## Research Article

# Eigenvalue Problems for $p$-Laplacian Functional Dynamic Equations on Time Scales 

Changxiu Song<br>School of Applied Mathematics, Guangdong University of Technology, Guangzhou 510006, China

Correspondence should be addressed to Changxiu Song, scx168@sohu.com
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This paper is concerned with the existence and nonexistence of positive solutions of the $p$-Laplacian functional dynamic equation on a time scale, $\left[\phi_{p}\left(x^{\Delta}(t)\right)\right]^{\nabla}+l a(t) f(x(t), x(u(t)))=0, t \in(0, T)$, $x_{0}(t)=\psi(t), t \in[-\tau, 0], x(0)-B_{0}\left(x^{\Delta}(0)\right)=0, x^{\Delta}(T)=0$. We show that there exists a $\lambda^{*}>0$ such that the above boundary value problem has at least two, one, and no positive solutions for $0<\lambda<\lambda^{*}, \lambda=\lambda^{*}$ and $\lambda>\lambda^{*}$, respectively.

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## 1. Introduction

Let $\mathbb{T}$ be a closed nonempty subset of $\mathbb{R}$, and let $\mathbb{T}$ have the subspace topology inherited from the Euclidean topology on $\mathbb{R}$. In some of the current literature, $\mathbb{T}$ is called a time scale (please see $[1,2]$ ). For notation, we will use the convention that, for each interval $J$ of $\mathbb{R}, J$ will denote time-scale interval, that is, $J:=J \cap \mathbb{T}$.

In this paper, let $\mathbb{T}$ be a time scale such that $-\tau, 0, T \in \mathbb{T}$. We are concerned with the existence of positive solutions of the $p$-Laplacian dynamic equation on a time scale

$$
\begin{gather*}
{\left[\phi_{p}\left(x^{\Delta}(t)\right)\right]^{\nabla}+\lambda a(t) f(x(t), x(\mu(t)))=0, \quad t \in(0, T),}  \tag{1.1}\\
x_{0}(t)=\psi(t), \quad t \in[-\tau, 0], \quad x(0)-B_{0}\left(x^{\Delta}(0)\right)=0, \quad x^{\Delta}(T)=0,
\end{gather*}
$$

where $\phi_{p}(u)$ is the $p$-Laplacian operator, that is, $\phi_{p}(u)=|u|^{p-2} u, p>1,\left(\phi_{p}\right)^{-1}(u)=\phi_{q}(u)$, where $1 / p+1 / q=1$.
(H1) The function $f:\left(\mathbb{R}^{+}\right)^{2} \rightarrow \mathbb{R}^{+}$is continuous and nondecreasing about each element; $f(0,0) \geq c>0$.
(H2) The function $a: \mathbb{T} \rightarrow \mathbb{R}^{+}$is left dense continuous (i.e., $a \in C_{l d}\left(\mathbb{T}, \mathbb{R}^{+}\right)$) and does not vanish identically on any closed subinterval of $[0, T]$. Here $C_{l d}\left(\mathbb{T}, \mathbb{R}^{+}\right)$denotes the set of all left dense continuous functions from $\mathbb{T}$ to $\mathbb{R}^{+}$.
(H3) $\psi:[-\tau, 0] \rightarrow \mathbb{R}^{+}$is continuous and $\tau>0$.
(H4) $\mu:[0, T] \rightarrow[-\tau, T]$ is continuous, $\mu(t) \leq t$ for all $t$.
(H5) $B_{0}: \mathbb{R} \rightarrow \mathbb{R}$ is continuous and nondecreasing; $B_{0}(k s)=k B_{0}(s), k \in \mathbb{R}^{+}$and satisfies that there exist $\beta \geq \delta>0$ such that

$$
\begin{equation*}
\delta s \leq B_{0}(s) \leq \beta s \quad \text { for } s \in \mathbb{R}^{+} . \tag{1.2}
\end{equation*}
$$

(H6) $\lim _{x \rightarrow \infty} f(x, \psi(s)) / x^{p-1}=\infty$ uniformly in $s \in[-\tau, 0]$.
$p$-Laplacian problems with two-, three-, m-point boundary conditions for ordinary differential equations and finite difference equations have been studied extensively, for example, see $[1-4]$ and references therein. However, there are not many concerning the $p$ Laplacian problems on time scales, especially for $p$-Laplacian functional dynamic equations on time scales.

