| ds \\ &\leq |x_1'|_{\infty} \int_0^T |(\varphi_p(x_1'(t + \sigma)))'| dt \\ &\leq \lambda^p |x_1'|_{\infty} \left( \int_0^T |f(x_1(t))| |x_1'(t)| dt + \int_0^T |g(t, x_1(t - \sigma))| dt + \int_0^T |e(t)| dt \right) \\ &\leq \lambda^p M_2^{p-1} (|f|_{M_1} M_1^{\frac{1}{p}} T^{\frac{1}{q}} + 2(|\psi|_{\infty} + \varepsilon) T M_1^{p-1} + 2T^{\frac{1}{2}} |g_{\varepsilon}^+|_2 + T^{\frac{1}{2}} |e|_2). \end{aligned}$$

We have

$$\begin{aligned} \left| \int_{\tau}^t f(x_1(s + \sigma))x_1'(s + \sigma)x_1'(s) ds \right| &\leq |f|_{M_1} \left( \int_0^T |x_1'(s)| ds \right)^2 \\ &\leq |f|_{M_1} T^{\frac{2}{q}} \left( \int_0^T |x_1'(t)|^p dt \right)^{\frac{2}{p}} \\ &\leq |f|_{M_1} T^{\frac{2}{q}} (M_1')^{\frac{2}{p}}, \\ \left| \int_{\tau}^t g(s + \sigma, x_1(s))x_1'(s) ds \right| &\leq |x_1'| \int_0^T |g(t, x(t - \sigma))| dt \leq M_2^{p-1} \sqrt{T} |g_{M_1}|_2, \end{aligned}$$

where  $g_{M_1} = \max_{0 \leq x \leq M_1} |g_1(t, x)| \in L^2(0, T)$  is as in (H<sub>3</sub>). We have

$$\left| \int_{\tau}^t e(t + \sigma)x_1'(t) dt \right| \leq M_2^{p-1} T^{\frac{1}{2}} |e|_2.$$

From these inequalities we can derive from (3.21) that

$$\left| \int_{x_1(\tau)}^{x_1(t)} g_0(u) du \right| \leq M_3', \tag{3.22}$$

for some constant  $M_3'$  which is independent on  $\lambda, x$ , and  $t$ . In view of the strong force condition (H<sub>4</sub>), we know that there exists a constant  $M_3 > 0$  such that

$$x_1(t) \geq M_3, \quad \forall t \in [\tau, T]. \tag{3.23}$$

The case  $t \in [0, \tau]$  can be treated similarly.

From (3.14), (3.17), and (3.23), we let

$$\Omega = \{x = (x_1, x_2)^\top : E_1 \leq |x_1|_\infty \leq E_2, |x_2|_\infty \leq E_3, \forall t \in [0, T]\},$$

where  $0 < E_1 < \min(M_3, D_1)$ ,  $E_2 > \max(M_1, D_2)$ ,  $E_3 > M_2$ .  $\Omega_2 = \{x : x \in \partial\Omega \cap \text{Ker} L\}$  then  $\forall x \in \partial\Omega \cap \text{Ker} L$

$$QNx = \frac{1}{T} \int_0^T \begin{pmatrix} \varphi_q(x_2(t)) \\ -f(x_1(t))x_1'(t) - g(t, x_1(t - \sigma)) + e(t) \end{pmatrix} dt.$$

If  $QNx = 0$ , then  $x_2(t) = 0$ ,  $x_1 = E_2$  or  $-E_2$ . But if  $x_1(t) = E_2$ , we know

$$0 = \int_0^T \{g(t, E_2) - e(t)\} dt.$$

From assumption  $(H_2)$ , we have  $x_1(t) \leq D_2 \leq E_2$ , which yields a contradiction. Similarly if  $x_1 = -E_2$ . We also have  $QNx \neq 0$ , i.e.,  $\forall x \in \partial\Omega \cap \text{Ker} L, x \notin \text{Im} L$ , so conditions (1) and (2) of Lemma 2.1 are both satisfied. Define the isomorphism  $J : \text{Im} Q \rightarrow \text{Ker} L$  as follows:

