

*Research Article*

# On the Oscillation of Second-Order Neutral Delay Differential Equations

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Some new oscillation criteria for the second-order neutral delay differential equation  $(r(t)z'(t))' + q(t)x(\sigma(t)) = 0$ ,  $t \geq t_0$  are established, where  $\int_{t_0}^{\infty} (1/r(t))dt = \infty$ ,  $z(t) = x(t) + p(t)x(\tau(t))$ ,  $0 \leq p(t) \leq p_0 < \infty$ ,  $q(t) > 0$ . These oscillation criteria extend and improve some known results. An example is considered to illustrate the main results.

## 1. Introduction

Neutral differential equations find numerous applications in natural science and technology. For instance, they are frequently used for the study of distributed networks containing lossless transmission lines; see Hale [1]. In recent years, many studies have been made on the oscillatory behavior of solutions of neutral delay differential equations, and we refer to the recent papers [2–23] and the references cited therein.

This paper is concerned with the oscillatory behavior of the second-order neutral delay differential equation

$$(r(t)z'(t))' + q(t)x(\sigma(t)) = 0, \quad t \geq t_0, \quad (1.1)$$

where  $z(t) = x(t) + p(t)x(\tau(t))$ .

In what follows we assume that

$$(I_1) \quad p, q \in C([t_0, \infty), \mathbb{R}), 0 \leq p(t) \leq p_0 < \infty, q(t) > 0,$$

$$(I_2) \quad r \in C([t_0, \infty), \mathbb{R}), r(t) > 0, \int_{t_0}^{\infty} (1/r(t)) dt = \infty,$$

$$(I_3) \quad \tau, \sigma \in C([t_0, \infty), \mathbb{R}), \tau(t) \leq t, \sigma(t) \leq t, \tau'(t) = \tau_0 > 0, \sigma'(t) > 0, \lim_{t \rightarrow \infty} \tau(t) = \lim_{t \rightarrow \infty} \sigma(t) = \infty, \tau(\sigma(t)) = \sigma(\tau(t)), \text{ where } \tau_0 \text{ is a constant.}$$

Some known results are established for (1.1) under the condition  $0 \leq p(t) < 1$ . Grammatikopoulos et al. [6] obtained that if  $0 \leq p(t) \leq 1$ ,  $q(t) \geq 0$  and  $\int_{t_0}^{\infty} q(s)[1-p(s-\sigma)] ds = \infty$ , then the second-order neutral delay differential equation

$$[y(t) + p(t)y(t-\tau)]'' + q(t)y(t-\sigma) = 0 \quad (1.2)$$

oscillates. In [13], by employing Riccati technique and averaging functions method, Ruan established some general oscillation criteria for second-order neutral delay differential equation

$$[a(t)(x(t) + p(t)x(t-\tau))]'' + q(t)f(x(t-\sigma)) = 0. \quad (1.3)$$

Xu and Meng [18] as well as Zhuang and Li [23] studied the oscillation of the second-order neutral delay differential equation

$$[r(t)(y(t) + p(t)y(\tau(t)))]'' + \sum_{i=1}^n q_i(t)f_i(y(\sigma_i(t))) = 0. \quad (1.4)$$

Motivated by [11], we will further the investigation and offer some more general new oscillation criteria for (1.1), by employing a class of function  $Y$ , operator  $T$ , and the Riccati technique and averaging technique.

Following [11], we say that a function  $\phi = \phi(t, s, l)$  belongs to the function class  $Y$ , denoted by  $\phi \in Y$  if  $\phi \in C(E, \mathbb{R})$ , where  $E = \{(t, s, l) : t_0 \leq l \leq s \leq t < \infty\}$ , which satisfies  $\phi(t, t, l) = 0$ ,  $\phi(t, l, l) = 0$ , and  $\phi(t, s, l) > 0$ , for  $l < s < t$ , and has the partial derivative  $\partial\phi/\partial s$  on  $E$  such that  $\partial\phi/\partial s$  is locally integrable with respect to  $s$  in  $E$ . By choosing the special function  $\phi$ , it is possible to derive several oscillation criteria for a wide range of differential equations.