The motivations for the present work stems from many recent investigations in [5-10] and references therein. Especially, Kaufmann and Raffoul [7] considered a nonlinear functional dynamic equation on a time scale and obtained sufficient conditions for the existence of positive solutions, Li and Liu [10] studied the eigenvalue problem for second-order nonlinear dynamic equations on time scales. In this paper, our results show that the number of positive solutions of (1.1) is determined by the parameter $\lambda$. That is to say, we prove that there exists a $\lambda^{*}>0$ such that (1.1) has at least two, one, and no positive solutions for $0<\lambda<\lambda^{*}, \lambda=\lambda^{*}$ and $\lambda>\lambda^{*}$, respectively.

For convenience, we list the following well-known definitions which can be found in [11-13] and the references therein.

Definition 1.1. For $t<\sup \mathbb{T}$ and $r>\inf \mathbb{T}$, define the forward jump operator $\sigma$ and the backward jump operator $\rho$, respectively, as

$$
\begin{equation*}
\sigma(t)=\inf \{\tau \in \mathbb{T} \mid \tau>t\} \in \mathbb{T}, \quad \rho(r)=\sup \{\tau \in \mathbb{T} \mid \tau<r\} \in \mathbb{T} \quad \forall t, r \in \mathbb{T} . \tag{1.3}
\end{equation*}
$$

If $\sigma(t)>t, t$ is said to be right scattered, and if $\rho(r)<r, r$ is said to be left scattered. If $\sigma(t)=t, t$ is said to be right dense, and if $\rho(r)=r, r$ is said to be left dense. If $\mathbb{T}$ has a right-scattered minimum $m$, define $\mathbb{T}_{\kappa}=\mathbb{T}-\{m\}$; otherwise set $\mathbb{T}_{\kappa}=\mathbb{T}$. If $\mathbb{T}$ has a left-scattered maximum $M$, define $\mathbb{T}^{\kappa}=\mathbb{T}-\{M\}$; otherwise set $\mathbb{T}^{\kappa}=\mathbb{T}$.

Definition 1.2. For $x: \mathbb{T} \rightarrow \mathbb{R}$ and $t \in \mathbb{T}^{\kappa}$, define the deltaderivative of $x(t), x^{\Delta}(t)$, to be the number (when it exists), with the property that, for any $\varepsilon>0$, there is a neighborhood $U$ of $t$ such that

$$
\begin{equation*}
\left|[x(\sigma(t))-x(s)]-x^{\Delta}(t)[\sigma(t)-s]\right|<\varepsilon|\sigma(t)-s| \quad \forall s \in U . \tag{1.4}
\end{equation*}
$$

For $x: \mathbb{T} \rightarrow \mathbb{R}$ and $t \in \mathbb{T}_{\kappa}$, define the nabla derivative of $x(t), x^{\nabla}(t)$, to be the number (when it exists), with the property that, for any $\varepsilon>0$, there is a neighborhood $V$ of $t$ such that

$$
\begin{equation*}
\left|[x(\rho(t))-x(s)]-x^{\nabla}(t)[\rho(t)-s]\right|<\varepsilon|\rho(t)-s| \quad \forall s \in V . \tag{1.5}
\end{equation*}
$$

If $\mathbb{T}=\mathbb{R}$, then $x^{\Delta}(t)=x^{\nabla}(t)=x^{\prime}(t)$. If $\mathbb{T}=\mathbb{Z}$, then $x^{\Delta}(t)=x(t+1)-x(t)$ is forward difference operator while $x^{\nabla}(t)=x(t)-x(t-1)$ is the backward difference operator.

Definition 1.3. If $F^{\Delta}(t)=f(t)$, then define the delta integral by $\int_{a}^{t} f(s) \Delta s=F(t)-F(a)$. If $\Phi^{\nabla}(t)=$ $f(t)$, then define the nabla integral by $\int_{a}^{t} f(s) \nabla s=\Phi(t)-\Phi(a)$.