$$J(x_1, x_2)^\top = (x_2, -x_1)^\top.$$

Let  $H(\mu, x) = -\mu x + (1 - \mu)JQNx$ ,  $(\mu, x) \in [0, 1] \times \Omega$ , then  $\forall (\mu, x) \in (0, 1) \times (\partial\Omega \cap \text{Ker} L)$ ,

$$H(\mu, x) = \begin{pmatrix} -\mu x_1 - \frac{1-\mu}{T} \int_0^T [g(t, x_1) - e(t)] dt \\ -\mu x_2 - (1 - \mu)|x_2|^{p-2}x_2 \end{pmatrix}.$$

We have  $\int_0^T e(t) dt = 0$ . So, we can get

$$H(\mu, x) = \begin{pmatrix} -\mu x_1 - \frac{1-\mu}{T} \int_0^T g(t, x_1) dt \\ -\mu x_2 - (1 - \mu)|x_2|^{p-2}x_2 \end{pmatrix},$$

$$\forall (\mu, x) \in (0, 1) \times (\partial\Omega \cap \text{Ker} L).$$

From  $(H_2)$ , it is obvious that  $x^\top H(\mu, x) < 0$ ,  $\forall (\mu, x) \in (0, 1) \times (\partial\Omega \cap \text{Ker} L)$ . Hence

$$\begin{aligned} \deg\{JQN, \Omega \cap \text{Ker} L, 0\} &= \deg\{H(0, x), \Omega \cap \text{Ker} L, 0\} \\ &= \deg\{H(1, x), \Omega \cap \text{Ker} L, 0\} \\ &= \deg\{I, \Omega \cap \text{Ker} L, 0\} \neq 0. \end{aligned}$$

So condition (3) of Lemma 2.1 is satisfied. By applying Lemma 2.1, we conclude that the equation  $Lx = Nx$  has a solution  $x = (x_1, x_2)^\top$  on  $\bar{\Omega} \cap D(L)$ , i.e., (2.1) has an  $T$ -periodic solution  $x_1(t)$ . □

Finally, we present an example to illustrate our result.

**Example 3.1** Consider the  $p$ -Laplacian Liénard type differential equation with singularity and deviating argument:

$$(\varphi_p(x'(t)))' + f(x(t))x'(t) + \frac{1}{5}(\cos 2t + 2)x^3(t - \sigma) - \frac{1}{x^\kappa(t - \sigma)} = \sin 2t, \tag{3.24}$$

where  $\kappa \geq 1$  and  $p = 4$ ,  $f$  is a continuous function,  $\sigma$  is a constant, and  $0 \leq \sigma < T$ .

It is clear that  $T = \pi$ ,  $g(t, x) = \frac{1}{5}(\cos 2t + 2)x^3(t - \sigma) - \frac{1}{x^\kappa(t - \sigma)}$ ,  $\psi(t) = \frac{1}{5}(\cos 2t + 2)$ . It is obvious that  $(H_1)$ - $(H_4)$  hold. Now we consider the assumption  $(H_5)$ . Since  $|\psi|_\infty \leq \frac{3}{5}$ , we have

$$\left(\frac{T}{\pi_p}\right)^p |\psi|_\infty = \left(\frac{T}{\frac{2\pi(p-1)^{1/p}}{p \sin(\pi/p)}}\right)^p |\psi|_\infty \leq \left(\frac{\pi}{\frac{2\pi(4-1)^{1/4}}{4 \sin \pi/4}}\right)^4 \times \frac{3}{5} = \frac{4}{5} < 1.$$

So by Theorem 3.1, we know (3.24) has at least one positive  $\pi$ -periodic solution.

**Competing interests**

The authors declare that they have no competing interests.

**Authors' contributions**

YX and ZBC worked together in the derivation of the mathematical results. Both authors read and approved the final manuscript.

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