Define the operator  $T[\cdot; l, t]$  by

$$T[g; l, t] = \int_l^t \phi(t, s, l)g(s)ds, \quad (1.5)$$

for  $t \geq s \geq l \geq t_0$  and  $g \in C^1[t_0, \infty)$ . The function  $\varphi = \varphi(t, s, l)$  is defined by

$$\frac{\partial\phi(t, s, l)}{\partial s} = \varphi(t, s, l)\phi(t, s, l). \quad (1.6)$$

It is easy to see that  $T[\cdot; l, t]$  is a linear operator and that it satisfies

$$T[g'; l, t] = -T[g\varphi; l, t], \quad \text{for } g(s) \in C^1[t_0, \infty). \quad (1.7)$$

## 2. Main Results

In this section, we give some new oscillation criteria for (1.1). We start with the following oscillation criteria.

**Theorem 2.1.** *If*

$$\int_{t_0}^{\infty} Q(t) dt = \infty, \quad (2.1)$$

where  $Q(t) := \min\{q(t), q(\tau(t))\}$ , then (1.1) oscillates.

*Proof.* Let  $x$  be a nonoscillatory solution of (1.1). Then there exists  $t_1 \geq t_0$  such that  $x(t) \neq 0$ , for all  $t \geq t_1$ . Without loss of generality, we assume that  $x(t) > 0$ ,  $x(\tau(t)) > 0$ , and  $x(\sigma(t)) > 0$ , for all  $t \geq t_1$ . From (1.1), we have

$$(r(t)z'(t))' = -q(t)x(\sigma(t)) < 0, \quad t \geq t_1. \quad (2.2)$$

Therefore  $r(t)z'(t)$  is a decreasing function. We claim that  $z'(t) > 0$  for  $t \geq t_1$ . Otherwise, there exists  $t_2 \geq t_1$  such that  $z'(t_2) < 0$ . Then from (2.2) we obtain

$$r(t)z'(t) \leq r(t_2)z'(t_2), \quad t \geq t_2, \quad (2.3)$$

and hence,

$$z(t) \leq z(t_2) - [-r(t_2)z'(t_2)] \int_{t_2}^t \frac{ds}{r(s)}. \quad (2.4)$$

Taking  $t \rightarrow \infty$ , we get  $z(t) \rightarrow -\infty$ ,  $t \rightarrow \infty$ . This contradiction proves that  $z'(t) > 0$  for  $t \geq t_1$ . Using definition of  $z(t)$  and applying (1.1), we get for sufficiently large  $t$

$$(r(t)z'(t))' + q(t)x(\sigma(t)) + p_0q(\tau(t))x(\sigma(\tau(t))) + \frac{p_0}{\tau'(t)}(r(\tau(t))z'(\tau(t)))' = 0, \quad (2.5)$$

and thus,

$$(r(t)z'(t))' + Q(t)z(\sigma(t)) + \frac{p_0}{\tau'(t)}(r(\tau(t))z'(\tau(t)))' \leq 0. \quad (2.6)$$

Integrating (2.6) from  $t_3$  ( $\geq t_1$ ) to  $t$ , we obtain

$$\int_{t_3}^t (r(s)z'(s))' ds + \int_{t_3}^t Q(s)z(\sigma(s)) ds + p_0 \int_{t_3}^t \frac{1}{\tau'(s)} (r(\tau(s))z'(\tau(s)))' ds \leq 0. \quad (2.7)$$

Noting that  $\tau'(t) = \tau_0 > 0$ , we have

$$\begin{aligned} \int_{t_3}^t Q(s)z(\sigma(s)) ds &\leq -\int_{t_3}^t (r(s)z'(s))' ds - p_0 \int_{t_3}^t \frac{1}{(\tau'(s))^2} (r(\tau(s))z'(\tau(s)))' d(\tau(s)) \\ &= -\int_{t_3}^t (r(s)z'(s))' ds - \frac{p_0}{\tau_0^2} \int_{\tau(t_3)}^{\tau(t)} (r(u)z'(u))' du \\ &= r(t_3)z'(t_3) - r(t)z'(t) + \frac{p_0}{\tau_0^2} r(\tau(t_3))z'(\tau(t_3)) - \frac{p_0}{\tau_0^2} r(\tau(t))z'(\tau(t)). \end{aligned} \quad (2.8)$$