The following lemma is crucial to prove our main results.
Lemma 1.4 ([14]). Let $E$ be a Banach space and let $P$ be a cone in E. For $r>0$, define $P_{r}=\{x \in P$ : $\|x\|<r\}$. Assume that $F: \bar{P}_{r} \rightarrow P$ is completely continuous such that $F x \neq x$ for $x \in \partial P_{r}=\{x \in P$ : $\|x\|=r\}$.
(i) If $\|F x\| \geq\|x\|$ for $x \in \partial P_{r}$, then $i\left(F, P_{r}, P\right)=0$.
(ii) If $\|F x\| \leq\|x\|$ for $x \in \partial P_{r}$, then $i\left(F, P_{r}, P\right)=1$.

## 2. Positive solutions

We note that $x(t)$ is a solution of (1.1) if and only if

$$
x(t)= \begin{cases}B_{0}\left(\phi_{q}\left(\int_{0}^{T} \operatorname{la}(r) f(x(r), x(\mu(r))) \nabla r\right)\right) &  \tag{2.1}\\ \quad+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \operatorname{la(r)f(x(r),x(\mu (r)))\nabla r)\Delta s,}\right. & t \in[0, T] \\ \psi(t), & t \in[-\tau, 0]\end{cases}
$$

Let $E=C_{\text {ld }}([0, T], \mathbb{R})$ be endowed with the norm $\|x\|=\max _{t \in[0, T]}|x(t)|$ and define the cone of $E$ by

$$
\begin{equation*}
P=\left\{x \in E: x(t) \geq \frac{\delta}{T+\beta}\|x\| \text { for } t \in[0, T]\right\} . \tag{2.2}
\end{equation*}
$$

Clearly, $E$ is a Banach space with the norm $\|x\|$. For each $x \in E$, extend $x(t)$ to $[-\tau, T]$ with $x(t)=\psi(t)$ for $t \in[-\tau, 0]$.

Define $F_{\lambda}: P \rightarrow E$ as

$$
\begin{align*}
F_{\curlywedge} x(t)= & B_{0}\left(\phi_{q}\left(\int_{0}^{T} \operatorname{la}(r) f(x(r), x(\mu(r))) \nabla r\right)\right)  \tag{2.3}\\
& +\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \lambda a(r) f(x(r), x(\mu(r))) \nabla r\right) \Delta s, \quad t \in[0, T]
\end{align*}
$$

We seek a fixed point, $x_{1}$, of $F_{\lambda}$ in the cone $P$. Define

$$
x(t)= \begin{cases}x_{1}(t), & t \in[0, T]  \tag{2.4}\\ \psi(t), & t \in[-\tau, 0]\end{cases}
$$

Then $x(t)$ denotes a positive solution of BVP (1.1).

It follows from (2.3) that the following lemma holds.
Lemma 2.1. Let $F_{\lambda}$ be defined by (2.3). If $x \in P$, then
(i) $F_{\lambda}(P) \subset P$.
(ii) $F_{\lambda}: P \rightarrow P$ is completely continuous.

The proof of Lemma 2.1 can be found in [15].
We need to define further subsets of $[0, T]$ with respect to the delay $\mu$. Set

$$
\begin{equation*}
\Upsilon_{1}:=\{t \in[0, T]: \mu(t)<0\} ; \quad \Upsilon_{2}:=\{t \in[0, T]: \mu(t) \geq 0\} . \tag{2.5}
\end{equation*}
$$

Throughout this paper, we assume $Y_{1} \neq \varnothing$ and $\phi_{q}\left(\int_{Y_{1}} a(r) \nabla r\right)>0$.
Lemma 2.2. Suppose that (H1)-(H5) hold. Then there exists a $\lambda^{*}>0$ such that the operator $F_{\lambda}$ has a fixed point $x^{*} \in P \backslash\{\theta\}$ at $\lambda^{*}$, where $\theta$ is the zero element of the Banach space $E$.

Proof. Set

$$
\begin{equation*}
e(t)=B_{0}\left(\phi_{q}\left(\int_{0}^{T} a(r) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} a(r) \nabla r\right) \Delta s, \quad t \in[0, T] . \tag{2.6}
\end{equation*}
$$

We know that $e \in P$. Let $\lambda^{*}=M_{f_{e}}^{-1}$, where

$$
\begin{align*}
& M_{f_{e}}=\max _{r \in[0, T]} f(e(r), e(\mu(r))) \geq c>0, \\
&\left(F_{\lambda^{*}} x\right)(t)= B_{0}\left(\phi_{q}\left(\int_{0}^{T} \lambda^{*} a(r) f(x(r), x(\mu(r))) \nabla r\right)\right)  \tag{2.7}\\
&+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \lambda^{*} a(r) f(x(r), x(\mu(r))) \nabla r\right) \Delta s, \quad t \in[0, T] .
\end{align*}
$$

From above, we have

$$
\begin{equation*}
e(t) \geq\left(F_{\lambda^{*}} e\right)(t) \tag{2.8}
\end{equation*}
$$

Let $x_{0}(t)=e(t)$ and $x_{n}(t)=\left(F_{\lambda^{*}} x_{n-1}\right)(t), n=1,2, \ldots, t \in[0, T]$. Then

$$
\begin{equation*}
x_{0}(t) \geq x_{1}(t) \geq \cdots \geq x_{n}(t) \geq \cdots \geq\left(c \lambda^{*}\right)^{q-1} e(t) \tag{2.9}
\end{equation*}
$$

By the Lebesgue dominated convergence theorem [16] together with (H3), it follows that $\left\{x_{n}\right\}_{n=0}^{\infty}=\left\{F_{\lambda^{*}}^{n} x_{0}\right\}_{n=0}^{\infty}$ decreases to a fixed point $x^{*} \in P \backslash\{\theta\}$ of the operator $F_{\lambda^{*}}$. The proof is complete.

Lemma 2.3. Suppose that (H1)-(H6) hold and that $\mathbf{I} \subset[b, \infty)$ for some $b>0$. Then there exists $a$ constant $C_{I}>0$ such that for all $\lambda \in \mathbf{I}$ and all possible fixed points $x$ of $F_{\lambda}$ at $\lambda$, one has $\|x\|<C_{I}$.

Proof. Set

$$
\begin{equation*}
S=\left\{x \in P: F_{\lambda} x=x, \lambda \in \mathbf{I}\right\} . \tag{2.10}
\end{equation*}
$$

We need to prove that there exists a constant $C_{I}>0$ such that $\|x\|<C_{I}$ for all $x \in S$. If the number of elements of $S$ is finite, then the result is obvious. If not, without loss of generality, we assume that there exists a sequence $\left\{x_{n}\right\}_{n=0}^{\infty}$ such that $\lim _{n \rightarrow \infty}\left\|x_{n}\right\|=+\infty$, where $x_{n} \in P$ is the fixed point of the operator $F_{\lambda}$ defined by (2.3) at $\lambda_{n} \in \mathbf{I}(n=1,2, \ldots)$.

Then

$$
\begin{equation*}
x_{n}(t) \geq \frac{\delta}{T+\beta}\left\|x_{n}\right\|, \quad t \in[0, T] \tag{2.11}
\end{equation*}
$$

We choose $J>0$ such that

$$
\begin{equation*}
\frac{J b^{q-1} \delta^{2}}{T+\beta} \phi_{q}\left(\int_{Y_{1}} a(r) \nabla r\right)>1 \tag{2.12}
\end{equation*}
$$

$L>0$ such that

$$
\begin{equation*}
f(x, \psi(s)) \geq(J x)^{p-1}, \quad x>L, s \in[-\tau, 0] . \tag{2.13}
\end{equation*}
$$

In view of (H6) there exists an $N$ sufficiently large such that $\left\|x_{N}\right\|>L$. For $t \in[0, T]$, we have

$$
\begin{align*}
\left\|x_{N}\right\| & =\left\|F_{{l_{N}}_{N}} x_{N}\right\| \\
& =\left(F_{\lambda_{N}} x_{N}\right)(T) \\
& \geq \delta \phi_{q}\left(\int_{0}^{T} \lambda_{N} a(r) f\left(x_{N}(r), x_{N}(\mu(r))\right) \nabla r\right) \\
& \geq \delta \phi_{q}\left(\int_{Y_{1}} \lambda_{N} a(r) f\left(x_{N}(r), \psi(\mu(r))\right) \nabla r\right)  \tag{2.14}\\
& >\delta J b^{q-1} \min _{t \in Y_{1}} \phi_{q}\left(\int_{Y_{1}} a(r) x_{N}^{p-1}(r) \nabla r\right) \\
& \geq \frac{J b^{q-1} \delta^{2}}{T+\beta}\left\|x_{N}\right\| \phi_{q}\left(\int_{Y_{1}} a(r) \nabla r\right) \\
& >\left\|x_{N}\right\|,
\end{align*}
$$