Since  $z'(t) > 0$  for  $t \geq t_1$ , we can find a constant  $c > 0$  such that  $z(\sigma(t)) \geq c$  for  $t \geq t_3 \geq t_1$ . Then from (2.8) and the fact that  $r(t)z'(t)$  is eventually decreasing, we have

$$\int_{t_3}^{\infty} Q(t) dt < \infty, \quad (2.9)$$

which is a contradiction to (2.1). This completes the proof.  $\square$

**Theorem 2.2.** Assume that  $\sigma(t) \leq \tau(t)$ , and there exist functions  $\phi \in Y$  and  $k \in C^1([t_0, \infty), R^+)$  such that

$$\limsup_{t \rightarrow \infty} T \left[ k(s)Q(s) - \frac{(1 + (p_0/\tau_0))(\varphi + (k'(s)/k(s)))^2}{4} \frac{r(\sigma(s))k(s)}{\sigma'(s)}; l, t \right] > 0, \quad (2.10)$$

where  $Q(t)$  is defined as in Theorem 2.1, the operator  $T$  is defined by (1.5), and  $\varphi = \varphi(t, s, l)$  is defined by (1.6). Then every solution  $x$  of (1.1) is oscillatory.

*Proof.* Let  $x$  be a nonoscillatory solution of (1.1). Then there exists  $t_1 \geq t_0$  such that  $x(t) \neq 0$  for all  $t \geq t_1$ . Without loss of generality, we assume that  $x(t) > 0$ ,  $x(\tau(t)) > 0$ , and  $x(\sigma(t)) > 0$ , for all  $t \geq t_1$ . Define

$$\omega(t) = k(t) \frac{r(t)z'(t)}{z(\sigma(t))}, \quad t \geq t_1. \quad (2.11)$$

Then  $\omega(t) > 0$  and

$$\omega'(t) = k'(t) \frac{r(t)z'(t)}{z(\sigma(t))} + k(t) \frac{(r(t)z'(t))' z(\sigma(t)) - r(t)z'(t)z'(\sigma(t))\sigma'(t)}{z^2(\sigma(t))}. \quad (2.12)$$

By (2.2) and the fact  $z'(t) > 0$ , we get

$$\frac{z'(\sigma(t))}{z'(t)} \geq \frac{r(t)}{r(\sigma(t))}. \quad (2.13)$$

From (2.11), (2.12), and (2.13), we have

$$\omega'(t) \leq k(t) \frac{(r(t)z'(t))'}{z(\sigma(t))} + \frac{k'(t)}{k(t)}\omega(t) - \frac{\sigma'(t)}{r(\sigma(t))k(t)}\omega^2(t). \quad (2.14)$$

Similarly, define

$$v(t) = k(t) \frac{r(\tau(t))z'(\tau(t))}{z(\sigma(t))}, \quad t \geq t_1. \quad (2.15)$$

Then  $v(t) > 0$  and

$$v'(t) = k'(t) \frac{r(\tau(t))z'(\tau(t))}{z(\sigma(t))} + k(t) \frac{(r(\tau(t))z'(\tau(t)))'z(\sigma(t)) - r(\tau(t))z'(\tau(t))z'(\sigma(t))\sigma'(t)}{z^2(\sigma(t))}. \quad (2.16)$$

By (2.2) and the facting  $z'(t) > 0$ , noting that  $\sigma(t) \leq \tau(t)$ , we get

$$\frac{z'(\sigma(t))}{z'(\tau(t))} \geq \frac{r(\tau(t))}{r(\sigma(t))}. \quad (2.17)$$

From (2.15), (2.16), and (2.17), we have

$$v'(t) \leq k(t) \frac{(r(\tau(t))z'(\tau(t)))'}{z(\sigma(t))} + \frac{k'(t)}{k(t)}v(t) - \frac{\sigma'(t)}{r(\sigma(t))k(t)}v^2(t). \quad (2.18)$$

Therefore, from (2.14) and (2.18), we get

$$\begin{aligned} \omega'(t) + \frac{p_0}{\tau_0}v'(t) &\leq k(t) \frac{(r(t)z'(t))'}{z(\sigma(t))} + \frac{p_0}{\tau_0}k(t) \frac{(r(\tau(t))z'(\tau(t)))'}{z(\sigma(t))} \\ &+ \frac{k'(t)}{k(t)}\omega(t) - \frac{\sigma'(t)}{r(\sigma(t))k(t)}\omega^2(t) + \frac{p_0}{\tau_0} \frac{k'(t)}{k(t)}v(t) - \frac{p_0}{\tau_0} \frac{\sigma'(t)}{r(\sigma(t))k(t)}v^2(t). \end{aligned} \quad (2.19)$$