which is a contradiction. The proof is complete.
Lemma 2.4. Suppose that (H1)-(H5) hold and that the operator $F_{\lambda}$ has a positive fixed point $x$ in $P$ at $\lambda>0$. Then for every $\lambda_{*} \in(0, \lambda)$ the operator $F_{\lambda}$ has a fixed point $x_{*} \in P \backslash\{\theta\}$ at $\lambda_{*}$, and $x_{*}<x$.

Proof. Let $x(t)$ be the fixed point of the operator $F_{\lambda}$ at $\lambda$. Then

$$
\begin{align*}
x(t) & =B_{0}\left(\phi_{q}\left(\int_{0}^{T} \lambda a(r) f(x(r), x(\mu(r))) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \lambda a(r) f(x(r), x(\mu(r))) \nabla r\right) \Delta s \\
& >B_{0}\left(\phi_{q}\left(\int_{0}^{T} \lambda_{*} a(r) f(x(r), x(\mu(r))) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \lambda_{*} a(r) f(x(r), x(\mu(r))) \nabla r\right) \Delta s, \tag{2.15}
\end{align*}
$$

where $0<\lambda_{*}<\lambda$. Set
$\left(F_{\lambda_{*}} x\right)(t)=B_{0}\left(\phi_{q}\left(\int_{0}^{T} \lambda_{*} a(r) f(x(r), x(\mu(r))) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{S}^{T} \lambda_{*} a(r) f(x(r), x(\mu(r))) \nabla r\right) \Delta s$,
$x_{0}(t)=x(t)$, and $x_{n}=F_{\lambda_{*}} x_{n-1}=\left(F_{\lambda_{*}}^{n} x_{0}\right)(t)$. Then

$$
\begin{equation*}
\left(c \lambda_{*}\right)^{(q-1)} e(t) \leq x_{n+1} \leq x_{n} \leq \cdots \leq x_{1}(t) \leq x_{0}(t) \tag{2.17}
\end{equation*}
$$

where $e(t)$ is also defined by (2.6), which implies that $\left\{F_{\lambda_{*}}^{n} x\right\}_{n=0}^{\infty}$ decreases to a fixed point $x_{*} \in P \backslash\{\theta\}$ of the operator $F_{\lambda_{*}}$, and $x_{*}<x$. The proof is complete.

Lemma 2.5. Suppose that (H1)-(H6) hold. Let $\wedge=\left\{\lambda>0: F_{\lambda}\right.$ have at least one fixed point at $\lambda$ in $\left.P\right\}$. Then $\wedge$ is bounded above.

Proof. Suppose to the contrary that there exists a fixed point sequence $\left\{x_{n}\right\}_{n=0}^{\infty} \subset P$ of $F_{\lambda}$ at $\lambda_{n}$ such that $\lim _{n \rightarrow \infty} \lambda_{n}=\infty$. Then we need to consider two cases:
(i) there exists a constant $H>0$ such that $\left\|x_{n}\right\| \leq H, n=0,1,2 \ldots$;
(ii) there exists a subsequence $\left\{x_{n_{k}}\right\}_{k=1}^{\infty}$ such that $\lim _{k \rightarrow \infty}\left\|x_{n_{k}}\right\|=\infty$ which is impossible by Lemma 2.3.

Only (i) is considered. We can choose $M>0$ such that $f(0,0)>M H$, and further $f\left(x_{n}, x_{n}(\mu)\right)>M H$. For $t \in[0, T]$, we have
$x_{n}(t)=B_{0}\left(\phi_{q}\left(\int_{0}^{T} \lambda_{n} a(r) f\left(x_{n}(r), x_{n}(\mu(r))\right) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \lambda_{n} a(r) f\left(x_{n}(r), x_{n}(\mu(r))\right) \nabla r\right) \Delta s$.

Now we consider (2.18).Assume that the case (i) holds. Then

$$
\begin{align*}
H \geq x_{n}(t) & \geq B_{0}\left(\phi_{q}\left(\int_{0}^{T}\left(\lambda_{n} a(r) M H\right) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T}\left(\lambda_{n} a(r) M H\right) \nabla r\right) \Delta s \\
& =\left(\lambda_{n} M H\right)^{q-1} e(t)  \tag{2.19}\\
& \geq\left(\lambda_{n} M H\right)^{q-1} \frac{\delta}{T+\beta}\|e\|
\end{align*}
$$

leads to

$$
\begin{equation*}
1 \geq\left(\lambda_{n} M\right)^{q-1} H^{q-2} \frac{\delta}{T+\beta}\|e\| \quad \text { for } t \in[0, T] \tag{2.20}
\end{equation*}
$$

which is a contradiction. The proof is complete.
Lemma 2.6. Let $\lambda^{*}=\sup \wedge$. Then $\wedge=\left(0, \lambda^{*}\right]$, where $\wedge$ is defined just as in Lemma 2.5.

Proof. In view of Lemma 2.4, it follows that $\left(0, \lambda^{*}\right) \subset \wedge$. We only need to prove $\lambda^{*} \in \wedge$. In fact, by the definition of $\lambda^{*}$, we may choose a distinct nondecreasing sequence $\left\{\lambda_{n}\right\}_{n=1}^{\infty} \subset \wedge$ such that $\lim _{n \rightarrow \infty} \lambda_{n}=\lambda^{*}$. Let $x_{n} \in P$ be the positive fixed point of $F_{\lambda}$ at $\lambda_{n}, n=1,2, \ldots$. By Lemma 2.3, $\left\{x_{n}\right\}_{n=1}^{\infty}$ is uniformly bounded, so it has a subsequence denoted by $\left\{x_{n}\right\}_{n=1}^{\infty}$, converging to $x_{\lambda^{*}} \in P$. Note that
$x_{n}(t)=B_{0}\left(\phi_{q}\left(\int_{0}^{T} \lambda_{n} a(r) f\left(x_{n}(r), x_{n}(\mu(r))\right) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \lambda_{n} a(r) f\left(x_{n}(r), x_{n}(\mu(r))\right) \nabla r\right) \Delta s$.

Taking the limitation $n \rightarrow \infty$ to both sides of (2.21), and using the Lebesgue dominated convergence theorem [16], we have
$x_{\lambda^{*}}=B_{0}\left(\phi_{q}\left(\int_{0}^{T} \lambda^{*} a(r) f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right) \nabla r\right)\right)+\int_{0}^{t} \phi_{q}\left(\int_{s}^{T} \lambda^{*} a(r) f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right) \nabla r\right) \Delta s$,
which shows that $F_{\lambda}$ has a positive fixed point $x_{\lambda^{*}}$ at $\lambda=\lambda^{*}$. The proof is complete.
Theorem 2.7. Suppose that (H1)-(H6) hold. Then there exists a $\lambda^{*}>0$ such that (1.1) has at least two, one, and no positive solutions for $0<\lambda<\lambda^{*}, \lambda=\lambda^{*}$ and $\lambda>\lambda^{*}$, respectively.

Proof. Assume that (H1)-(H5) hold. Then there exists a $\lambda^{*}>0$ such that $F_{\lambda}$ has a fixed point $x_{\lambda^{*}} \in P \backslash\{\theta\}$ at $\lambda=\lambda^{*}$. In view of Lemma 2.4, $F_{\lambda}$ also has a fixed point $x_{\underline{\lambda}}<x_{\lambda^{*}}, x_{\underline{\lambda}} \in P \backslash\{\theta\}$ and $0<\underline{\lambda}<\lambda^{*}$. Note that $f$ is continuous on $\left(\mathbb{R}^{+}\right)^{2}$. For $0<\underline{\lambda}<\lambda^{*}$, there exists a $\delta_{0}>0$ such that
$f\left(x_{\lambda^{*}}(r)+\delta, x_{\lambda^{*}}(\mu(r))+\delta\right)-f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right) \leq f(0,0)\left(\frac{\lambda^{*}}{\underline{\lambda}}-1\right)$ for $r \in[0, T], 0<\delta \leq \delta_{0}$.