From (2.6), we obtain

$$\begin{aligned} \omega'(t) + \frac{p_0}{\tau_0}v'(t) &\leq -k(t)Q(t) + \frac{k'(t)}{k(t)}\omega(t) - \frac{\sigma'(t)}{r(\sigma(t))k(t)}\omega^2(t) \\ &+ \frac{p_0}{\tau_0} \frac{k'(t)}{k(t)}v(t) - \frac{p_0}{\tau_0} \frac{\sigma'(t)}{r(\sigma(t))k(t)}v^2(t). \end{aligned} \quad (2.20)$$

Applying  $T[\cdot; l, t]$  to (2.20), we get

$$\begin{aligned} & T\left[\omega'(s) + \frac{p_0}{\tau_0} \nu'(s); l, t\right] \\ & \leq T\left[-k(s)Q(s) + \frac{k'(s)}{k(s)}\omega(s) - \frac{\sigma'(s)}{r(\sigma(s))k(s)}\omega^2(s) + \frac{p_0}{\tau_0} \frac{k'(s)}{k(s)}\nu(s) - \frac{p_0}{\tau_0} \frac{\sigma'(s)}{r(\sigma(s))k(s)}\nu^2(s); l, t\right]. \end{aligned} \quad (2.21)$$

By (1.7) and the above inequality, we obtain

$$\begin{aligned} & T[k(s)Q(s); l, t] \\ & \leq T\left[\left(\varphi + \frac{k'(s)}{k(s)}\right)\omega(s) - \frac{\sigma'(s)}{r(\sigma(s))k(s)}\omega^2(s) + \frac{p_0}{\tau_0} \left(\varphi + \frac{k'(s)}{k(s)}\right)\nu(s) - \frac{p_0}{\tau_0} \frac{\sigma'(s)}{r(\sigma(s))k(s)}\nu^2(s); l, t\right]. \end{aligned} \quad (2.22)$$

Hence, from (2.22) we have

$$T[k(s)Q(s); l, t] \leq T\left[\left(\frac{(\varphi + (k'(s)/k(s)))^2}{4} + \frac{(p_0/\tau_0)(\varphi + (k'(s)/k(s)))^2}{4}\right) \frac{r(\sigma(s))k(s)}{\sigma'(s)}; l, t\right], \quad (2.23)$$

that is,

$$T\left[k(s)Q(s) - \frac{(1 + (p_0/\tau_0))(\varphi + (k'(s)/k(s)))^2}{4} \frac{r(\sigma(s))k(s)}{\sigma'(s)}; l, t\right] \leq 0. \quad (2.24)$$

Taking the super limit in the above inequality, we get

$$\limsup_{t \rightarrow \infty} T\left[k(s)Q(s) - \frac{(1 + (p_0/\tau_0))(\varphi + (k'(s)/k(s)))^2}{4} \frac{r(\sigma(s))k(s)}{\sigma'(s)}; l, t\right] \leq 0, \quad (2.25)$$

which contradicts (2.10). This completes the proof.  $\square$

*Remark 2.3.* With the different choice of  $k$  and  $\phi$ , Theorem 2.2 can be stated with different conditions for oscillation of (1.1). For example, if we choose  $\phi(t, s, l) = \rho(s)(t-s)^\sigma(s-l)^\mu$  for  $\sigma > 1/2, \mu > 1/2, \rho \in C^1([t_0, \infty), (0, \infty))$ , then

$$\varphi(t, s, l) = \frac{\rho'(s)}{\rho(s)} + \frac{\mu t - (\sigma + \mu)s + \sigma l}{(t-s)(s-l)}. \quad (2.26)$$

By Theorem 2.2 we can obtain the oscillation criterion for (1.1), the details are left to the reader.

For an application, we give the following example to illustrate the main results.

*Example 2.4.* Consider the following equation:

$$(x(t) + 2x(t - \pi))'' + x(t - \pi) = 0, \quad t \geq t_0. \quad (2.27)$$

Let  $r(t) = 1$ ,  $p(t) = 2$ ,  $q(t) = 1$ , and  $\tau(t) = \sigma(t) = t - \pi$ , then by Theorem 2.1 every solution of (2.27) oscillates; for example,  $x(t) = \sin t$  is an oscillatory solution of (2.27).

*Remark 2.5.* The recent results cannot be applied in (2.27) since  $p(t) = 2 > 1$ ; so our results are new ones.

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