Hence,

$$
\begin{align*}
& \underline{\lambda} a(r) f\left(x_{\lambda^{*}}(r)+\delta, x_{\lambda^{*}}(\mu(r))+\delta\right)-\lambda^{*} a(r) f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right) \\
&= \underline{\lambda} a(r)\left[f\left(x_{\lambda^{*}}(r)+\delta, x_{\lambda^{*}}(\mu(r))+\delta\right)-f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right)\right] \\
&-\left(\lambda^{*}-\underline{\lambda}\right) a(r) f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right)  \tag{2.24}\\
& \leq\left(\lambda^{*}-\underline{\lambda}\right) a(r) f(0,0)-\left(\lambda^{*}-\underline{\lambda}\right) f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right) \\
&=\left(\lambda^{*}-\underline{\lambda}\right) a(r)\left[f(0,0)-f\left(x_{\lambda^{*}}(r), x_{\lambda^{*}}(\mu(r))\right)\right] \\
& \leq 0, \quad \forall r \in[0, T] .
\end{align*}
$$

From above, we have

$$
\begin{equation*}
F_{\underline{\lambda}}\left(x_{\lambda^{*}}+\delta\right) \leq F_{\lambda^{*}}\left(x_{\lambda^{*}}\right)=x_{\lambda^{*}}<x_{\lambda^{*}}+\delta . \tag{2.25}
\end{equation*}
$$

Set $R_{1}=\left\|x_{\lambda^{*}}(t)+\delta\right\|$ for $t \in[0, T]$ and $P_{R_{1}}=\left\{x \in P:\|x\|<R_{1}\right\}$. We have $F_{\underline{1}} x \neq x$ for $x \in \partial R_{1}$. By Lemma 2.1, $i\left(F_{\underline{\jmath}}, P_{R_{1}}, P\right)=1$. In view of (H6), we can choose $L>R_{1}>0$ such that

$$
\begin{gather*}
f(x, \psi(s)) \geq(J x)^{p-1} \\
\frac{J \underline{\lambda}^{q-1} \delta^{2}}{T+\beta} \phi_{q}\left(\int_{Y_{1}} a(r) \nabla r\right)>1 \quad \text { for } x>L, s \in[-\tau, 0] . \tag{2.26}
\end{gather*}
$$

Set

$$
\begin{equation*}
R_{2}=\frac{T+\beta}{\delta}(L+1), \quad P_{R_{2}}=\left\{x \in P:\|x\|<R_{2}\right\} . \tag{2.27}
\end{equation*}
$$

Similar to Lemma 2.3, it is easy to obtain that

$$
\begin{align*}
\left\|F_{\underline{\underline{l}}} x\right\| & =\left(F_{\underline{\underline{\jmath}}} x\right)(T) \\
& \geq \delta \phi_{q}\left(\int_{0}^{T} \underline{\underline{\jmath}} a(r) f(x(r), x(\mu(r))) \nabla r\right) \\
& \geq \delta \phi_{q}\left(\int_{Y_{1}} \underline{\lambda} a(r) f(x(r), \psi(\mu(r))) \nabla r\right) \\
& >\delta J \underline{\underline{\lambda}}^{q-1} \min _{t \in Y_{1}}\{x(t)\} \phi_{q}\left(\int_{Y_{1}} a(r) \nabla r\right)  \tag{2.28}\\
& \geq \frac{J \underline{\lambda}^{q-1} \delta^{2}}{T+\beta}\|x\| \phi_{q}\left(\int_{Y_{1}} a(r) \nabla r\right) \\
& >\|x\| \text { for } x \in \partial P_{R_{2}} .
\end{align*}
$$

In view of Lemma 2.1, $i\left(F_{\underline{\underline{1}}}, P_{R_{2}}, P\right)=0$. By the additivity of fixed point index,

$$
\begin{equation*}
i\left(F_{\underline{\underline{1}}}, P_{R_{2}} \backslash \bar{P}_{R_{1}}, P\right)=i\left(F_{\underline{1}}, P_{R_{2}}, P\right)-i\left(F_{\underline{\underline{1}}}, P_{R_{1}}, P\right)=-1 . \tag{2.29}
\end{equation*}
$$

So, $F_{\underline{\imath}}$ has at least two fixed points in $P$. The proof is complete.

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